



BI-HAMILTONIAN STRUCTURES FOR INTEGRABLE SYSTEMS ON TIME SCALES

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”30 YEARS OF BI-HAMILTONIAN SYSTEMS”

Time Scale Calculus

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* \mathbb{Q} , $\mathbb{R} - \mathbb{Q}$,

* The **open intervals**

are **not** time scales.

Jump Operators

Let \mathbb{T} be a time scale. $\forall x \in \mathbb{T}$, the **forward** and the **backward jump operators** are defined respectively

$$\sigma(x) := \inf\{y \in \mathbb{T} : y > x\}$$

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x is called

* **right dense** if $\sigma(x) = x$, **right scattered** if $\sigma(x) > x$,

* **left dense** if $\rho(x) = x$, **left scattered**, if $\rho(x) < x$

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The **graininess functions**

$$\mu(x) := \sigma(x) - x, \quad \nu(x) := x - \rho(x), \quad \text{for all } x \in \mathbb{T}.$$

Δ -Derivative

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A function $f : \mathbb{T} \rightarrow \mathbb{R}$ is Δ -smooth if it is infinitely Δ -differentiable at all points of \mathbb{T}^κ .

Example

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If $\mathbb{T} = \mathbb{K}_q$ for $x \neq 0$ then $\sigma(x) = qx$, $\rho(x) = q^{-1}x$

$$\Delta f(x) = \frac{f(qx) - f(x)}{(q - 1)x}$$

Δ -Integral

A function $F : \mathbb{T} \rightarrow \mathbb{R}$ is called Δ -antiderivative of $f : \mathbb{T} \rightarrow \mathbb{R}$ if $\Delta F(x) = f(x)$, $\forall x \in \mathbb{T}^\kappa$. Thus Δ -integral of f from a to b is

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Otherwise set $x_* = -\infty$, $x^* = \infty$.

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Δ -integral over an whole time scale is given as

$$\int_{\mathbb{T}} f(x) \Delta x := \int_{x_*}^{x^*} f(x) \Delta x = \lim_{x \rightarrow x^*} F(x) - \lim_{x \rightarrow x_*} F(x)$$

Regular time scales

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Thus the **inverse** E^{-1} is deduced

$$(E^{-1}f)(x) = f(\sigma^{-1}(x)) = f(\rho(x)).$$

Algebra of δ -differential operators

Let \mathcal{G} be an algebra of δ -**differential operators** equipped with the commutator,

$$\mathcal{G} = \mathcal{G}_{\geq k} \oplus \mathcal{G}_{< k} = \left\{ \sum_{i \geq k} u_i(x) \delta^i \right\} \oplus \left\{ \sum_{i < k} u_i(x) \delta^i \right\}.$$

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The classical **R -matrix**

$$R := \frac{1}{2} (P_{\geq k} - P_{< k}) \quad k = 0, 1.$$

The Lax Hierarchy

The Lax hierarchy of commuting evolution equations is

$$\frac{dL}{dt_n} = \left[\left(L^{\frac{n}{N}} \right)_{\geq k}, L \right] \quad k = 0, 1.$$

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The admissible finite-field Lax operators are

$$L = u_N \delta^N + u_{N-1} \delta^{N-1} + \dots + u_1 \delta + u_0 + \delta^{-1} u_{-1} + \sum_s \psi_s \delta^{-1} \varphi_s,$$

where for $k = 0$, u_N is time-independent and $u_{-1} = 0$.

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The natural **constraints** between dynamical fields

$$\sum_{i=-k}^{N+k-1} (-\mu)^i u_i - \mu \sum_s \psi_s \varphi_s = a,$$

The Continuous Limit of a Time Scale

$$\mathbb{T} = \hbar\mathbb{Z} \xrightarrow{\hbar \rightarrow 0} \mathbb{T} = \mathbb{R};$$

while

$$\mathbb{T} = \mathbb{K}_q \xrightarrow{q \rightarrow 1} \mathbb{T} = \mathbb{R}_+ \cup \{0\}.$$

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In the continuous time scale, the **algebra of δ -differential operators** turns out to be the **algebra of pseudo-differential operators**

$$\mathcal{G} = \mathcal{G}_{\geq k} \oplus \mathcal{G}_{< k} = \left\{ \sum_{i \geq k} u_i(x) \partial^i \right\} \oplus \left\{ \sum_{i < k} u_i(x) \partial^i \right\},$$

which is valid for $k = 0, 1, 2$ and $\partial u = u_x + u\partial$.

