

Lecture 7. 29.03.2011

Summary of lecture 6

k-forms  $\alpha \in V \otimes \wedge^k M$  s.t.  $\alpha(ae) = g(a)\alpha$

connections  $\omega \in \text{End}(V) \otimes \wedge^1 M$   $\omega(ae) = a\omega(e)a^{-1} - dae^{-1}$

covariant differential  $D\alpha = d\alpha + g'(\omega) \wedge \alpha$

$$g'(A) = \left. \frac{d}{dt} \right|_{t=0} g(\exp(tA))$$

$$D\alpha^A = d\alpha^A + g^A_{B\mu\nu} \omega^\nu \wedge \alpha^B$$

$$g^A_{B\mu\nu} = \left. \frac{\partial g^A_B}{\partial a^\mu} \right|_{a=1}$$

e.g.

$$\left[ \begin{array}{l} DK^\mu = dK^\mu + \omega^\mu_{\nu} \wedge K^\nu \\ DK_\mu = dK_\mu - \omega^\nu_{\mu} \wedge K_\nu \\ DK^\mu_{\nu} = dK^\mu_{\nu} + \omega^\mu_{\rho} \wedge K^\rho_{\nu} - \omega^\rho_{\nu} \wedge K^\mu_{\rho} \\ DK_{\mu\nu} = dK_{\mu\nu} - \omega^\rho_{\mu} \wedge K_{\rho\nu} - \omega^\rho_{\nu} \wedge K_{\mu\rho} \text{ etc.} \end{array} \right.$$

etc.

moving (co)frames:  $\theta^\mu(e) = e^\mu$

torsion:  $\Theta^\mu = d\theta^\mu + \omega^\mu_{\nu} \wedge \theta^\nu = D\theta^\mu$

curvature:  $\Omega^\mu_{\nu} = d\omega^\mu_{\nu} + \omega^\mu_{\rho} \wedge \omega^\rho_{\nu}$

Bianchi identities:  $\left\{ \begin{array}{l} D\Theta^\mu = \Omega^\mu_{\nu} \wedge \theta^\nu \\ D\Omega^\mu_{\nu} = 0 \end{array} \right.$

Ricci formula:  $D^2\alpha^A = g^A_{B\mu\nu}(\Omega) \wedge \alpha^B$

Note that

$$\Theta^\mu = \frac{1}{2} T^\mu_{\nu\rho} \theta^\nu \wedge \theta^\rho$$

$$\Omega^\mu_{\nu} = \frac{1}{2} R^\mu_{\nu\rho\sigma} \theta^\rho \wedge \theta^\sigma$$

$T^\mu_{\nu\rho}$  - torsion tensor

$R^\mu_{\nu\rho\sigma}$  - curvature tensor

## 7) Covariant differentiation (Koszul notation)

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$\alpha^A$  - zero-form  $\Rightarrow$

$$D\alpha^A \in V \otimes \Lambda^1 M \Rightarrow \boxed{D\alpha^A = \nabla_{\mu} \alpha^A \theta^{\mu}}$$

$\nabla_{\mu} \alpha^A$  - covariant derivative of  $\alpha^A$  in the direction of the frame vector  $e_{\mu}$

$$\boxed{\nabla_{\mu} \alpha^A = e_{\mu} \lrcorner D\alpha^A}$$

$$X^{\mu} e_{\mu} \lrcorner D\alpha^A = X \lrcorner D\alpha^A$$

"

$$\nabla_X \alpha^A \Rightarrow \boxed{\nabla_X \alpha^A = X \lrcorner D\alpha^A}$$

$\nabla_X$  is a map "from tensors to tensors of the same type"

More formally (in the language "without indices")

$$\mathcal{X}(M) \times \mathcal{X}_s^r(M) \ni (X, K) \longmapsto \nabla_X K \in \mathcal{X}_s^r(M)$$

Properties:

1°  $\nabla_X$  preserves type of a tensor field

$$2^{\circ} \nabla_{fX+gY} = f\nabla_X + g\nabla_Y$$

3°  $\nabla$  is  $\mathbb{R}$ -linear in  $K$

4° satisfies Leibnitz rule:

$$\nabla_X (K \otimes L) = \nabla_X K \otimes L + K \otimes \nabla_X L$$

5°  $\nabla_X$  commutes with contractions

$$6^{\circ} \nabla_X f = X(f).$$

Remark 1

if  $K \in \mathcal{X}_s^r(M)$  and we have  $\nabla$  as above

$\Rightarrow$  we define  $\nabla K$  as a tensor field of type  $\binom{r}{s+1}$

by:

$$\nabla K(X_1, \dots, X_r, X_0, X_1, \dots, X_s) = (\nabla_{X_0} K)(X_1, \dots, X_r, X_1, \dots, X_s)$$

Exercice explain relation between  $\nabla K$  and  $DK$   
 when  $K$  is a usual  $s$ -form here and  $D$ -form with  $s$  antisymmetric indices here

Remark 2

If  $\{e_\mu\}$  is a local frame in  $U \subset M$  then

consider

$$\nabla_{e_\mu} e_\nu = \Gamma_{\nu\mu}^\sigma e_\sigma$$

Dual frame:

$$\begin{aligned} (\nabla_{e_\mu} e^\nu)(e_\sigma) &= c_i^i (\nabla_{e_\mu} e^i \otimes e_\sigma) = \\ &= c_i^i \nabla_{e_\mu} (e^i \otimes e_\sigma) - c_i^i e^i \otimes \nabla_{e_\mu} e_\sigma = \\ &= c_i^i \nabla_{e_\mu} (\delta_\sigma^i) - c_i^i e^i \otimes \Gamma_{\sigma\mu}^\alpha e_\alpha = \\ &= -\Gamma_{\sigma\mu}^\nu \end{aligned}$$

$$\Rightarrow \nabla_{e_\mu} e^\nu = -\Gamma_{\sigma\mu}^\nu e^\sigma$$

Notation  $\nabla_{e_\mu} := \nabla_\mu$

if

$$K = K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} e_{\mu_1} \otimes \dots \otimes e_{\mu_r} \otimes e^{\nu_1} \otimes \dots \otimes e^{\nu_s}$$

$$\begin{aligned} \nabla_x K &= X(K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}) e_{\mu_1} \otimes \dots \otimes e^{\nu_s} + \\ &+ K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} \nabla_x e_{\mu_1} \otimes \dots \otimes e^{\nu_s} + \\ &+ \dots + K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} e_{\mu_1} \otimes \dots \otimes \nabla_x e^{\nu_s} = \end{aligned}$$

$$\begin{aligned} &= X^\mu \left[ e_\mu (K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}) e_{\mu_1} \otimes \dots \otimes e^{\nu_s} \right. \\ &\quad + \Gamma_{\mu\lambda}^\beta K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} e_\beta \otimes \dots \otimes e^{\nu_s} + \\ &\quad \vdots \\ &\quad \left. - \Gamma_{\nu\mu}^\beta K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} e_{\nu_1} \otimes \dots \otimes e^\beta \right] = \end{aligned}$$

$$\begin{aligned} &= X^\mu \left[ e_\mu (K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}) + \right. \\ &\quad + \Gamma_{\beta\mu}^{\mu_1} K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} + \Gamma_{\beta\mu}^{\mu_2} K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} + \dots + \\ &\quad \left. - \Gamma_{\nu_1\mu}^\beta K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} - \dots - \Gamma_{\nu_s\mu}^\beta K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} \right] e_{\mu_1} \otimes \dots \otimes e^{\nu_s} \\ &= X^\mu (\nabla_\mu K)^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} e_{\mu_1} \otimes \dots \otimes e^{\nu_s} \end{aligned}$$

$$\begin{aligned} (\nabla_\mu K)^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} &= e_\mu (K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}) + \\ &+ \Gamma_{\beta\mu}^{\mu_1} K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} + \dots + \Gamma_{\beta\mu}^{\mu_r} K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} + \\ &- \Gamma_{\nu_1\mu}^\beta K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} + \dots - \Gamma_{\nu_s\mu}^\beta K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} \end{aligned}$$



