

Tensor fields on manifolds1) Vector fields

$M$  - differentiable manifold of class  $C^\infty$

$F(M)$  - set of smooth functions on  $M$

it is an algebra:

$$(f_1 + f_2)(p) = f_1(p) + f_2(p)$$

$$(c \cdot f_1)(p) = c \cdot f_1(p)$$

$$(f_1 \cdot f_2)(p) = f_1(p) \cdot f_2(p)$$

• Definition

$X$  is a vector field on  $M$  iff

$$X : F(M) \longrightarrow F(M) \quad \text{s.t. that}$$

①  $X$  is  $\mathbb{R}$ -linear:

$$X(c_1 f_1 + c_2 f_2) = c_1 X(f_1) + c_2 X(f_2) \quad \forall c_1, c_2 \in \mathbb{R} \quad \forall f_1, f_2 \in F(M)$$

$$\textcircled{2} \quad X(f \cdot g) = X(f) \cdot g + f \cdot X(g) \quad \forall f, g \in F(M)$$

↖ Leibniz rule.

• One can produce new vector fields by taking commutators:

$X, Y$  - vector field  $\Rightarrow$  define  $[X, Y] : F(M) \rightarrow F(M)$  by

$$[X, Y](f) = X(Y(f)) - Y(X(f))$$

Ex check that  $[X, Y]$  is a vector field.

Define  $\mathcal{X}(M)$  - set of all vector fields on  $M$ .

It is

a) Lie algebra over  $\mathbb{R}$

b) module over  $F(M)$ .

• Given  $X \in \mathcal{X}(M)$  we have a map  $X_p : F(M) \rightarrow \mathbb{R}$

defined by  $X_p(f) := X(f)(p)$ , called a value of  $X$  at  $p$

Obviously  $X_p$  is

a) linear

$$b) \quad X_p(f \cdot g) = X_p(f) \cdot g(p) + f(p) X_p(g)$$

- Definition A map  $X_p: F(M) \rightarrow \mathbb{R}$  satisfying a) and b) is called tangent vector to  $M$  at  $p$ .

One can add ~~and~~ tangent vectors, and multiply them by real numbers.  $\Rightarrow$  the set  $T_p M$  of all tangent vectors to  $M$  at  $p$  is a vector space. It is called tangent space to  $M$  at  $p$ .

- Example let  $]-\varepsilon, \varepsilon[ \ni t \rightarrow \gamma(t) \in M$  be a smooth curve, such that  $\gamma(0) = p$ .

Take as  $X_p$  a map defined by

$$X_p(t) = \left. \frac{d}{dt} f \circ \gamma(t) \right|_{t=0}.$$

It is a tangent vector at  $p$  (Ex. check it!)

- Fact  $\dim M = n \Rightarrow \dim T_p M = n$

$p \in U, x$ ; Let  $x^u$  be coordinates in  $U$ .  $x^u: p \rightarrow x^u(t)$

$$U \ni p \xrightarrow{x} \{x^u(p)\} \in \mathbb{R}^n$$

$\uparrow$   
u-th component  
of a vector in  
 $\mathbb{R}^n$ .

$\Rightarrow \frac{\partial}{\partial x^u} \Big|_p$  is a tangent vector at  $p$ , where  $\rightarrow$

$\rightarrow$  and  $\left( \frac{\partial}{\partial x^1} \Big|_p, \dots, \frac{\partial}{\partial x^n} \Big|_p \right)$  form a basis in  $T_p(U) = T_p(M)$

(Recall:  $\frac{\partial}{\partial x^u}(x^v) = \delta^v_u$ )

Locally in  $(U, x)$  every vector field can be written as:

$$\boxed{X = X^u \frac{\partial}{\partial x^u}} \quad \text{where } X^u = X(x^u).$$

## 2) Covariant tensor fields of type $\binom{0}{k}$ .

$$\lambda: \underbrace{\mathcal{X}(M) \times \dots \times \mathcal{X}(M)}_{k\text{-times}} \longrightarrow \mathcal{F}(M)$$

$\uparrow$   
 $\mathcal{F}(M)$  linear in each argument.

one can think about  $\lambda$  as a smooth map

$$M \ni p \xrightarrow{\text{smooth}} \lambda_p \in (T_p M)^* \otimes \dots \otimes (T_p M)^*$$

$$\lambda_p(X_1, \dots, X_k) := (\lambda(X_1, \dots, X_k))(p)$$

this in particular means that  $\lambda_p: T_p M \times \dots \times T_p M \longrightarrow \mathbb{R}$   
 $\uparrow$   
 $\mathbb{R}$ -linear in each argument.

