

## 8) covariant tensor fields of type $(0_k)$

$$\mathfrak{A}: \mathcal{X}(M) \times \dots \times \mathcal{X}(M) \xrightarrow{\text{$k$-linear}} \mathbb{F}(M)$$

$\underbrace{\quad}_{k \text{ times}}$        $\mathbb{F} \text{-linear } !!!$

at  $p \in M$

$$\mathfrak{A}(x_1, \dots, x_k)(p) = \mathfrak{A}_p(x_{1p}, \dots, x_{kp})$$

$$\mathfrak{A}_p: T_p(M) \times \dots \times T_p(M) \xrightarrow{\text{$k$-}\mathbb{R}\text{-linear}} \mathbb{R}$$

- $k=1$  fields of 1-forms (1-form fields).

$$\mathfrak{A} \in \Lambda^1 M$$

Example differential of a function  $f \in \mathbb{F}(M)$

$$df(x) := X(f).$$

Local basis in  $\Lambda^1 M$ :  $(U, x) \Rightarrow \{dx^\mu\}_{\mu=1}^n$

gives  $n$ -linearly independent 1-forms at each point  $p \in U$ .

$\{dx^\mu\}_{\mu=1}^n$  constitutes a basis in  $\Lambda^1 U$

$$\mathfrak{A} = \mathfrak{A}_{\mu\nu} dx^\mu ; \quad \mathfrak{A}_\mu = \mathfrak{A}(\frac{\partial}{\partial x^\mu}).$$

- $k=2$  METRIC:  $g: \mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathbb{F}(M)$

$$1^\circ \quad g(X, Y) = g(Y, X)$$

$$2^\circ \quad (\forall X \quad g(X, Y) = 0) \Rightarrow (Y = 0)$$

A metric  $g$  on  $M$  defines a map

$$\tilde{g}: \mathcal{X}(M) \rightarrow \Lambda^1 M$$

$$\tilde{g}(X)(Y) := g(X, Y)$$

1-form condition  $2^\circ$  means that  $\tilde{g}$  is invertible.  
(Invariance under rotation of a coordinate)

### g) Antisymmetric covariant tensor fields : $\Lambda^k M$

$\lambda$  - tensor fields of type  $\binom{0}{k}$  s.t.

$$\lambda(x_1, \dots, x_i, \dots, x_j, \dots, x_n) = -\lambda(x_1, \dots, x_j, \dots, x_i, \dots, x_n)$$

for all pairs  $x_i, x_j$  from the set  $x_1, \dots, x_n$ .

#### N wedge product

$\lambda \in \Lambda^k M, \mu \in \Lambda^l M \Rightarrow \lambda \wedge \mu \in \Lambda^{k+l} M$  and is defined by:

$$(\lambda \wedge \mu)(x_1, \dots, x_{k+l}) = \frac{1}{k! l!} \sum_{\sigma \in S_{k+l}} \operatorname{sgn} \sigma \lambda(x_{\sigma(1)}, \dots, x_{\sigma(k)}) \mu(x_{\sigma(k+1)}, \dots, x_{\sigma(k+l)})$$

#### Example

$$\begin{aligned} 1) \quad \lambda, \mu \in \Lambda^1 \Rightarrow (\lambda \wedge \mu)(x_1, x_2) &= \frac{1}{1! 1!} [\lambda(x_1) \mu(x_2) - \lambda(x_2) \mu(x_1)] = \\ &= (\lambda \otimes \mu)(x_1, x_2) - (\mu \otimes \lambda)(x_1, x_2) = \\ &= (\lambda \otimes \mu - \mu \otimes \lambda)(x_1, x_2) \end{aligned}$$

$$\lambda \wedge \mu = \lambda \otimes \mu - \mu \otimes \lambda$$

$$2) \quad \alpha \in \Lambda^1$$

$$[(\lambda \wedge \mu) \wedge \nu](x_1, x_2, x_3) = \frac{1}{2! 1!} [(\lambda(x_1) \mu(x_2) - \lambda(x_2) \mu(x_1)) \nu(x_3) +$$