Change of a frame:

$$e_\mu = a^\nu_\mu e'_\nu \quad a \in GL(n, \mathbb{R})$$

$$\Gamma^{\sigma}_{\nu\mu} e_\sigma = \Gamma^{\sigma}_{\nu\mu} a^\alpha_\sigma e'_\alpha$$

||

$$\nabla_\mu e_\nu = \nabla_\mu (a^\alpha_\nu e'_\alpha) = \partial_\mu (a^\alpha_\nu) e'_\alpha + a^\alpha_\nu (\nabla'_\mu e'_\alpha)$$

$$= \partial_\mu (a^\alpha_\nu) e'_\alpha + a^\alpha_\nu a^\beta_\mu \nabla'_{e'_\beta} e'_\alpha =$$

$$= \partial_\mu (a^\alpha_\nu) e'_\alpha + a^\alpha_\nu a^\beta_\mu \Gamma^{\sigma}_{\alpha\beta} e'_\sigma =$$

$$= a^\beta_\nu a^\sigma_\mu \Gamma^{\alpha}_{\beta\sigma} e'_\alpha + \partial_\mu (a^\alpha_\nu)$$

$$\boxed{a^\alpha_\sigma \Gamma^{\sigma}_{\nu\mu} = \Gamma^{\alpha}_{\beta\sigma} a^\beta_\nu a^\sigma_\mu + \partial_\mu (a^\alpha_\nu)}$$

introduce:

$$\boxed{\Gamma^\sigma_\nu := \Gamma^{\sigma}_{\nu\mu} e^\mu}$$

$$\Rightarrow a^\alpha_\sigma \Gamma^\sigma_\nu = \Gamma^{\alpha}_{\beta\sigma} a^\beta_\nu e^\sigma + da^\alpha_\nu$$

$$\Rightarrow a^\alpha_\sigma \Gamma^\sigma_\nu = \Gamma^{\alpha}_{\beta\sigma} a^\beta_\nu + da^\alpha_\nu$$

$$\boxed{\Gamma^{\alpha}_{\beta\sigma} = a^\alpha_\mu \Gamma^\mu_{\beta\sigma} \bar{a}^{-1\sigma}_\nu - da^\alpha_\mu \bar{a}^{-1\mu}_\nu}$$

writing

$$\boxed{\Gamma^\sigma_\nu = \omega^\sigma_\nu(e)}$$

$$\boxed{\omega^\sigma_\nu(ae) = a^\beta_\nu \omega^\sigma_\beta(e) \bar{a}^{-1\sigma}_\alpha - da^\beta_\nu \bar{a}^{-1\beta}_\alpha}$$

$\Rightarrow$  we have a connection in the previous sense!

8) Torsion tensor  $X, Y \in \mathcal{X}(M)$ ,  $\nabla$ -covariant diff. 6

$$T(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y]$$

Fact  $T$  is a  $\text{typ} = \binom{1}{2}$  tensor field!

Proof

$$T(X, Y) = -T(Y, X)$$

f linearity?

$$T(fX, Y) = f \nabla_X Y - \nabla_Y (fX) - [fX, Y] =$$

$$= f \nabla_X Y - Y(f)X - f \nabla_Y X - f[X, Y] + Y(f)X$$

$$= f T(X, Y).$$

q.