### Examples

- a)  $k=1$  fields of 1-forms (1-form fields)  
 space of 1-form fields denoted by  $\Lambda^1 M$ .

In particular, given a function  $f \in \mathcal{F}(M)$  define  $df \in \Lambda^1 M$   
 by

$$df(X) := X(f)$$

$df$  — exterior differential of  $f$ .

Local basis in  $\Lambda^1 M$  : if  $(U, x)$  a chart around  $p$   
 $\Rightarrow$  we have functions  $p \mapsto x^\mu(p) \in \mathbb{R}$

Take :  $dx^\mu$

$\uparrow$   
 with component

This gives  $n$  1-forms; moreover

$$dx^\mu \left( \frac{\partial}{\partial x^\nu} \right) = \delta^\mu_\nu \Rightarrow \{dx^\mu\}_{\mu=1}^n \text{ basis in } \Lambda^1 U$$

dual to basis  $\frac{\partial}{\partial x^\mu}$ .

Any 1-form field in  $U$  is of the form  $\lambda = \lambda_\mu dx^\mu$ ;  $\lambda_\mu = \lambda \left( \frac{\partial}{\partial x^\mu} \right)$ .

b)  $k=2$ .Here a nice example is a metric, i.e.

$$g: \mathcal{X}(M) \times \mathcal{X}(M) \rightarrow \mathcal{F}(M)$$

$\mathcal{F}$ -linear in both arguments

such that

- ①  $g(X, Y) = g(Y, X)$  symmetric
- ②  $(\forall X \quad g(X, Y) = 0) \Rightarrow Y = 0$  nondegenerate.

A metric  $g$  on  $M$  defines a map

$$\tilde{g}: \mathcal{X}(M) \xrightarrow{\mathcal{F}\text{-linear}} \Lambda^1 M \quad \text{by} \quad X \mapsto \tilde{g}(X) \text{ s.t.}$$

$$\tilde{g}(X)(Y) = g(X, Y).$$

Condition ② means that  $\tilde{g}$  is invertible.  
(raising and lowering of an index).

$$\begin{aligned} g &= g_{\mu\nu} dx^\mu \otimes dx^\nu \\ \tilde{g}(X) &= g_{\mu\nu} X^\mu dx^\nu \\ &= X_\nu dx^\nu \end{aligned}$$

3) Antisymmetric covariant tensor fields of type  $\binom{0}{k}$  -  $k$ -forms  $\Lambda^k M$   
 $\lambda$ -tensor field of type  $\binom{0}{k}$  s.t.

$$\lambda(X_1, \dots, X_i, \dots, X_j, \dots, X_k) = -\lambda(X_1, \dots, X_j, \dots, X_i, \dots, X_k).$$

for all pairs  $X_i, X_j$  from the set  $X_1, \dots, X_k$ .

They form a set (vector space over  $\mathbb{R}$ , module over  $\mathcal{F}(M)$ )  $\Lambda^k M$   
 called  $k$ -forms on  $M$ .

How to produce them?

Wedge product  $\lambda^k \in \Lambda^k M$  and  $\lambda^l \in \Lambda^l M$  define  $\lambda^k \wedge \lambda^l \in \Lambda^{k+l} M$

by:  $(\lambda^k \wedge \lambda^l)(X_1, \dots, X_{k+l}) = \frac{1}{k!} \frac{1}{l!} \sum_{\sigma \in S_{k+l}} \text{sgn}(\sigma) \lambda^k(X_{\sigma(1)}, \dots, X_{\sigma(k)}) \lambda^l(X_{\sigma(k+1)}, \dots, X_{\sigma(k+l)})$

Example (check it!)