$\begin{array}{r} 123 \\ + 312 \\ + 231 \\ - 213 \\ - 321 \\ \hline - 132 \end{array}$

$$+ (\lambda(x_3) \mu(x_1) - \lambda(x_1) \mu(x_3)) \nu(x_2) +$$

$$+ (\lambda(x_2) \mu(x_3) - \lambda(x_3) \mu(x_2)) \nu(x_1) -$$

$$- (\lambda(x_2) \mu(x_1) - \lambda(x_1) \mu(x_2)) \nu(x_3) -$$

$$- (\lambda(x_3) \mu(x_2) - \lambda(x_2) \mu(x_3)) \nu(x_1) -$$

$$- (\lambda(x_1) \mu(x_3) - \lambda(x_3) \mu(x_1)) \nu(x_2)] =$$

$$= \lambda(x_1) \mu(x_2) \nu(x_3) + \lambda(x_3) \mu(x_1) \nu(x_2) + \lambda(x_2) \mu(x_3) \nu(x_1) +$$

$$- \lambda(x_2) \mu(x_1) \nu(x_3) - \lambda(x_1) \mu(x_3) \nu(x_2) - \lambda(x_3) \mu(x_2) \nu(x_1) =$$

$$= (\lambda \otimes \mu \otimes \nu + \mu \otimes \nu \otimes \lambda + \nu \otimes \lambda \otimes \mu - \mu \otimes \lambda \otimes \nu - \lambda \otimes \nu \otimes \mu - \nu \otimes \mu \otimes \lambda)(x_1, x_2, x_3)$$

Define:  $\Lambda^0 M = \mathbb{F}(M)$ . and if  $f \in \Lambda^0 M$  and  $\lambda \in \Lambda^k M$

we have  $f \cdot \lambda = f \cdot \lambda$ .

$$\Rightarrow \Lambda M = \bigoplus_{k=0}^n \Lambda^k M, \quad \underbrace{\Lambda}_{\text{Cartan algebra}} \quad \begin{array}{l} \text{product. (in particular} \\ \text{ASSOCIATIVE) .} \end{array}$$

Fact  $\boxed{\omega \wedge \omega = (-1)^{kl} \omega \wedge \omega}$

#### 10) Exterior differential

$$d: \Lambda M \rightarrow \Lambda M \quad \text{s.t.}$$

$$1^\circ d \Lambda^k M \subset \Lambda^{k+1} M$$

$$2^\circ d - \boxed{\mathbb{R}}\text{-linear}$$

$$3^\circ f \in \Lambda^0 M \Rightarrow df(x) = X(f)$$

$$4^\circ d(\overset{k}{\omega} \wedge \overset{l}{\omega}) = d\overset{k}{\omega} \wedge \overset{l}{\omega} + (-1)^k \overset{k}{\omega} \wedge d\overset{l}{\omega}$$

$$5^\circ d^2 \equiv 0.$$

The above properties define  $d$  uniquely!

#### 11) Inner product (Hook operator)

$X$  - a vector field on  $M$ ;  $X \in \mathfrak{X}(M)$ .

$$X \lrcorner: \Lambda M \rightarrow \Lambda M \quad \text{s.t.}$$

$$0^\circ X \lrcorner f = 0 \quad \forall f \in \Lambda^0 M$$

$$1^\circ X \lrcorner \Lambda^k M \subset \Lambda^{k-1} M \quad \forall k \geq 1$$

$$2^\circ X \lrcorner - \boxed{\mathbb{F}}\text{-linear}$$

$$3^\circ X \lrcorner df = df(X) = X(f)$$

$$4^\circ X \lrcorner (\overset{k}{\omega} \wedge \overset{l}{\omega}) = (X \lrcorner \overset{k}{\omega}) \wedge \overset{l}{\omega} + (-1)^k \overset{k}{\omega} \wedge (X \lrcorner \overset{l}{\omega})$$