In a local frame:

$$T(e_\mu, e_\nu) = \nabla_\mu e_\nu - \nabla_\nu e_\mu - [e_\mu, e_\nu] =$$

$$= (\Gamma_{\mu\nu}^\rho - \Gamma_{\nu\mu}^\rho - C_{\mu\nu}^\rho) e_\rho = T_{\mu\nu}^\rho e_\rho$$

$$\boxed{T_{\mu\nu}^\rho = \Gamma_{\nu\mu}^\rho - \Gamma_{\mu\nu}^\rho - C_{\mu\nu}^\rho} \quad \underline{\text{NEW}}$$

$$\underline{\underline{T_{\mu\nu}^\rho = -T_{\nu\mu}^\rho}}$$

Note that in a holonomic frame  $C_{\mu\nu}^\rho \equiv 0 \Rightarrow$

$$\underline{\underline{T_{\mu\nu}^\rho = 0 \text{ if } T_{\mu\nu}^\rho = \Gamma_{\nu\mu}^\rho}}$$

Historic name for a connection without torsion

$\equiv$  symmetric connection!  $\underline{\underline{T_{\mu\nu}^\rho = \Gamma_{\nu\mu}^\rho}}$

Calculating: (in the language of Lecture 6!)

$$\textcircled{H}^S(e) = de^S + \Gamma_{\mu\nu}^S e^\mu e^\nu = -\frac{1}{2} C_{\mu\nu}^S + \Gamma_{\mu\nu}^S e^\nu e^\mu$$

$$\frac{1}{2} T_{\mu\nu}^S e^\mu e^\nu \Rightarrow \boxed{T_{\mu\nu}^S = -\Gamma_{\mu\nu}^S + \Gamma_{\nu\mu}^S - C_{\mu\nu}^S} \quad \underline{\underline{\text{OLD}}}$$

$$T(X, Y) = \nabla_X Y - \nabla_Y X - [X, Y]$$

$$\Leftrightarrow \Theta^S = d\theta^S + \omega^S_{\mu\nu} \theta^\mu = \frac{1}{2} T^S_{\mu\nu} \theta^\mu \wedge \theta^\nu$$

9) Curvature tensor

$$X, Y \in \mathfrak{X}(M), \nabla$$

$$R(X, Y): \mathfrak{J}(M) \longrightarrow \mathfrak{J}(M)$$

$$R(X, Y)K = [\nabla_X, \nabla_Y]K - \nabla_{[X, Y]}K$$

Fact the second term makes  $R$  to be  $f$ -linear in  $K, X, Y$

Properties of  $R(X, Y)$ :

- 1  $f$ -linear in  $K, X, Y$
- 2 preserves type
- 3 commutes with contractions
- 4 satisfies Leibnitz rule.

e.g.

$$R(X, Y)f = [\nabla_X, \nabla_Y]f - [X, Y](f) =$$

$$= \nabla_X Y(f) - \nabla_Y X(f) - [X, Y]f = [X, Y]f - [X, Y]f = 0.$$

$$\Rightarrow f\text{-linear in } K$$

□.

in particular:

$$\mathfrak{X}(M) \times \mathfrak{X}(M) \times \mathfrak{X}(M) \ni (X, Y, Z) \longmapsto R(X, Y)Z \in \mathfrak{X}(M)$$

is  $f$ -linear in  $X, Y, Z$ .

Proof

$$\begin{aligned}
 R(fX, Y)Z &= [f\nabla_X, \nabla_Y]Z - \nabla_{[fX, Y]}Z = \\
 &= f[\nabla_X, \nabla_Y]Z - \nabla_Y(f)\nabla_X Z - f\nabla_{[X, Y]}Z + Y(f)\nabla_X Z = \\
 &= fR(X, Y)Z
 \end{aligned}$$

In second argument:  $R(X, Y) = -R(Y, X)$   $\square$ .

$R(X, Y)$  defines a tensor of type  $\binom{1}{3}$ :

$$\boxed{R(e_\mu, e_\nu)e_\sigma = R^\sigma_{\ \mu\nu} e_\sigma}$$

$$R^\sigma_{\ \mu\nu} = -R^\sigma_{\ \nu\mu}$$

$$\Rightarrow \boxed{\Omega^\sigma_{\ \rho}(e) = \frac{1}{2} R^\sigma_{\ \mu\nu} e^\mu \wedge e^\nu} \quad (*)$$