The Trace Functional

The **trace form** is introduced by

$$\mathrm{Tr}A := - \int_{\mathbb{T}} \frac{1}{\mu} (A_{<0})|_{\delta=-\frac{1}{\mu}} \Delta x \equiv \int_{\mathbb{T}} \sum_{i<0} a_i (-\mu)^{-i-1} \Delta x,$$

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Theorem: The **inner product** on \mathcal{G} defined by bilinear map

$$(\cdot, \cdot)_{\mathcal{G}} : \mathcal{G} \times \mathcal{G} \rightarrow \mathbb{K} \quad (A, B)_{\mathcal{G}} := \mathrm{Tr}(AB),$$

is **nondegenerate, symmetric and ad-invariant**.

The Poisson Tensors

Theorem: The **Linear Poisson tensor** has the form

$$\begin{aligned}\pi_0 dH &= [RdH, L] + R^\dagger [dH, L] \\ &= [L, dH_{<k}] + ([dH, L] (1 + \mu\delta)^{-1})_{<-k} (1 + \mu\delta).\end{aligned}$$

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Since the recursion operators Φ s.t

$$\Phi L_{t_n} = L_{t_{n+N}}.$$

are hereditary, the **quadratic Poisson tensor** π_1 can be reconstructed from Φ :

$$\pi_1 = \Phi \pi_0.$$

Bi-Hamiltonian Structure

Hence, the Lax hierarchies have **bi-Hamiltonian** structure

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$$L_{t_n} = \pi_0 dH_n = \pi_1 dH_{n-N},$$

where the related **Hamiltonians** are given by

$$H_n(L) = \frac{N}{n+N} \text{Tr} \left(L^{\frac{n}{N}+1} \right).$$

such that

$$dH_n = L^{\frac{n}{N}}$$

Example: Δ -differential AKNS

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The **first flow** is

$$\psi_{t_1} = \mu\psi^2\varphi + \Delta\psi,$$

$$\varphi_{t_1} = -\mu\varphi^2\psi + \Delta E^{-1}\varphi.$$

The **second flow** is

$$\begin{aligned}\psi_{t_2} = & \psi(\Delta\mu\psi\varphi + (\mu\psi\varphi)^2 + \varphi E(\psi) + \psi E^{-1}(\varphi)) \\ & + (E + 1)(\mu\psi\varphi\Delta\psi) + \Delta^2\psi,\end{aligned}$$

$$\begin{aligned}\varphi_{t_2} = & -\varphi(\Delta\mu\psi\varphi + (\mu\psi\varphi)^2 + \varphi E(\psi) + \psi E^{-1}(\varphi)) \\ & + \Delta E^{-1}(\varphi(E + 1)\mu\psi\varphi) - (\Delta E^{-1})^2\varphi.\end{aligned}$$

which is Δ -differential counterpart of soliton AKNS.

Continuous AKNS

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$$L = \partial + \psi \partial^{-1} \varphi.$$

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The **second flow** implies the **AKNS equation**

$$\begin{aligned} \frac{d\psi}{dt_2} &= \psi_{xx} + 2\psi^2 \varphi, \\ \frac{d\varphi}{dt_2} &= -\varphi_{xx} - 2\varphi^2 \psi \end{aligned}$$

Differentials

The implicit form of the **differentials**

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where n is the number of independent dynamical fields,

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where n is the number of independent dynamical fields,
such that the following holds

$$(dH, L_t)_{\mathfrak{g}} = \int_{\mathbb{T}} \left(\sum_{i=k}^{N+k-2} \frac{\delta F}{\delta u_i} (u_i)_t + \sum_s \left(\frac{\delta F}{\delta \psi_s} (\psi_s)_t + \frac{\delta F}{\delta \phi_s} (\phi_s)_t \right) \right) \Delta x.$$

