

\Rightarrow since $[X_i, X_j] = 0 \Rightarrow$ distribution $\text{Span}\{X_i\} = \mathcal{D}$ is integrable and Frobenius theorem says that there exists coordinate system $\{y^a\}$ s.t.

$$X_i = A_i^j(y^A) \frac{\partial}{\partial y^j}$$

Matrix A_i^j is INVERTIBLE at each point y^A on M since X_i are l. independent (and $\frac{\partial}{\partial y^i}$ is a basis at each point for \mathcal{D})

$\Rightarrow \exists B_i^j = B_i^j(y^A)$ s.t.

$$A_i^j B_j^k = \delta_i^k = B_i^j A_j^k \quad (1)$$

We are now looking for n functions

$$x^i = x^i(y^A) \text{ s.t.}$$

$$\frac{\partial x^i}{\partial y^j} = B_j^i$$

Do they exist?

Yes, provided that

$$\frac{\partial^2 x^i}{\partial y^k \partial y^j} = \frac{\partial^2 x^i}{\partial y^j \partial y^k} \text{ i.e. iff } \boxed{B_j^i{}_{,k} = B_k^i{}_{,j}} \quad (*)$$

~~We~~ To check that $(*)$ is satisfied we use the condition that $[X_i, X_j]$ commute:

$$0 = [A_i^j \frac{\partial}{\partial y^j}, A_k^l \frac{\partial}{\partial y^l}] = (A_i^j A_{k,j}^l - A_k^j A_{i,j}^l) \frac{\partial}{\partial y^l}$$

$$\text{i.e. } \boxed{A_i^j A_{k,j}^l = A_k^j A_{i,j}^l}$$

Now we differentiate (1)

$$0 = B_i^j{}_{,k} A_j^k - B_i^j A_j^k{}_{,k}$$

$$\Rightarrow B_i^j{}_{,k} A_j^k = B_i^j A_j^k{}_{,k} \quad \text{with } \cancel{B_i^j{}_{,k} A_j^k} = \cancel{B_i^j A_j^k{}_{,k}}$$

$$B_{i,j}^k A_j^k B_k^m = B_{i,j}^k A_j^k B_k^m$$

$$\Rightarrow B_{i^m, l} = B_{i^j}^k A_j^k B_k^m$$

We need antisymmetrization of k 's in i, l indices:

$$B_{i^m, l} - B_{l^m, i} = (B_{i^j}^k A_j^k B_k^m - B_{l^j}^k A_j^k B_k^m)$$

$$\text{But } A_s^i (B_{i^j}^k A_j^k B_k^m - B_{l^j}^k A_j^k B_k^m) =$$

$$= A_s^k B_{i^j}^k - B_{l^j}^k A_j^k A_s^i =$$

$$= A_s^k B_{i^j}^k - B_{l^j}^k A_j^i A_s^k = A_s^k B_{i^j}^k - A_s^k B_{l^j}^k = 0$$

\Rightarrow because A_s^i is invertible

$$B_{i^j}^k A_j^k B_k^m - B_{l^j}^k A_j^k B_k^m = 0 \text{ and consequently}$$

$$B_{i^m, l} - B_{l^m, i} = 0.$$

\Rightarrow PDE Equation $\frac{\partial x^i}{\partial y^j} = B_j^i(y^A)$ for $x^i = x^i(y^A)$ has solutions

$$\Rightarrow \text{take } x^i = x^i(y^A) \quad i=1, \dots, m$$

$$x^\alpha = y^\alpha \quad \alpha = m+1, \dots, n$$

The set of functions

$$x^A = (x^i(y^A), x^\alpha(y^A)) \text{ is a coordinate system on } M$$

since

$$\frac{\partial x^A}{\partial y^B} = \begin{pmatrix} B_j^i & \text{small} \\ 0 & \mathbb{1} \end{pmatrix}, \quad \det \left(\frac{\partial x^A}{\partial y^B} \right) \neq 0.$$

In this coordinate system:

$$\begin{aligned} X_i &= A_i^j \frac{\partial}{\partial y^j} = A_i^j \frac{\partial x^k}{\partial y^j} \partial_{x^k} = A_i^j \frac{\partial x^k}{\partial y^j} \partial_{x^k} + A_i^j \frac{\partial x^\alpha}{\partial y^j} \partial_{x^\alpha} \\ &= A_i^j B_j^k \partial_{x^k} = \frac{\partial}{\partial x^i} \end{aligned}$$

□.