Fact

$$\Omega^\sigma_{\ \rho} = d\omega^\sigma_{\ \rho} + \omega^\sigma_{\ \mu} \wedge \omega^\mu_{\ \rho}$$

Indeed:

$$\begin{aligned}
 R^\sigma_{\ \mu\nu} e_\sigma &= R(e_\mu, e_\nu)e_\sigma = [\bar{\nabla}_\mu, \bar{\nabla}_\nu]e_\sigma - \nabla_{[e_\mu, e_\nu]}e_\sigma = \\
 &= \dots
 \end{aligned}$$

$$\begin{aligned}
 R^\sigma_{\ \mu\nu} &= e_\mu(\Gamma^\sigma_{\ \nu\rho}) - e_\nu(\Gamma^\sigma_{\ \mu\rho}) - c^\rho_{\ \mu\nu}\Gamma^\sigma_{\ \rho\rho} + \Gamma^\rho_{\ \mu\rho}\Gamma^\sigma_{\ \rho\nu} \\
 &\quad - \Gamma^\rho_{\ \nu\rho}\Gamma^\sigma_{\ \rho\mu}
 \end{aligned}$$

and this easily proves (\*)

$\square$ .



$$R(x, y) = [\bar{\nabla}_x, \nabla_y] - \nabla_{[x, y]}$$

$$\Leftrightarrow \Omega^a{}_v = d\omega^a{}_v + \omega^a{}_p \wedge \omega^p{}_v = \frac{1}{2} R^a{}_{\nu\sigma} \theta^\nu \wedge \theta^\sigma$$

10) Parallel transport

$\gamma$  - a curve of class  $C^1$ ,  $\dot{x} = \frac{dx}{dt}$

$\nabla_x K$  is called in such a case an absolute derivative of  $K$  along a curve  $\gamma$ .

To define this one needs only  $K$  along  $\gamma$ !!!

Indeed:  $\gamma(t) = (x^\mu(t))$   $\dot{x}^\mu = \frac{dx^\mu}{dt}$

$$(\nabla_x K)^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} =$$

$$= \dot{x}^\rho (\nabla_\rho K)^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} =$$

$$= \underbrace{\frac{dx^\rho}{dt} \frac{\partial}{\partial x^\rho}}_{\frac{d}{dt}} (K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}) + \underbrace{\dot{x}^\rho \Gamma^{\mu_1}_{\alpha\rho} K^{\alpha \dots \mu_r}_{\nu_1 \dots \nu_s} + \dots}_{\text{no problem here}}$$

$$= \frac{d}{dt} (K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}(t)) + \dots$$

$$= \left( \frac{D}{dt} K \right)^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s}$$

$$\left( \frac{D}{dt} K \right)^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} = \frac{d}{dt} K^{\mu_1 \dots \mu_r}_{\nu_1 \dots \nu_s} + \frac{dx^\rho}{dt} \Gamma^{\mu_1}_{\alpha\rho} K^{\alpha \dots \mu_r}_{\nu_1 \dots \nu_s} + \dots - \frac{dx^\rho}{dt} \Gamma^{\alpha}_{\nu_s\rho} K^{\mu_1 \dots \mu_r}_{\alpha \dots \nu_{s-1}}$$

## Definition

Tensor field  $K$  is parallelly transported along  $\gamma$

$$\text{iff } \nabla_x K = 0 \quad \left( \frac{D}{dt} K \equiv 0 \right)$$

Note that if  $\Gamma \equiv 0 \Rightarrow \left( \frac{D}{dt} K = 0 \Leftrightarrow \frac{d}{dt} K \equiv 0 \right)$ ,

i.e.  $K$  is parallelly transported in an affine space with  $\Gamma \equiv 0$  iff  $K$  has constant components!  
 ↑  
 frame dependent!

So in such a case this is the usual parallel transport.