$$\lambda, \mu \in \Lambda^1 M \Rightarrow \lambda \wedge \mu = \lambda \otimes \mu - \mu \otimes \lambda$$

$$\lambda, \mu, \nu \in \Lambda^1 M \Rightarrow \lambda \wedge \mu \wedge \nu = \lambda \otimes \mu \otimes \nu + \nu \otimes \lambda \otimes \mu + \mu \otimes \nu \otimes \lambda - \mu \otimes \lambda \otimes \nu - \nu \otimes \mu \otimes \lambda - \lambda \otimes \nu \otimes \mu$$

- ⑤ Define  $\Lambda^0 M = \mathcal{F}(M)$  and if  $f \in \Lambda^0 M$  and  $\lambda \in \Lambda^k M$  define  $f \wedge \lambda = f \cdot \lambda$

$$\Rightarrow \left[ \Lambda M = \bigoplus_{k=0}^{\infty} \Lambda^k M, \wedge \right] \text{ — } \underline{\text{Cartan algebra over } M}$$

↑  
product (in particular associative)  
of course  $\Lambda^{k+l} M = 0 \quad \forall k+l > \dim M$

Fact (check it)

$$\boxed{\tilde{\omega}^k \wedge \tilde{\omega}^l = (-1)^{kl} \tilde{\omega}^l \wedge \tilde{\omega}^k}$$

- ⑥ Definition Exterior differential in  $\Lambda M$

$$d: \Lambda M \rightarrow \Lambda M \text{ s.t.}$$

- ①  $d\Lambda^k M \subset \Lambda^{k+1} M$
- ②  $d$  is  $\mathbb{R}$ -linear
- ③  $f \in \Lambda^0 M \Rightarrow df(X) = X(f)$
- ④  $d(\tilde{\omega}^k \wedge \tilde{\omega}^l) = d\tilde{\omega}^k \wedge \tilde{\omega}^l + (-1)^k \tilde{\omega}^k \wedge d\tilde{\omega}^l$
- ⑤  $d^2 \equiv 0$ .

Fact these properties define  $d$  uniquely!

- ⑦ Definition Inner product (hook operator)

if  $X \in \mathcal{X}(M)$  is a vector field define

$$X \lrcorner: \Lambda M \rightarrow \Lambda M \text{ s.t.}$$

- ①  $X \lrcorner f = 0 \quad \forall f \in \Lambda^0 M$
- ②  $X \lrcorner \Lambda^k M \subset \Lambda^{k-1} M \quad \forall k \geq 1$
- ③  $X \lrcorner$  is  $\mathbb{F}$ -linear
- ④  $X \lrcorner df = df(X) = X(f)$
- ⑤  $X \lrcorner (\tilde{\omega}^k \wedge \tilde{\omega}^l) = (X \lrcorner \tilde{\omega}^k) \wedge \tilde{\omega}^l + (-1)^k \tilde{\omega}^k \wedge (X \lrcorner \tilde{\omega}^l)$

Check that

$$(X \lrcorner \tilde{\omega}^k)(X_1, \dots, X_k) = \tilde{\omega}^k(X, X_1, \dots, X_k).$$

⑤ Derivation of degree k of algebra  $\Lambda M$  is a map

$$D : \Lambda M \rightarrow \Lambda M \quad \text{such that}$$

$\mathbb{R}$ -linear

①  $D(\Lambda^k M) \subset \Lambda^{k+1} M$

②  $D(\lambda^i \wedge \lambda^m) = (D\lambda^i) \wedge \lambda^m + (-1)^{jk} \lambda^i \wedge D\lambda^m$

Example  $d$  is a derivation of degree +1  
 $X \lrcorner$  is a derivation of degree -1.

• Definition A Lie derivative of a k-form  $\lambda$  with respect to the vector field  $X$  is

~~$$\mathcal{L}_X \lambda = (X \lrcorner + d \circ)$$~~

$$\mathcal{L}_X \lambda = (X \lrcorner \circ d + d \circ X \lrcorner) \lambda.$$

Exercise Check that  $\mathcal{L}_X$  is a derivation of degree 0 of  $\Lambda M$ .