2) Tensors and tensor fields

1) Tensors i.e. multilinear maps.

V - vector space over the field $\mathbb{K} = \mathbb{R}$ or \mathbb{C} , $\dim_{\mathbb{K}} V = n < \infty$

V^* - its dual:

$$V^* = \{ \lambda: V \xrightarrow{\text{linear}} \mathbb{K} \}$$

Given a pair $(v, \lambda) \in V \times V^*$ we have a bilinear map

$$\langle \cdot, \cdot \rangle: V \times V^* \longrightarrow \mathbb{K}$$

$$(v, \lambda) \longmapsto \langle v, \lambda \rangle := \lambda(v)$$

(obviously linear in the first argument, since λ is linear; linearity in the second argument by

$$(v, \alpha\lambda + \beta\mu) \longmapsto \langle v, \alpha\lambda + \beta\mu \rangle = (\alpha\lambda + \beta\mu)(v) = \alpha\lambda(v) + \beta\mu(v) \\ \forall \alpha, \beta \in \mathbb{K}.$$

Definition

The space V_s^r of s -times covariant and r -times contravariant tensors is the space of ^{all} V maps

$$T: \underbrace{V \times V \times \dots \times V}_{s\text{-times}} \times \underbrace{V^* \times \dots \times V^*}_{r\text{-times}} \longrightarrow \mathbb{K}$$

which are linear in each of its $(s+r)$ arguments.

Remarks

1° V_s^r denoted also by $V_s^r = \underbrace{V \otimes \dots \otimes V}_r \otimes \underbrace{V^* \otimes \dots \otimes V^*}_s = \otimes_r V \otimes_s V^*$

is a vector space over \mathbb{K} :

$$(\alpha T_1 + \beta T_2)(v_1, \dots, v_s, \lambda_1, \dots, \lambda_r) = \alpha T_1(v_1, \dots, v_s, \lambda_1, \dots, \lambda_r) + \beta T_2(v_1, \dots, v_s, \lambda_1, \dots, \lambda_r)$$

2° $\boxed{V_0^1 = V ; V_1^0 = V^*}$ indeed:

$V_0^1 = V \ni v : V^* \xrightarrow{\text{linear}} \mathbb{K}$
 $\lambda \longmapsto \langle v, \lambda \rangle$

similarly:
 $V_1^0 = V^* \ni \lambda : V \xrightarrow{\text{linear}} \mathbb{K}$
 $v \longmapsto \langle v, \lambda \rangle$

3° $\boxed{\dim V_s^r = n(r+s)}$ indeed:

$e = \{e_\mu\}_{\mu=1, \dots, n}$ basis in V .
 Then: $\omega = \{\omega^\mu\}_{\mu=1, \dots, n}$ defined by

$\omega^\mu \in V^*$ and $\omega^\mu(e_\nu) = \langle e_\nu, \omega^\mu \rangle = \delta_\nu^\mu$
 is a basis in V^* .

Define:

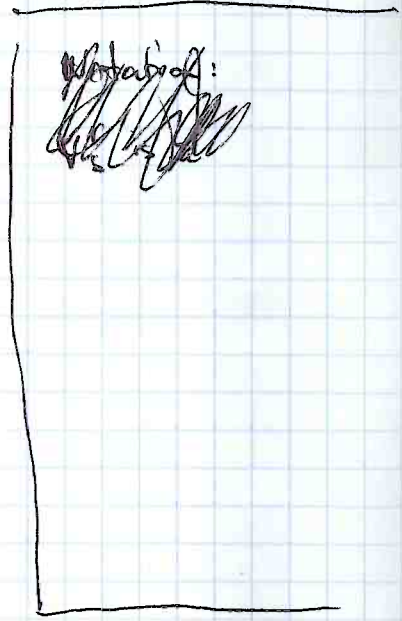
$e_{\mu_1} \otimes \dots \otimes e_{\mu_r} \otimes \omega^{\nu_1} \otimes \dots \otimes \omega^{\nu_s} \in V_s^r$ by
 $(e_{\mu_1} \otimes \dots \otimes e_{\mu_r} \otimes \omega^{\nu_1} \otimes \dots \otimes \omega^{\nu_s})(e_{\alpha_1}, \dots, e_{\alpha_s}, \omega^{\beta_1}, \dots, \omega^{\beta_r}) :=$
 $= \langle e_{\mu_1}, \omega^{\beta_1} \rangle \dots \langle e_{\mu_r}, \omega^{\beta_r} \rangle \langle e_{\alpha_1}, \omega^{\nu_1} \rangle \dots \langle e_{\alpha_s}, \omega^{\nu_s} \rangle =$
 $(= \delta_{\mu_1}^{\beta_1} \dots \delta_{\mu_r}^{\beta_r} \delta_{\alpha_1}^{\nu_1} \dots \delta_{\alpha_s}^{\nu_s})$
 + linearity in each argument.

Fakt: $\{e_{\mu_1} \otimes \dots \otimes e_{\mu_r} \otimes \omega^{\nu_1} \otimes \dots \otimes \omega^{\nu_s}\}_{\substack{\mu_i=1, \dots, n ; i=1, \dots, r \\ \nu_j=1, \dots, n ; j=1, \dots, s}}$

is a basis in V_s^r .

Thus $V_s^r \ni T = T^{\mu_1, \dots, \mu_r, \nu_1, \dots, \nu_s} e_{\mu_1} \otimes \dots \otimes e_{\mu_r} \otimes \omega^{\nu_1} \otimes \dots \otimes \omega^{\nu_s}$

e.g. $\langle \cdot, \cdot \rangle = e_\alpha \otimes \omega^\alpha$ (check!)



4° Change of bases

$$V \ni v = v^\mu e_\mu$$

$$V^* \ni \lambda = \lambda_\mu \omega^\mu$$

$$\text{let } a \in GL(n, \mathbb{R}); \quad a = (a^\mu_\nu)$$

Suppose that e_μ is related to e'_μ by
 $e_\mu = e'_\nu a^\nu_\mu$ i.e. by $e'_\mu = e_\nu \bar{a}^{\nu\mu}$,

how ω^μ is related to ω'^μ ?

Of course ω'^μ is linearly related to ω^μ so that

$$\omega'^\mu = b^\mu_\nu \omega^\nu. \quad \text{We have to find } b^\mu_\nu.$$

We have:

$$\begin{aligned} \delta_\mu^\nu &= \langle e'_\mu, \omega'^\nu \rangle = \langle e_\alpha \bar{a}^{\alpha\mu}, b^\nu_\beta \omega^\beta \rangle = \\ &= \bar{a}^{\alpha\mu} b^\nu_\beta \langle e_\alpha, \omega^\beta \rangle = \bar{a}^{\alpha\mu} b^\nu_\beta \delta_\alpha^\beta = \\ &= \bar{a}^{\alpha\mu} b^\nu_\alpha \quad | \cdot a^\mu_\beta \end{aligned}$$

$$\Rightarrow a^\nu_\beta = b^\nu_\alpha \Rightarrow \boxed{b^\nu_\beta = a^\nu_\beta}$$

Thus

$$\boxed{e'_\mu = e_\nu \bar{a}^{\nu\mu} \Leftrightarrow \omega'^\mu = a^\mu_\nu \omega^\nu} \quad a \in GL(n, \mathbb{R}).$$