We have

$\gamma: [0, 1] \rightarrow M$  and let's assume that  $\gamma$  is piecewise continuous

$$P_\gamma: \left( \text{Tensor algebra at } \gamma(0) \right) \longrightarrow \left( \text{Tensor algebra at } \gamma(1) \right)$$

$$K_{\gamma(0)} \xrightarrow{\quad \eta \quad} K_{\gamma(1)}$$

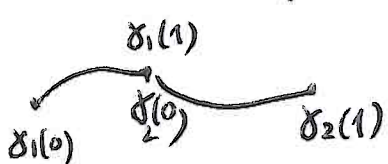
propagate the tensor  $K_{\gamma(0)}$  along  $\gamma$  in such a way that

$$\frac{DK}{dt} = 0 \quad \text{all the time.}$$

## Properties of $P_\gamma$

1) does not depend on parametrization

2) if two curves  $\gamma_1, \gamma_2$  s.t.  $\gamma_2(0) = \gamma_1(1)$



$$\Rightarrow (\gamma_2 \circ \gamma_1)(t) = \begin{cases} \gamma_1(2t) & 0 \leq t \leq \frac{1}{2} \\ \gamma_2(2t-1) & \frac{1}{2} < t \leq 1 \end{cases}$$

$$\boxed{P_{\gamma_2 \times \gamma_1} = P_{\gamma_2} \circ P_{\gamma_1}}$$

3°)  $P_\gamma$  is an isomorphism of tensor algebras that preserves the type and commutes with contractions.

## 11) Self parallels

Def

$\gamma$  - a curve of class  $C^2$  is selfparallel iff

$$\nabla_X X = \lambda X, \quad X = \frac{dx}{dt}$$

Locally:

$$\frac{d}{dt} X^\mu + X^\beta \Gamma_{\alpha\beta}^\mu X^\alpha = \lambda X^\mu, \quad X^\alpha = \frac{dz^\alpha}{dt}$$

$$\Rightarrow \boxed{\frac{d^2 z^\mu}{dt^2} + \Gamma_{\alpha\beta}^\mu \frac{dz^\alpha}{dt} \frac{dz^\beta}{dt} = \lambda \frac{dz^\mu}{dt}}$$

Reparametrization:

$$t \rightarrow t' = f(t) \quad \dot{f} \neq 0.$$

$$\frac{d}{dt} = \frac{dt}{dt'} \frac{d}{dt'} = \dot{f} \frac{d}{dt'}$$

$$\frac{d^2 x^\mu}{dt^2} = \frac{d}{dt} \left( \dot{f} \frac{dx^\mu}{dt'} \right) = \ddot{f} \frac{dx^\mu}{dt'} + \dot{f}^2 \frac{d^2 x^\mu}{dt'^2}$$

$$\Rightarrow \dot{f}^2 \left( \frac{d^2 x^\mu}{dt'^2} + \Gamma_{\alpha\beta}^\mu \frac{dx^\alpha}{dt'} \frac{dx^\beta}{dt'} \right) = (\lambda \dot{f} - \ddot{f}) \frac{dx^\mu}{dt'}$$

$$\Rightarrow \lambda \rightarrow \lambda' = \frac{\lambda \dot{f} - \ddot{f}}{\dot{f}^2}$$

### Corollaries:

- 1) definition is parametrization independent  $\lambda \rightarrow \lambda' = \frac{\hat{t} - \hat{t}''}{\hat{t}^2}$
- 2) there exist a parameter  $t'$  s.t.  $\lambda' = 0$ .  
Such a parameter is called an affine parameter
- 3) Affine parameter is given up to  $t' \rightarrow at' + b$   
Of  $a, b = \text{const.}$

Equation of selfparallels in an affine parametrization:

$$\boxed{\frac{d^2 x^\mu}{dt^2} + \Gamma^\mu_{\nu\rho} \frac{dx^\nu}{dt} \frac{dx^\rho}{dt} = 0.}$$

### (5) Riemannian manifolds

$(M, g)$  where  $g$  is symmetric, nondegenerate,  
tensor of type  $(2)$ .