One can check that  $X_1: \Lambda^k M \rightarrow \Lambda^{k-1}$  is given by:

$$(X_1 \circ \omega)(x_1, \dots, x_k) = \overset{\leftarrow}{\omega}(x_1, x_2, \dots, x_k)$$

## 12) Derivations of $\mathbb{Z}$ -graded algebras

1°  $A = \bigoplus_{k=-\infty}^{\infty} A_k$   $A$  is an algebra with  $A_k$  vector spaces s.t.

$$A_k \cdot A_\ell \subset A_{k+\ell}$$

$A$  is called (anti)abelian  $\mathbb{Z}$ -graded algebra iff:

$$a_k \cdot a_\ell = (-1)^{kl} a_\ell \cdot a_k \quad a_k \in A_k$$

Example  $(\Lambda M)$  - abelian  $\mathbb{Z}$ -graded algebra with  
 $\bullet \quad A_k = \Lambda^k M \text{ for } k=0, \dots, n$   
 $\bullet \quad A_k = \{0\} \text{ for } k \notin \{0, \dots, n\}$

## 2° Derivation of degree $k$

$$D: A \longrightarrow A$$

linear

- $D(A_j) \subset A_{j+k}$
- $D(a_i \cdot a_j) = D a_i \cdot a_j + (-1)^{ik} a_i \cdot D a_j$

Example In  $(\Lambda M, \wedge)$   $\boxed{d}$  is a derivation of degree  $\boxed{+1}$   
 $\boxed{X_1}$  is a derivation of degree  $\boxed{-1}$

3° The set of all derivations of A

A -  $\mathbb{Z}$ -graded

$$\text{Der}_k A = \{ D - \text{derivations of degree } k \text{ of } A \}$$

$$\text{Der} A = \bigoplus_{k=-\infty}^{\infty} \text{Der}_k A.$$

Given  $D_1 \in \text{Der}_{k_1} A$  and  $D_2 \in \text{Der}_{k_2} A$  define

$$[D_1, D_2] = D_1 \circ D_2 - (-1)^{k_1 k_2} D_2 \circ D_1 \in \text{Der}_{k_1+k_2} A$$

Then

$[D_1, D_2]$  is a derivation of degree  $k_1 + k_2$  of A.

Proof

$$\begin{aligned}
 [D_1, D_2](a_i a_j) &= D_1(D_2 a_i a_j + (-1)^{i k_2} a_i D_2 a_j) + \\
 &\quad - (-1)^{k_1 k_2} D_2(D_1 a_i a_j + (-1)^{i k_1} a_i D_1 a_j) = \\
 &= \cancel{D_1 D_2 a_i \cdot a_j} + (-1)^{(i+k_2)k_1} \cancel{D_2 a_i \cdot D_1 a_j} + \\
 &\quad \cancel{(-1)^{i k_2} D_1 a_i \cdot D_2 a_j} + (-1)^{i k_2} \cancel{(-1)^{i k_1} a_i \cdot D_1 D_2 a_j} \\
 &\quad - \cancel{(-1)^{k_1 k_2} D_2 D_1 a_i \cdot a_j} - \cancel{(-1)^{k_1 k_2} D_1 a_i \cdot D_2 a_j} (-1)^{(i+k_1)k_2} + \\
 &\quad - \cancel{(-1)^{k_1 k_2} (-1)^{i k_1} D_2 a_i \cdot D_1 a_j} - \cancel{(-1)^{k_1 k_2} (-1)^{i k_1} (-1)^{i k_2} a_i \cdot D_2 D_1 a_j} \\
 &= \underbrace{[D_1, D_2](a_i) \cdot a_j}_{=} + (-1)^{i(k_1+k_2)} \underbrace{[a_i D_1 D_2 a_j - (-1)^{k_1 k_2} a_i D_2 D_1 a_j]}_{=} \\
 &= ([D_1, D_2] a_i) a_j + (-1)^{i(k_1+k_2)} a_i [D_1, D_2] a_j \\
 &\quad \uparrow \\
 &\quad a_k !
 \end{aligned}$$