Exercise Check that on  $\Lambda M$  we have

a)  $d \circ \mathcal{L}_X = \mathcal{L}_X \circ d.$

b)  $\mathcal{L}_X \circ Y \lrcorner - Y \lrcorner \circ \mathcal{L}_X = [X, Y] \lrcorner$

c)  $\mathcal{L}_X \circ \mathcal{L}_Y - \mathcal{L}_Y \circ \mathcal{L}_X = \mathcal{L}_{[X, Y]}.$

• ~~This derivative can be uniquely extended to a map  $\mathcal{L}_X$  from tensor fields of type  $\binom{m}{s}$  to tensor fields of type  $\binom{m}{s}$  such that:~~

- ~~$\mathcal{L}_X$  is  $\mathbb{R}$ -linear on  $\mathcal{T}(M)^{\binom{m}{s}}$~~
- ~~$\mathcal{L}_X (K \otimes L) = \mathcal{L}_X K \otimes L + K \otimes \mathcal{L}_X L$~~

- Useful formula for the exterior derivative:

$$d\omega(x_0, \dots, x_n) = \sum_{i=0}^n x_i(\omega(x_0, \dots, \underbrace{\phantom{x_0, \dots, x_n}}_{\text{without } x_i}, x_n)) (-1)^i + \\ + \sum_{0 \leq i < j \leq n} (-1)^{i+j} \omega([x_i, x_j], x_0, \dots, \underbrace{\phantom{x_0, \dots, x_n}}_{\text{without } x_i \text{ and without } x_j}, x_n)$$

In particular:

- $k=0$

$$(df)(x_0) = x_0(f) \quad \checkmark$$

- $k=1 \quad \lambda \in \Lambda^1 M$

$$(d\lambda)(x_0, x_1) = x_0(\lambda(x_1)) - x_1(\lambda(x_0)) - \lambda([x_0, x_1])$$

$$\boxed{(d\lambda)(x, y) = x(\lambda(y)) - y(\lambda(x)) - \lambda([x, y])} \quad (*)$$

### 3) Maurer-Cartan theorem

Local unholonomic frames  $\{X_\mu\}_{\mu=1}^n$  s.t.  $X_\mu \in \mathfrak{X}(M)$

is a frame in  $U$  if  $\{X_\mu|_p\}_{\mu=1}^n$  is a basis for  $T_p U \quad \forall p \in U$ .

Example  $\{X_\mu = \frac{\partial}{\partial x^\mu}\}$  is a frame in  $(M, x)$ .



by definition it is HOLONOMIC FRAME.

Note:  $[\frac{\partial}{\partial x^\mu}, \frac{\partial}{\partial x^\nu}] = 0$ .

Unholonomic frames such that  $[X_\mu, X_\nu] \neq 0$  for some (all)  $\mu, \nu$  s.

e.g.  $X_\mu = A_\mu^\nu(x) \frac{\partial}{\partial x^\nu}$ .

$A_\mu^\nu(x)$  is invertible at every point  $p \in U$ .

$\{X_\mu\}_{\mu=1}^n$  local frame

$$[X_\mu, X_\nu] = C_{\mu\nu}^\rho X_\rho \quad C_{\mu\nu}^\rho = C_{\nu\mu}^\rho(x) \text{ s.t. } C_{\mu\nu}^\rho = -C_{\nu\mu}^\rho,$$

↑  
functions. - coefficients of anholonomy.

### Fact

- $\{X_\mu\}$  is a holonomic frame  $\Leftrightarrow [X_\mu, X_\nu] = 0$
- $\{X_\mu\}$  - a frame,  $\{\omega^\mu\}$  - dual frame (cotframe), i.e.

$$\omega^\mu \in \Lambda^1 M \quad \forall \mu=1, \dots, n,$$

$$\omega^\mu(X_\nu) = \delta_\nu^\mu$$

$$X_\mu \lrcorner \omega^\mu$$

Then Maurer - Cartan.

$$[X_\mu, X_\nu] = C_{\mu\nu}^\rho X_\rho \Leftrightarrow d\omega^\mu = -\frac{1}{2} C_{\rho\sigma}^\mu \omega^\rho \omega^\sigma$$

Exercise Prove it, by applying (\*) from page 7.