$$g: \mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathcal{F}(M)$$

$$1) \quad g(X, Y) = g(Y, X)$$

$$2) \quad g(X, Y) = 0 \quad \forall X \Rightarrow Y = 0.$$

Signature of  $g$ :

at every point  $g$  can be brought to  $g = g_{\mu\nu} e^\mu e^\nu$

$$g_{\mu\nu} = \text{diag}(\underbrace{1, \dots, 1}_p, \underbrace{-1, \dots, -1}_q) \quad \text{by } GL(n, \mathbb{R}) \text{ transf.}$$

If a signature is

$$(1, \dots, 1, -1, \dots, -1) \text{ at a point } \Rightarrow$$

$\Rightarrow$  by continuity is the same in a neighbourhood.



1) Geodesics  $\gamma = \gamma(t)$  curve of class  $C^2$  in  $M$

Arc length:  $\gamma, \dot{\gamma} = \frac{d\gamma}{dt}$

$$s := \int_{t_0}^{t_1} \sqrt{|g(\dot{\gamma}, \dot{\gamma})|} dt, \quad \gamma = (x^\mu)$$

$$s = \int_{t_0}^t \sqrt{|g_{\mu\nu} \frac{dx^\mu}{dt} \frac{dx^\nu}{dt}|} dt$$

note:  $s$  is parametrization independent!

Def

$\gamma = \gamma(t)$  is a geodesic iff  $\gamma$  satisfies the necessary condition for extremizing  $s$ .

I.E.

$$(\gamma \text{ is geodesic}) \Leftrightarrow \left( \delta \int_{t_0}^t \sqrt{|g_{\mu\nu} \frac{dx^\mu}{dt} \frac{dx^\nu}{dt}|} dt = 0 \right) \\ \Leftrightarrow \delta x^\mu(t_0) = \delta x^\mu(t_1) = 0$$

Euler-Lagrange equations:

$$L = L(x^\mu, \dot{x}^\mu) = \sqrt{|g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu|}$$

$$\Rightarrow \frac{d}{dt} \frac{\partial}{\partial \dot{x}^\mu} L - \frac{\partial}{\partial x^\mu} L = 0 \Leftrightarrow$$

$$\frac{d}{dt} \frac{\partial}{\partial \dot{x}^\mu} \sqrt{|g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu|} - \frac{\partial}{\partial x^\mu} \sqrt{|g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu|} = 0$$

$\frac{\partial}{\partial x^\mu} = \partial_\mu$ :

$$\frac{d}{dt} \frac{g_{\mu\nu} \dot{x}^\nu}{\sqrt{|g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu|}} - \frac{1}{2} \frac{g_{\mu\nu, \alpha} \dot{x}^\alpha \dot{x}^\nu}{\sqrt{|g_{\mu\nu} \dot{x}^\mu \dot{x}^\nu|}} = 0 \quad (*)$$

Formulation is parameterization independent; we can choose any parameter. We take the arc length:  $s = \int \sqrt{\dots} dt$  14

$$\Rightarrow \frac{d}{ds} = \frac{d}{\sqrt{\dots} dt}$$

$$\Rightarrow (*) \quad \frac{1}{\sqrt{\dots}}$$

$$\frac{d}{ds} \left( g_{\mu\nu} \frac{dx^\nu}{ds} \right) - \frac{1}{2} g_{\alpha\gamma,\mu} \frac{dx^\alpha}{ds} \frac{dx^\gamma}{ds} = 0$$

$$g_{\mu\nu} \frac{d^2 x^\nu}{ds^2} + g_{\mu\nu,\alpha} \frac{dx^\alpha}{ds} \frac{dx^\nu}{ds} - \frac{1}{2} g_{\alpha\gamma,\mu} \frac{dx^\alpha}{ds} \frac{dx^\gamma}{ds} = 0$$

$$g_{\mu\nu} \frac{d^2 x^\nu}{ds^2} + \frac{1}{2} (g_{\mu\nu,\alpha} + g_{\alpha\nu,\mu} - g_{\alpha\mu,\nu}) \frac{dx^\alpha}{ds} \frac{dx^\nu}{ds} = 0$$