Note that

$$\text{a) } [D_1, D_2] = -(-1)^{k_1 k_2} [D_2, D_1]$$

$\Rightarrow (\text{Der } A, [\cdot, \cdot])$  anti abelian  $\mathbb{Z}$  graded algebra.

b) one can check that:

$$[D_i, [D_j, D_k]] = [[D_i, D_j], D_k] + (-1)^{ij} [D_j, [D_i, D_k]]$$

and this differs from the Jacobi identity  
by  $(-1)^{ij}$ .

### Definition

B- an anti abelian  $\mathbb{Z}$  graded algebra is called  
~~the~~ graded Lie algebra iff.  
 $b_i \cdot (b_j \cdot b_k) = (b_i \cdot b_j) b_k + (-1)^{ij} b_j (b_i \cdot b_k)$

As an example take  $B = \text{Der } A$ ,  $\cdot = [\cdot, \cdot]$ .

4° Returning to  $(\Lambda M, \wedge)$

$$\text{Der}_1(\Lambda M) \ni d$$

$$\text{Der}_{-1}(\Lambda M) \ni X$$

Note that  $\text{Der}_{-2}(\Lambda M) = \{0\}$ .

because if  $D \in \text{Der}_{-2}(\Lambda M)$

$$Df \equiv 0 \quad (\text{no } -2 \text{ forms})$$

$$D\lambda \equiv 0 \quad (\text{no } -1 \text{ forms})$$

but functions and 1-forms generate entire  $\Lambda M$ .  $\square$

$$\text{So } D\omega \equiv 0. \Rightarrow \boxed{\text{Der}(\Lambda M) = \bigoplus_{k=-1}^n \text{Der}_k(\Lambda M)}$$

in particular  $X \wedge Y + Y \wedge X = f \wedge k \wedge l = 0$ .

In particular:

$$\text{Der}_{-2}^A M \ni [X_J, Y_J] = X_J \circ Y_J - (-1)^{(-1)(-1)} Y_J \circ X_J = \boxed{X_J \circ Y_J + Y_J \circ X_J = 0}$$

What about

$$[d, X_J] = d \circ X_J - (-1)^{(-1) \cdot 1} X_J \circ d = d \circ X_J + X_J \circ d ?$$

This is a derivation of degree  $-1+1=0$ .

We denote it by

$$\boxed{\begin{matrix} f \\ X \end{matrix}} = d \circ X_J + X_J \circ d = [d, X_J]$$

We have in addition

$$\begin{aligned} \text{Der}_+^A M \ni [f_x, d] &= f_x \circ d - (-1)^{0 \cdot (-1)} d \circ f_x = f_x \circ d - d \circ f_x \\ &= (d \circ X_J + X_J \circ d) \circ d - d \circ (d \circ X_J + X_J \circ d) = 0. \end{aligned}$$

$$\boxed{d \circ f_x = f_x \circ d}$$

$$\begin{aligned} \text{Der}_+^A M \ni [f_x, Y_J] &= f_x \circ Y_J - (-1)^{0 \cdot (-1)} Y_J \circ f_x = \\ &= f_x \circ Y_J - Y_J \circ f_x = \boxed{[X_J, Y_J]} \uparrow \\ &\quad \text{almost obvious!} \end{aligned}$$

$$\boxed{f_x \circ Y_J - Y_J \circ f_x = [X_J, Y_J]}$$

$$\boxed{[f_x, f_y] = ?}$$

8

(3) Lie derivative of tensor fields

$\mathfrak{X}_s^r(M) \ni$

$T$ - tensor field of type $(r, s)$	$T : \underbrace{\mathcal{F}(M) \times \dots \times \mathcal{F}(M)}_s \times \underbrace{\Lambda^r M \times \dots \times \Lambda^r M}_{r+s} \rightarrow \mathcal{F}(M)$ $(r+s)$ - $\mathcal{F}$ linear.
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Let  $M$  and  $M'$  two manifolds,  $\varphi : M \xrightarrow[\text{smooth map}]{\varphi} M'$