5° Transformation of components

$$\begin{aligned} v &= v^\mu e_\mu = v'^\mu e'_\mu = v^\alpha \underbrace{\delta^\mu_\alpha}_{\delta^\mu_\alpha} \cdot e_\beta \bar{a}^{\beta\mu} = \\ &= \underbrace{c^\mu_\alpha}_{\delta^\mu_\alpha} \bar{a}^{\beta\mu} v^\alpha e_\beta \end{aligned}$$

$$\Rightarrow c^\mu_\alpha = a^\mu_\alpha$$

$$\Rightarrow \boxed{e'_\mu = e_\nu \bar{a}^{\nu\mu} \Rightarrow v'^\mu = a^\mu_\alpha v^\alpha}$$

$$\text{Similarly } \lambda = \lambda_\mu \omega^\mu \text{ then } \Rightarrow \boxed{\lambda'_\mu = \lambda_\nu \bar{a}^{\nu\mu}}$$

Components of vectors transform as basis 1-forms
 Components of covectors transform as basis vectors.

6° More generally: $T \in V_s^m$

4

$$T = T^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} e_{\mu_1} \otimes \dots \otimes e_{\mu_r} \otimes \omega^{\nu_1} \otimes \dots \otimes \omega^{\nu_s}$$

If we change a basis:

$$\{e_\mu\} \mapsto \{e'_\mu\} \text{ s.t.}$$

(*) $\boxed{e'_\mu = e_\nu a^{-1\nu}_\mu}$ then the components of T change as

$$\begin{array}{l} \overbrace{T^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} \mapsto} \\ (**) \quad T^{\alpha_1 \dots \alpha_r}_{\beta_1 \dots \beta_s} = a^{\alpha_1}_{\mu_1} \dots a^{\alpha_r}_{\mu_r} T^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} a^{-1\nu_1}_{\beta_1} \dots a^{-1\nu_s}_{\beta_s} \end{array}$$

This is a classical PHYSICISTS definition of $\binom{m}{s}$ -type tensor:

It is an equivalence class of pairs:

$$(e_\mu, T^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}) \text{ s.t.}$$

$$(e_\mu, T^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}) \sim (e'_\mu, T'^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}) \Leftrightarrow$$

$$\Leftrightarrow \exists a \in GL(n, \mathbb{R}) \text{ s.t.}$$

$$(e', T') \text{ is related to } (e, T) \text{ via (*) \& (**).}$$

Def 45 formalize this a bit more:

2) G acts transitively on $S \Leftrightarrow \forall p, q \in S \exists a \in G$ s.t. $q = \varphi_a(p)$

Ex 3 take $S = G$

$$G \times S \ni (a, b) \longmapsto \varphi_a(b) = a \cdot b \in S = G$$

It is a good left action: $\varphi_{ab}(c) = (ab)(c) = a \cdot b \cdot c = (\varphi_a \circ \varphi_b)(c)$

if b and $c \in G \Rightarrow$ a s.t. $a \cdot b = c$ is equal to
 $a = c \cdot b^{-1}$.

G acts transitively on itself (right action: $\varphi_a(b) = b \cdot a$).

BUT: There are non-transitive actions, e.g. in Ex 2

two vectors in \mathbb{R}^3 of unequal length can not be ~~connected~~ transformed to each other by an el. of $SO(3)$!

\Downarrow

3) An orbit of the action of G in S

Orbit of an element $p \in S \equiv$ set of all points in S
that are ~~connected~~ to p by an
action of G .

Precisely:

$$O_p = \{ p' \in S : \exists a \in G \quad \varphi_a(p) = p' \}$$

In particular:

G acts transitively in S iff there is only ONE
orbit equal to S .

In general:

Given an action of G on S , the set S splits
into disjoint orbits — equivalence classes of the relation

$$p_1 \sim p_2 \Leftrightarrow \exists a \in G \text{ s.t. } \varphi_a(p_1) = p_2$$

- 4) G acts effectively in $S \Leftrightarrow \forall e \neq a \in G \exists p \in S : \varphi_a(p) \neq p$
- 5) G acts freely in $S \Leftrightarrow \forall a \neq e \in G \forall p \in S : \varphi_a(p) \neq p$

e.g. $SO(3)$ acts effectively in \mathbb{R}^3 but NOT freely!
 $\mathbb{R}^3 \ni \vec{0}$ when acted by each element from $SO(3)$ is NOT moved.

