

# Bianchi I model in terms of loop geometry: Classical dynamics

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Based on:

- [1] P. Dz., P. Małkiewicz and W. Piechocki,  
‘Turning Big Bang into Big Bounce: I. Classical dynamics’,  
Phys. Rev. D80, 104001 (2009) [arXiv:gr-qc/0907.3436].
- [2] P. Dz., W. Piechocki,  
‘The Bianchi I model in terms of nonstandard loop quantum  
cosmology: Classical dynamics’,  
Phys. Rev. D80, 124033 (2009) [arXiv:gr-qc/0909.4211].

# OUTLINE

## 1 Introduction

## 2 Classical level

- Bianchi I model
- Modified Hamiltonian
- Equations of motion
- Algebra of observables
- Functions on the physical space

## 3 Conclusions

# Introduction

Two LQC methods:

- **standard** LQC: 'first quantize, then impose constraints'
- **non-standard** LQC: 'first solve constraints, then quantize'

Bianchi I with massless scalar field:

- standard LQC: classical Big Bang is replaced by quantum Big Bounce due to strong quantum effects at the Planck scales
- non-standard LQC: **modification** of GR by loop geometry is responsible for the resolution of the singularity

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# Bianchi I model

Bianchi I model describes **homogeneous** and **anisotropic** universe.  
The metric reads:

$$ds^2 = -N^2 dt^2 + \sum_{i=1}^3 a_i^2(t) dx_i^2,$$
$$\sum_{i=1}^3 k_i = 1, \quad \sum_{i=1}^3 k_i^2 + k_\phi^2 = 1 \quad (1)$$

where  $a_i(t) = a_i(0) \left( \frac{\tau}{\tau_0} \right)^{k_i}$ ,  $d\tau = N dt$ ,  $k_\phi$  describes matter density.  
For  $k_\phi = 0$  (vacuum) we have **Kasner model**.

# Modified Hamiltonian

We consider Bianchi I cosmology with massless scalar field in space with  $\mathbb{R}^3$ -topology.

- Hamiltonian reads:

$$H_g := \int_{\Sigma} d^3x (N^i C_i + N^a C_a + NC), \quad (2)$$

where:  $\Sigma$  is the space-like part of spacetime  $\mathbb{R} \times \Sigma$ ;  $(N^i, N^a, N)$  Lagrange multipliers;  $(C_i, C_a, C)$  are Gauss, diffeomorphism and scalar constraints;  $(a, b = 1, 2, 3)$ , spatial indices;  $(i, j, k = 1, 2, 3)$  internal  $SU(2)$  indices. The constraints must satisfy specific algebra.



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# Modified Hamiltonian

Having fixed local gauge and diffeomorphism freedom we can rewrite the gravitational part of the classical Hamiltonian in the form:

$$H_g = -\gamma^{-2} \int_{\mathcal{V}} d^3x \, N e^{-1} \varepsilon_{ijk} E^{aj} E^{bk} F_{ab}^i, \quad (3)$$

where:  $\gamma$  is the Barbero-Immirzi parameter;  $\mathcal{V} \subset \Sigma$  elementary cell;  $N$  lapse function;  $\varepsilon_{ijk}$  alternating tensor;  $E_i^a$  density weighted triad;  $F_{ab}^k = \partial_a A_b^k - \partial_b A_a^k + \epsilon_{ij}^k A_a^i A_b^j$  curvature of  $SU(2)$  connection  $A_a^i$ ;  $e := \sqrt{|\det E|}$ ;

# Modified Hamiltonian

Rewriting the curvature in terms of holonomies:

$$F_{ab}^k = -2 \lim_{Ar \square_{ij} \rightarrow 0} Tr \left( \frac{h_{\square_{ij}}^{(\mu)} - 1}{Ar \square_{ij}} \right) \tau^k {}^o\omega_a^i {}^o\omega_a^j, \quad (4)$$

where:

$$h_{\square_{ij}} = h_i^{(\mu_i)} h_j^{(\mu_j)} (h_i^{(\mu_i)})^{-1} (h_j^{(\mu_j)})^{-1} \quad (5)$$

is the holonomy of the gravitational connection around the square loop  $\square_{ij}$ , considered over a face of the elementary cell, each of whose sides has length  $\mu_j L_j$  (and  $V_o := L_1 L_2 L_3$ ) with respect to the flat fiducial metric  ${}^oq_{ab} := \delta_{ij} {}^o\omega_a^i {}^o\omega_a^j$ .

In the fundamental,  $j = 1/2$ , representation of  $SU(2)$ , reads

$$h_i^{(\mu_i)} = \cos(\mu_i c_i / 2) \mathbb{I} + 2 \sin(\mu_i c_i / 2) \tau_i \quad (6)$$

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# Modified Hamiltonian

Making use of (3), (4) and the so-called Thiemann identity leads to  $H_g$  in the form:

$$H_g = \lim_{\mu_1, \mu_2, \mu_3 \rightarrow 0} H_g^{(\mu_1 \mu_2 \mu_3)}, \quad (7)$$

where:

$$\begin{aligned} H_g^{(\mu_1 \mu_2 \mu_3)} &= -\frac{\text{sgn}(p_1 p_2 p_3)}{2\pi G \gamma^3 \mu_1 \mu_2 \mu_3} \sum_{ijk} N_{\varepsilon}{}^{ijk} \text{Tr} \left( h_i^{(\mu_i)} h_j^{(\mu_j)} \times \right. \\ &\quad \left. \times (h_i^{(\mu_i)})^{-1} (h_j^{(\mu_j)})^{-1} h_k^{(\mu_k)} \{ (h_k^{(\mu_k)})^{-1}, V \} \right) \end{aligned} \quad (8)$$

and is the  $V = a_1 a_2 a_3 V_0$  volume of the elementary cell.