Differential of AKNS

For **AKNS**: $N = 1$, $n = 2$, $k = 0$

The **differential** is of the form

$$dH = \gamma_1 + \delta\gamma_2$$

where

$$\gamma_1 = \frac{1}{\varphi} \frac{\delta H}{\delta \psi} - \frac{\Delta E^{-1}(\varphi)}{\psi \varphi E^{-1}(\varphi)} \Delta^{-1}(A)$$

$$\gamma_2 = - \frac{1}{\psi E^{-1}(\varphi)} \Delta^{-1}(A)$$

$$A = \frac{1}{\psi} \frac{\delta H}{\delta \psi} - \varphi \frac{\delta H}{\delta \varphi}$$

Bi-Hamiltonian structure for AKNS

The Linear Poisson Tensor

$$\pi_0 = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

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$$\pi_1 = \Phi\pi_0 = \begin{pmatrix} -\mu\psi^2 - 2\psi\Delta^{-1}\psi & \Delta + 2\mu\psi\varphi + 2\psi\Delta^{-1}\varphi \\ -\Delta^\dagger + 2\varphi\Delta^{-1}\psi & -\mu\varphi^2 - 2\varphi\Delta^{-1}\varphi \end{pmatrix}$$

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where $\Delta^\dagger = -\Delta E^{-1}$ and Recursion Operator is

$$\Phi = \begin{pmatrix} \Delta + 2\mu\psi\varphi + 2\psi\Delta^{-1}\varphi & \mu\psi^2 + 2\psi\Delta^{-1}\psi \\ -\mu\varphi^2 - 2\varphi\Delta^{-1}\varphi & \Delta^\dagger - 2\varphi\Delta^{-1}\psi \end{pmatrix}$$

Bi-Hamiltonian structure for AKNS

The related first three **Hamiltonians** are

$$H_0 = \text{Tr}(L) = \int_{\mathbb{T}} \psi \varphi \Delta x$$

$$H_1 = \frac{1}{2} \text{Tr}(L^2) = \int_{\mathbb{T}} \left(\varphi \Delta \psi + \frac{1}{2} \mu \psi^2 \varphi^2 \right) \Delta x$$

$$H_2 = \frac{1}{3} \text{Tr}(L^3) = \int_{\mathbb{T}} \left(\varphi \Delta^2 \psi - \psi^2 \varphi^2 + \psi \varphi^2 E \psi + \frac{1}{3} \psi \varphi E^{-1}(\psi \varphi) \right. \\ \left. + \frac{2}{3} \psi^2 \varphi E^{-1} \varphi + \mu \psi^3 \varphi^3 - \frac{2}{3} \mu^2 \psi^3 \varphi^3 \right) \Delta x$$

Remark:

Note that when $\mathbb{T} = \mathbb{R}$, or **in the continuous limit of some special time scales**: the **Linear Poisson Tensor**

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and **Hamiltonians**

$$H_0 = \int_{\mathbb{R}} \psi \varphi dx, \quad H_1 = \int_{\mathbb{R}} \varphi \psi_x dx$$

Δ -differential Kaup-Broer, $k = 1$

Let

$$L = (1 + \mu v - \mu^2 w)\delta + v + \delta^{-1}w.$$

The first flow

$$\frac{dv}{dt_1} = (\mu v - \mu^2 w)\Delta v + \mu\Delta E^{-1}(w(\mu v - \mu^2 w)),$$

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The **linear Poisson tensor** is given by

$$\pi_0 = \begin{pmatrix} \tilde{u}\Delta\mu - \mu\Delta^\dagger\tilde{u} & \tilde{u}\Delta \\ -\Delta^\dagger\tilde{u} & 0 \end{pmatrix}$$

Δ -differential Kaup-Broer

The Quadratic Poisson Tensor

$$\pi_1 = \begin{pmatrix} \pi_{11} & \pi_{12} \\ \pi_{21} & \pi_{22} \end{pmatrix}$$

where

$$\begin{aligned} \pi_{11} &= \tilde{u}\Delta\mu v - \mu v\Delta^\dagger u + \tilde{u}\Delta\tilde{u} \\ &\quad - \tilde{u}\Delta^\dagger\tilde{u} + \tilde{u}\Delta\tilde{u}\Delta\mu - \mu\Delta^\dagger\tilde{u}\Delta^\dagger\tilde{u} + \mu\tilde{u}w\Delta\mu - \mu\Delta^\dagger\mu\tilde{u}w \\ \pi_{12} &= \tilde{u}\Delta v + \tilde{u}\Delta\tilde{u}\Delta + \mu\tilde{u}w\Delta - \mu\Delta^\dagger\tilde{u}w \\ \pi_{21} &= -v\Delta^\dagger\tilde{u} - \Delta^\dagger\tilde{u}\Delta^\dagger\tilde{u} + \tilde{u}w\Delta\mu - \Delta^\dagger\mu\tilde{u}w \\ \pi_{22} &= \tilde{u}w\Delta - \Delta^\dagger\tilde{u}w \end{aligned}$$