1°) Pull-back of a function

$$\varphi^* : \mathcal{F}(M') \rightarrow \mathcal{F}(M)$$

$$(\varphi^* f')(p) := f'(\varphi(p)) \quad \text{i.e. } \varphi^* f' = f' \circ \varphi$$

2°) Push forward of tangent vectors

$$\varphi_{*p} : T_p M \longrightarrow T_{\varphi(p)} M'$$

$X_p$  - a vector tangent to  $M$  at  $p$

$\gamma(t)$  - a curve passing through  $p$ , ~~tangent~~  
with a tangent vector  $X_p$

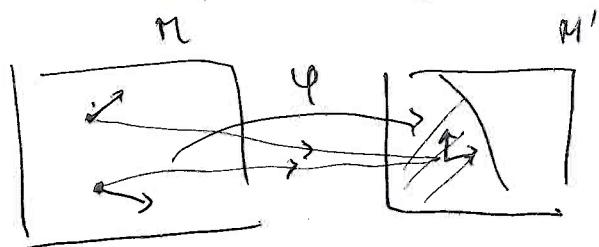
$\tilde{\gamma}(t) = \varphi(\gamma(t))$  - a curve in  $M'$  passing through  $\varphi(p)$ :  $\tilde{\gamma}(0) = \varphi(p)$

$\varphi_{*p} X_p =$  tangent vector to  $\tilde{\gamma}(t)$  at  $t=0$  i.e. in  $\varphi(p)$ .

A formula:

$$(\varphi_{*p} X_p)(f') = X(\varphi^* f')$$

3°) Trouble with vector fields



For transporting vector fields one needs diffeomorphisms

$$\varphi: M \xrightarrow{\text{diffeo}} M'$$

Then one transforms  $\mathbf{X}$  by transporting point by point  
all tangent vectors representing  $\mathbf{X}$ . This defines  $\varphi^*: \mathcal{X}(M) \rightarrow \mathcal{X}(M')$

4°) Transport of tensorfields of type  $(\overset{0}{s})$  :  $\mathcal{X}_s^0(M)$

given  $\varphi: M \rightarrow M'$  there exist a unique

map  $\varphi^*: \mathcal{X}_s^0(M') \rightarrow \mathcal{X}_s^0(M)$  st.

a)  $\varphi^*$  is  $\mathbb{R}$ -linear

b)  $\varphi^*(\omega^1 \otimes v^1) = \varphi^*(\omega^1) \otimes \varphi^*(v^1)$

c)  $\varphi^*(\omega^1 \wedge v^1) = \varphi^*(\omega^1) \wedge \varphi^*(v^1)$  if  $\omega^1, v^1 \in \Lambda^k M', \Lambda^l M'$

d)  $\varphi^*(\Lambda^k M') \subset \Lambda^k M$

e)  $\varphi^* \circ d = d \circ \varphi^*$

f)  $\varphi^* f' = f' \circ \varphi \quad \forall f' \in \mathcal{F}(M')$

5°) Tensor fields  $(\overset{r}{s})$

$\varphi: M \rightarrow M'$  diffeomorphism.