$$\frac{d^2 x^\nu}{ds^2} + \underbrace{\frac{1}{2} g^{\nu\beta} (g_{\beta\mu,\alpha} + g_{\alpha\beta,\mu} - g_{\alpha\mu,\beta})}_{\{\alpha\mu\}^\nu} \frac{dx^\alpha}{ds} \frac{dx^\mu}{ds} = 0$$

$$\Rightarrow \boxed{\frac{d^2 x^\nu}{ds^2} + \{\alpha\mu\}^\nu \frac{dx^\alpha}{ds} \frac{dx^\mu}{ds} = 0}$$

$$\boxed{\{\alpha\mu\}^\nu = \frac{1}{2} g^{\nu\beta} (g_{\beta\mu,\alpha} + g_{\alpha\beta,\mu} - g_{\alpha\mu,\beta})}$$

This defines a connection  $\omega^\mu$ , which in a coordinate frame  $dx^\mu$  is

$$\omega^\mu(dx^\alpha) = \{\alpha\nu\}^\mu dx^\nu$$

$\Rightarrow$  geodesics are self-parallel in this connection.

Note that

$$\textcircled{1} \Gamma^{\mu}_{\alpha\nu} = \left\{ \begin{matrix} \mu \\ \alpha\nu \end{matrix} \right\} = \left\{ \begin{matrix} \mu \\ \nu\alpha \end{matrix} \right\} = \Gamma^{\mu}_{\nu\alpha}$$

and  $dx^{\mu}$  is a coordinate frame. Then  $C^{\mu}_{\nu\sigma} = 0$

$$\text{and } T^{\mu}_{\nu\sigma} = \Gamma^{\mu}_{\sigma\nu} - \Gamma^{\mu}_{\nu\sigma} = 0$$

$\Rightarrow$  this connection has NO torsion

$$\begin{aligned} \textcircled{2} \omega^{\mu}_{\nu}(dx^{\alpha}) &= \frac{1}{2} g^{\mu\beta} (g_{\beta\nu,\alpha} + g_{\alpha\beta,\nu} - g_{\alpha\nu,\beta}) dx^{\alpha} = \\ \Gamma^{\mu}_{\nu}{}^{\alpha} &= \frac{1}{2} g^{\mu\beta} dg_{\beta\nu} + \frac{1}{2} g^{\mu\beta} (g_{\alpha\beta,\nu} - g_{\alpha\nu,\beta}) dx^{\alpha} \end{aligned}$$

Thus:

$$\begin{aligned} (Dg)_{\alpha\nu} &= dg_{\alpha\nu} - \Gamma^{\beta}_{\alpha} g_{\beta\nu} - \Gamma^{\beta}_{\nu} g_{\alpha\beta} = \\ &= \cancel{dg_{\alpha\nu}} - g_{\beta\nu} \left[ \frac{1}{2} \cancel{g^{\beta\mu} dg_{\mu\alpha}} + \frac{1}{2} g^{\beta\mu} (g_{\alpha\mu,\nu} - g_{\alpha\nu,\mu}) dx^{\alpha} \right] \\ &\quad - g_{\alpha\beta} \left[ \frac{1}{2} \cancel{g^{\beta\mu} dg_{\mu\nu}} + \frac{1}{2} g^{\beta\mu} (g_{\mu\beta,\nu} - g_{\mu\nu,\beta}) dx^{\alpha} \right] = 0 \end{aligned}$$

$$\Rightarrow \omega^{\mu}_{\nu}(dx^{\alpha}) = \left\{ \begin{matrix} \mu \\ \alpha\nu \end{matrix} \right\} dx^{\alpha}$$

is a connection which is

- $$\left\{ \begin{array}{l} \textcircled{1} \text{ torsionless } \oplus = 0 \quad \checkmark \\ \textcircled{2} \text{ such that } Dg \equiv 0 \quad \checkmark \end{array} \right.$$

$\nwarrow$  such connection is called metric

this is called Levi-Civita connection!