Δ -differential Kaup-Broer

The **Hamiltonians** are

$$H_0 = \int_{\mathbb{T}} w \Delta x$$

$$H_1 = \int_{\mathbb{T}} \left(vw - \frac{1}{2} \mu w^2 \right) \Delta x$$

$$H_2 = \int_{\mathbb{T}} \left(w^2 + v^2 w + \frac{2}{3} w \Delta v + \frac{2}{3} \mu v w \Delta v - \frac{2}{3} \mu^2 w^2 \Delta v - \frac{2}{3} \mu^2 w^3 \right) \Delta x$$

\vdots

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THANK YOU FOR YOUR ATTENTION!

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The recursion operators of the finite field N^{th} order Lax hierarchies can be constructed solving

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$$L_{t_{n+N}} = L_{t_n} L + [R, L] \quad (7)$$

For $k = 0$, with the remainder in the form

$$R = a_{N-1} \delta^{N-1} + \cdots + a_0 + \sum_s a_{-1,s} \delta^{-1} \varphi_s, \quad (8)$$

Recursion Operators

The recursion operators of the finite field N^{th} order Lax hierarchies can be constructed solving

$$L_{t_{n+N}} = L_{t_n} L + [R, L] \quad (10)$$

For $k = 0$, with the remainder in the form

$$R = a_{N-1} \delta^{N-1} + \cdots + a_0 + \sum_s a_{-1,s} \delta^{-1} \varphi_s, \quad (11)$$

For $k = 1$,

$$R = a_N \delta^N + \cdots + a_0 + \sum_s a_{-1,s} \delta^{-1} \varphi_s. \quad (12)$$

The appropriate reminder is found for AKNS

$$R = \Delta^{-1} (\mu^{-1} u_{t_n}) - \psi_{t_n} \delta^{-1} \varphi. \quad (13)$$

The appropriate reminder is found for AKNS

$$R = \Delta^{-1} (\mu^{-1} u_{t_n}) - \psi_{t_n} \delta^{-1} \varphi. \quad (15)$$

Thus the recursion formula

$$\begin{pmatrix} u - \mu^{-1} & \phi E & \psi E^{-1} \\ \psi + \psi \Delta^{-1} \mu^{-1} & \Delta + u + \psi \Delta^{-1} \varphi & \psi \Delta^{-1} \psi \\ -\varphi \Delta^{-1} \mu^{-1} & -\varphi E \Delta^{-1} \varphi & u - \Delta E^{-1} - \varphi E \Delta^{-1} \psi \end{pmatrix} \quad (16)$$

when $\mu \neq 0$.

Otherwise, with the constraint

$$\begin{pmatrix} \Delta + u + \mu\psi\varphi + 2\psi\Delta^{-1}\varphi & \mu\psi^2 + 2\psi\Delta^{-1}\psi \\ -\mu\varphi^2 - 2\varphi\Delta^{-1}\varphi & \Delta^\dagger - 2\varphi\Delta^{-1}\psi. \end{pmatrix} \quad (17)$$

Otherwise, with the constraint

$$\begin{pmatrix} \Delta + u + \mu\psi\varphi + 2\psi\Delta^{-1}\varphi & \mu\psi^2 + 2\psi\Delta^{-1}\psi \\ -\mu\varphi^2 - 2\varphi\Delta^{-1}\varphi & \Delta^\dagger - 2\varphi\Delta^{-1}\psi. \end{pmatrix} \quad (19)$$

When $\mathbb{T} = \mathbb{R}$, the recursion formula reduces to

$$\begin{pmatrix} D + 2\psi D^{-1}\varphi & 2\psi D^{-1}\psi \\ -2\varphi D^{-1}\varphi & -D_x - 2\varphi D_x^{-1}\psi \end{pmatrix}. \quad (20)$$