$$\tilde{\varphi}: \mathcal{X}_s^r(M) \rightarrow \mathcal{X}_s^r(M')$$

we have  $\varphi^*: \mathcal{X}_s^0(M') \rightarrow \mathcal{X}_s^0(M)$  and

$$(\varphi^{-1})^*: \mathcal{X}_s^0(M) \rightarrow \mathcal{X}_s^0(M')$$

On We define  $\varphi_*: \mathcal{X}_s^r(M) \rightarrow \mathcal{X}_s^r(M')$  by  $\varphi_*(X \otimes Y \otimes \dots \otimes Z) =$   
 $= (\varphi_* X) \otimes \varphi_*(Y) \otimes \dots \otimes \varphi_*(Z)$

and finally

$$\begin{aligned}\tilde{\varphi}(x_1 \otimes \dots \otimes x_r \otimes \lambda^1 \otimes \dots \otimes \lambda^s) &= \\ &= (\varphi_* x_1) \otimes \dots \otimes \varphi_* x_r \otimes (\varphi^*)^* \lambda^1 \otimes \dots \otimes (\varphi^*)^* \lambda^s\end{aligned}$$

6°) Transport map  $\tilde{\varphi}: \mathcal{X}_s^r(M) \rightarrow \mathcal{X}_s^{r'}(M')$

commutes with contractions,

where a contraction  $C_{i,j}$  is a map:

$$C_{i,j}: \mathcal{X}_s^r(M) \xrightarrow{\text{$F$-linear}} \mathcal{X}_{s-1}^{r-1}(M)$$

$$\begin{aligned}C_{i,j}(x_1 \otimes \dots \otimes \overset{i}{x_i} \otimes \dots \otimes \lambda^1 \otimes \dots \otimes \lambda^s) &= \\ &= x_1 \otimes \dots \otimes \underset{i\text{th}}{\underset{\uparrow}{x_i}} \otimes \lambda^1 \otimes \dots \otimes \underset{j\text{th}}{\underset{\uparrow}{\lambda^j}} \otimes \dots \otimes \lambda^s \cdot \langle x_i, \lambda^j \rangle\end{aligned}$$

removed

7°) LIE DERIVATIVE

X - vector field on M

$\varphi_t$  - its local 1-parameter group of transformations in  $U$

around p

$$\boxed{(L_X T)_p = \lim_{t \rightarrow 0} \frac{T_p - (\varphi_t T)_p}{t} = - \left. \frac{d}{dt} \right|_{t=0} (\varphi_t T)_p}$$

8°) Properties:

- a)  $\mathcal{L}_X$  preserves the type of a tensor  $(^r_s) \rightarrow (^r_s)$
- b)  $\mathcal{L}_X$  is  $\mathbb{R}$ -linear
- c)  $\mathcal{L}_X(K \otimes L) = (\mathcal{L}_X K) \otimes L + K \otimes \mathcal{L}_X L$
- d)  $\mathcal{L}_X$  commutes with contractions
- e)  $\mathcal{L}_X(\Lambda M) \subset \Lambda M$
- f)  $\mathcal{L}_X(\omega \wedge \tau) = \mathcal{L}_X \omega \wedge \tau + \omega \wedge \mathcal{L}_X \tau$
- g)  $\mathcal{L}_X \circ d = d \circ \mathcal{L}_X$  on  $T \in \Lambda M$
- h)  $[\mathcal{L}_X, \mathcal{L}_Y] = \mathcal{L}_{[X, Y]}$ .

9°) Lie derivative of a function

$$\begin{aligned} (\mathcal{L}_X f)_p &= -\left. \frac{d}{dt} ((\varphi_{-t})^* f)(p) \right|_{t=0} = -\left. \frac{d}{dt} (f \circ \varphi_t)(p) \right|_{t=0} = \\ &= -\left. \frac{d}{dt} f(\varphi_{-t}(p)) \right|_{t=0} = \frac{d}{dt} f(\varphi_t(p)) = X_p(f) \\ \Rightarrow \quad \boxed{\mathcal{L}_X f = X(f)} \end{aligned}$$

10°) Lie derivative of a k-form

$$\boxed{\mathcal{L}_X \omega = X \lrcorner (d\omega) + d(X \lrcorner \omega)} \quad \text{i.e. } \cancel{\text{def}}$$

on forms, the operator  $\mathcal{L}_X$  is equal to  
this what we had before.