6) Important example of an action of $GL(n, \mathbb{R})$.

Let: V - be an n -dimensional vector space over \mathbb{R}

$P(V)$ = set of all bases in V

$P(V) \ni e = (e_\mu) = (e_1, e_2, \dots, e_n)$ - basis

Take $G = GL(n, \mathbb{R}) \ni a = \begin{pmatrix} a^{\mu\nu} \\ \nu \end{pmatrix}$ matrices $n \times n$ invertible
 $S = P(V)$

$GL(n, \mathbb{R}) \times P(V) \ni (a, e) \mapsto \varphi_a(e) = e \cdot a^{-1} = (e_\mu \cdot a^{-1\mu\nu}) \in P(V)$

~~$\varphi_{ab}(e) = e(a \cdot b)^{-1} = e b^{-1} a^{-1} = \varphi_a(e b^{-1}) = \varphi_a(\varphi_b(e))$~~
 left action

it is

- 1) free
- 2) transitive (even simply transitive)

$\forall e, e' \exists! a \text{ s.t. } e' = \varphi_a(e)$

7) Tensors, tensor densities, pseudotensors (

Scheme:

V - vector space of dim n , $P(V)$ - set of all bases,

$\varphi_a(e) = e a^{-1}$ $a \in G = GL(n, \mathbb{R})$

ρ - representation of $GL(n, \mathbb{R})$ in a vector space W .

$\rho: GL(n, \mathbb{R}) \xrightarrow{\text{homo}} GL(W)$

$\rho(a \cdot b) = \rho(a) \cdot \rho(b)$.

- We define an action of $G = GL(n, \mathbb{R})$ in $S = P(V) \times W$

$$G \times S \ni (a, (e, w)) \xrightarrow{\Psi_a} (\Psi_a(e), \rho(a)w) \in S$$

- We check that Ψ_a is a left action:

$$\Psi_a(e, w) = (\Psi_a(e), \rho(a)w)$$

$$\begin{aligned} \Psi_{ab}(e, w) &= (\Psi_{ab}(e), \rho(ab)w) = ((\Psi_a \circ \Psi_b)(e), \rho(a) \cdot (\rho(b)w)) \\ &= (\Psi_a \circ \Psi_b)(e, w). \quad \checkmark \end{aligned}$$

- We are interested in the set of orbits, i.e. in the set of equivalence classes of the relation:

$$(e, w) \sim (e', w') \iff \exists a \in GL(n, \mathbb{R}) \text{ s.t. } (e', w') = \Psi_a(e, w).$$

The set of orbits is denoted by

$$W_G = S / \sim = \frac{P(V) \times W}{\sim}$$

Facts

1° W_G is a vector space. The linear structure in W_G is defined as follows:

$$(e, w) \longmapsto \text{equivalence class } [(e, w)]$$

$$(e', w') \longmapsto \dots \dots \dots [(e', w')] \sim [(e, \tilde{w})]$$

$$\alpha \cdot [(e, w)] + \alpha' [(e', w')] := [(e, \alpha w + \alpha' \tilde{w})]$$

~~Check~~ Check that this def does NOT depend on the choice of representative (e, w) of $[(e, w)]$ and (e', w') of $[(e', w')]$.

$$\begin{aligned} 2^\circ \quad \dim(P(V) \times W) &= \dim GL(n, \mathbb{R}) + \dim W \\ \dim W_G &= \dim W \end{aligned}$$

Important examples

(I) TENSORS

$$V = \mathbb{R}^n, \quad W = \mathbb{R}^{n(r+s)}$$

$$W \ni K = \left(K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} \right)$$

$$\begin{aligned} \mu_i &= 1, \dots, n \\ \nu_i &= 1, \dots, n \end{aligned}$$

$$(\alpha K + \beta L)^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} = \alpha K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} + \beta L^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}$$

$$\rho_s^r : GL(n, \mathbb{R}) \longrightarrow GL(W)$$

$$\left[\rho_s^r(a) K \right]^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} = a^{\mu_1}_{\beta_1} a^{\mu_2}_{\beta_2} \dots a^{\mu_r}_{\beta_r} K^{\beta_1 \dots \beta_r}_{\nu_1 \dots \nu_s} a^{-1\nu_1}_{\alpha_1} \dots a^{-1\nu_s}_{\alpha_s}$$