Proof

on functions:

$$\text{but: } \left. \begin{array}{l} \mathcal{L}_X f = X(f) \\ (X \lrcorner d + d \lrcorner X)(f) = X \lrcorner df + d(X \lrcorner f) = X(f) \end{array} \right\} \text{ok}$$

on 1-forms (it is enough on differentials)

$$\text{but: } \left. \begin{array}{l} \mathcal{L}_X df = d(\mathcal{L}_X f) = d(X(f)) \\ (X \lrcorner d + d \lrcorner X)(df) = X \lrcorner df + d(X \lrcorner df) = d(X(f)) \end{array} \right\} \text{ok}$$

Functions and 1-forms generate  $\Lambda M$ .

□.

## 11° Lie derivative of a vector field

$$\boxed{\mathcal{L}_X Y = [X, Y]} \quad (*)$$

To prove it we need

### 14) Usefull formula for the exterior derivative

$$\boxed{\begin{aligned} (d\omega)(x_0, x_1, \dots, x_k) &= \sum_{i=1}^k (-1)^i x_i \left( \overset{\text{without } x_i}{\omega}(x_0, \overset{\vee}{\dots}, \overset{\vee}{x_k}) \right) + \\ &+ \sum_{0 \leq i < j \leq k} (-1)^{i+j} \overset{\text{without } x_i \text{ and } x_j}{\omega}([x_i, x_j], x_0, \overset{\vee}{\dots}, \overset{\vee}{x_k}) \end{aligned}}$$

In particular for 1-forms:

$$\boxed{(d\omega)(X, Y) = X(\omega(Y)) - Y(\omega(X)) - \omega([X, Y])}$$

Proof of (\*) at point  $11^\circ$ )  $\quad Y$ -vector field,  $\omega$  - 1-form:

Note that  $Y \lrcorner \omega = C_1(Y \otimes \omega)$

$$\begin{aligned} \underset{x}{\mathcal{L}}(Y \lrcorner \omega) &= \underset{x}{\mathcal{L}} C_1(Y \otimes \omega) = C_1 \underset{x}{\mathcal{L}}(Y \otimes \omega) = \\ &= C_1 \left( \underset{x}{\mathcal{L}} Y \otimes \omega + Y \otimes \underset{x}{\mathcal{L}} \omega \right) = \\ &= \omega(\underset{x}{\mathcal{L}} Y) + Y \lrcorner (\underset{x}{\mathcal{L}} \omega) \end{aligned}$$

$$\begin{aligned} \Rightarrow \omega(\underset{x}{\mathcal{L}} Y) &= \underset{x}{\mathcal{L}}(Y \lrcorner \omega) - Y \lrcorner (d(X \lrcorner \omega) + X \lrcorner d\omega) = \\ &= X(\omega(Y)) - Y \lrcorner d(\omega(X)) - Y \lrcorner X \lrcorner d\omega = \\ &= X(\omega(Y)) - Y(\omega(X)) - d\omega(X, Y) = \\ &= \omega([X, Y]) \quad \forall \omega \Rightarrow \\ \Rightarrow \boxed{\underset{x}{\mathcal{L}} Y = [X, Y]} \end{aligned}$$

15) Local anholonomic frames on Fribenius theorem revisited

$\{X_\mu\}$  in  $U \subset M$  is a frame in  $U$  iff  
 $\underset{\text{open}}{\cap} \{X_{\mu|p}\}_{\mu=1}^n$  is a basis of  $T_p(M)$   $\forall p \in U$

1<sup>o</sup> exaple  $(\frac{\partial}{\partial x^i})$  is a frame in  $(M, x)$ .

↑  
by definition it is called holonomic frame

But there are anholonomic i.e. such that  $[X_\mu, X_\nu] \neq 0$ .

e.g.

$$\underline{X_\mu = A_\mu^\nu(x) \frac{\partial}{\partial x^\nu}}$$

$A_\mu^\nu(x)$  invertible  
at every point  $p$ .

## 2<sup>o</sup> Maurer - Cartan formula

$\{X_\mu\}$  local frame:

$$[X_\mu, X_\nu] = C_{\mu\nu}^{\sigma} X_\sigma \quad C_{\mu\nu}^{\sigma} = C_{\mu\nu}^{\sigma}(x).$$

↑  
Coefficients of anholonomy

$$C_{\mu\nu}^{\sigma} = -C_{\nu\mu}^{\sigma}.$$

$C_{\mu\nu}^{\sigma} \equiv 0 \iff \exists_{x \in U} X_\mu = \frac{\partial}{\partial x^\mu}$

Let  $\{\omega^\mu\}$  be a basis in  $\Lambda^1 U$  dual to  $\{X_\mu\}$  i.e.

$$X_\mu \lrcorner \omega^\nu = \delta_\mu^\nu. \quad (\text{i.e. } \omega^\nu(X_\mu) = \delta_\mu^\nu).$$

Then N.C.

$[X_\mu, X_\nu] = C_{\mu\nu}^{\sigma} X_\sigma \iff d\omega^\mu = -\frac{1}{2} C_{\mu\sigma}^{\tau} \omega^\nu \wedge \omega^\sigma$

Proof

$$\begin{aligned} d\omega^\mu(X_\mu, X_\nu) &= X_\mu(\omega^\mu(X_\nu)) - X_\nu(\omega^\mu(X_\mu)) - \overset{\circ}{\omega}([X_\mu, X_\nu]) = \\ &\quad \underset{\delta\delta_\nu}{\cancel{X_\mu(\omega^\mu(X_\nu))}} - \underset{\delta\delta_\mu}{\cancel{X_\nu(\omega^\mu(X_\mu))}} - \overset{\circ}{\omega}([X_\mu, X_\nu]) = \\ &= -\omega^\mu(C_{\mu\nu}^{\sigma} X_\sigma) = -C_{\mu\nu}^{\sigma} \end{aligned}$$

□.

### 3° Fröbenius theorem once again

$S$ -distribution on  $M$

$$S^* = \{ \omega \in \Lambda^1 M : \omega(x) = 0 \quad \forall x \in S \}$$

$\{X_i\}$  - vector fields spanning  
 $S$  in  $M$        $\{\theta^\alpha\}$  - 1-forms spanning  $S^*$   
 in  $M$ .

$$X_i : i=1, \dots, m$$

$$\theta^\alpha : \alpha=m+1, \dots, n.$$

The Fröbenius

the following conditions are equivalent:

- 1)  $S$  is involutive
- 2) through every point passes precisely one integral manifold of  $S$
- 3)  $[X_i, X_j] = C_{ij}^k X_k$
- 4)  $X_i = a_i^\beta(x^\kappa, x^\ell) \frac{\partial}{\partial x^\beta}$
- 5)  $d\theta^\alpha \wedge \theta^{m+1} \wedge \dots \wedge \theta^n = 0 \quad \forall \alpha = m+1, \dots, n$
- 6)  $\theta^\alpha = b_\beta^\alpha(x^\kappa, x^\ell) dx^\beta$

Proof

$$4) \Rightarrow 6) \text{ obvious } (\theta^\alpha(X_i) = 0.)$$

$$6) \Rightarrow 5) \text{ obvious}$$

$$5) \Rightarrow 3) \quad d\theta^\alpha = -\frac{1}{2} C_{\mu\nu}^\alpha \theta^\mu \theta^\nu - \frac{1}{2} C_{ij}^\alpha \theta^i \theta^j - \frac{1}{2} C_{ip}^\alpha \theta^i \theta^p$$

$$5) \Rightarrow \underline{C_{ij}^\alpha = 0}$$