↑

this is a good representation

$$\mathbb{R} \ni \rho_s^r = \mathcal{P}(\mathbb{R}^n) \times \mathbb{R}^{n(r+s)}$$

$$\Psi_a(e, K) = (ea^{-1}, \rho_s^r(K))$$

$W_{\rho_s^r} \rightarrow$ vector space of tensors of type $\begin{pmatrix} s \\ r \end{pmatrix}$

— s -times covariant
and r -times contravariant,

(II) Tensor densities of weight ω ,

$$W = \mathbb{R}^{n(r+s)} \quad \begin{array}{l} \text{as before} \\ \text{(but now take} \end{array}$$

$${}^\omega \rho_s^r(a) = (\det a)^\omega \rho_s^r(a),$$

e.g.

a) Leri-Civita symbol

definition:

① $\left\{ \begin{array}{l} \epsilon_{\mu_1 \dots \mu_n} \text{ s.t. } \epsilon_{\mu_1 \dots \mu_n} = \text{sgn } \pi \\ \text{if } \pi = \begin{pmatrix} 1 \dots n \\ \mu_1 \dots \mu_n \end{pmatrix} \\ \epsilon_{\mu_1 \dots \mu_n} = 0 \\ \text{if at least one of } \mu_i \text{ is repeated.} \end{array} \right.$

$\Rightarrow \epsilon_{\mu_1 \dots \mu_n} = \epsilon_{[\mu_1 \dots \mu_n]} \leftarrow$ totally antisymmetric

② $\epsilon^{\mu_1 \dots \mu_n} = \epsilon_{\mu_1 \dots \mu_n}$ i.e. ϵ looks the same in all bases.

Consider:

$a^{-1 \mu_1} \dots a^{-1 \mu_n} \epsilon_{\nu_1 \dots \nu_n} = \det(a^{-1}) \epsilon_{\mu_1 \dots \mu_n}$

Example

$n=2, \epsilon_{\alpha\beta} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$

$\begin{pmatrix} a^{\mu\alpha} \\ b^{\mu\beta} \end{pmatrix} = \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}$

~~$\begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix}$~~

$a^{-1\alpha} a^{-1\beta} \epsilon_{\alpha\beta} = a^{-1\alpha} \epsilon_{\alpha\beta} a^{-1\beta}$

$(a^{-1})^T \epsilon \cdot a^{-1} =$

$= \begin{pmatrix} \alpha & \gamma \\ \beta & \delta \end{pmatrix} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} \alpha & \beta \\ \gamma & \delta \end{pmatrix} =$

$= \begin{pmatrix} \alpha & \gamma \\ \beta & \delta \end{pmatrix} \begin{pmatrix} \gamma & \delta \\ -\alpha & -\beta \end{pmatrix} = \begin{pmatrix} 0 & \alpha\delta - \beta\gamma \\ \beta\gamma - \alpha\delta & 0 \end{pmatrix} =$

$= \det(a^{-1}) \cdot \epsilon$

$\Rightarrow \det a \cdot a^{-1 \mu_1} \dots a^{-1 \mu_n} \epsilon_{\nu_1 \dots \nu_n} = \epsilon_{\mu_1 \dots \mu_n} = \epsilon^{\mu_1 \dots \mu_n}$

$\epsilon^{\mu_1 \dots \mu_n} = \left[(\det a)^{+1} \epsilon^{\nu_1 \dots \nu_n} \right]_{\mu_1 \dots \mu_n} = \left[\rho(a) \epsilon \right]_{\mu_1 \dots \mu_n}$

\Rightarrow
 ϵ
 tensor
 of type
 $\begin{pmatrix} 0 \\ n \end{pmatrix}$
 density
 of
 weight
 $+1$