# Modified Hamiltonian

In considered model the hamiltonian reads:

$$H = H_g + H_\phi \approx 0, \quad (9)$$

where  $H_g$  is defined by (7) and  $H_\phi = N p_\phi^2 |p|^{-\frac{3}{2}}/2$ . The relation  $H \approx 0$  defines the **physical** phase space of considered gravitational system with constraints.

Making use of (6) we calculate (8) and get the modified total Hamiltonian. The Hamiltonian modified by loop geometry (in the gauge  $N = \sqrt{|p_1 p_2 p_3|}$ ) reads:

$$H^{(\lambda)} = -\frac{1}{8\pi G \gamma^2 \mu_1 \mu_2} \left[ |p_1 p_2| \sin(c_1 \mu_1) \sin(c_2 \mu_2) + \text{cyclic} \right] + \frac{p_\phi^2}{2} \quad (10)$$

# Modified Hamiltonian

We use so called  $\bar{\mu}$  scheme:

$\mu_i := \sqrt{\frac{1}{|p_i|}} \lambda$  and  $\lambda$  is a **free parameter**.

Now we introduce following canonical variables:

$\beta_i := \frac{c_i}{\sqrt{|p_i|}}$ ,  $v_i := |p_i|^{3/2} \text{sgn}(p_i)$ ,

and the Poisson bracket:

$$\{\cdot, \cdot\} := 12\pi G\gamma \sum_{k=1}^3 \left[ \frac{\partial \cdot}{\partial \beta_k} \frac{\partial \cdot}{\partial v_k} - \frac{\partial \cdot}{\partial v_k} \frac{\partial \cdot}{\partial \beta_k} \right] + \frac{\partial \cdot}{\partial \phi} \frac{\partial \cdot}{\partial p_\phi} - \frac{\partial \cdot}{\partial p_\phi} \frac{\partial \cdot}{\partial \phi}$$

The Hamiltonian in new variables reads:

$$H^{(\lambda)} = \frac{p_\phi^2}{2} - \frac{1}{8\pi G\gamma^2} \left( \frac{\sin(\lambda\beta_1) \sin(\lambda\beta_2)}{\lambda^2} v_1 v_2 + \right. \quad (11)$$
$$\left. + \frac{\sin(\lambda\beta_1) \sin(\lambda\beta_3)}{\lambda^2} v_1 v_3 + \frac{\sin(\lambda\beta_2) \sin(\lambda\beta_3)}{\lambda^2} v_2 v_3 \right)$$

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# Equations of motion

Equations of motion plus the constraint reads:

$$\dot{\beta}_i = -18\pi G \frac{\sin(\lambda\beta_i)}{\lambda} (O_j + O_k) \quad (12)$$

$$\dot{v}_i = 18\pi G v_i \cos(\lambda\beta_i) (O_j + O_k) \quad (13)$$

$$\dot{p}_\phi = 0 \quad (14)$$

$$\dot{\phi} = p_\phi \quad (15)$$

$$H^{(\lambda)} \approx 0, \quad (16)$$

where  $O_j := \frac{v_j \sin(\lambda\beta_j)}{12\pi G \gamma \lambda}$ ,  $O_i$  are **constants of motion**.

Worth of noting:  $\phi$  plays the role of time.

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# Equations of motion

Solution of equation, for example (13):

$$2 v_i(\phi) = \exp\left(\frac{18\pi G}{p_\phi}(O_j + O_k)(\phi - \phi_i^0)\right) + \\ + (12\pi G\gamma\lambda O_i)^2 \cdot \exp\left(-\frac{18\pi G}{p_\phi}(O_j + O_k)(\phi - \phi_i^0)\right) \quad (17)$$

We can write this in a different form:

$$v_i = 12\pi G\gamma\lambda O_i \cosh\left(\frac{18\pi G}{p_\phi}(O_j + O_k)(\phi - \phi_i^0) - \ln|12\pi G\gamma\lambda O_i|\right) \quad (18)$$

Because  $V = (v_1 v_2 v_3)^{1/3}$  it is clear that for nonzero  $\lambda$  there is no singularity for any value of  $\phi$ .

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# Algebra of observables

**Our aim** : Singularity aspects of the model in terms of observables.

A function  $F$  defined on phase space is a Dirac observable if it is the solution to the equation

$$\{F, H^{(\lambda)}\} = 0 \quad (19)$$

We found that:

$$A_i^{\text{dyn}} = \ln \left| \tan \left( \frac{\lambda \beta_i}{2} \right) \right| + \frac{3\sqrt{\pi G} \operatorname{sgn}(p_\phi) (O_j + O_k) \phi}{\sqrt{O_1 O_2 + O_1 O_3 + O_2 O_3}} \quad (20)$$

$$O_i = \frac{v_i \sin(\lambda \beta_i)}{12\pi G \gamma \lambda} \quad (21)$$

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# Algebra of observables

These observables satisfy the [Lie algebra](#):

$$\begin{aligned}\{O_i, O_j\}_{\text{dyn}} &= 0, & \{A_i^{\text{dyn}}, O_i\}_{\text{dyn}} &= 1, \\ \{A_i^{\text{dyn}}, O_j\}_{\text{dyn}} &= 0, & \{A_i^{\text{dyn}}, A_j^{\text{dyn}}\}_{\text{dyn}} &= 0.\end{aligned}\tag{22}$$

where:

$$\{\cdot, \cdot\}_{\text{dyn}} := \sum_{i=1}^3 \left( \frac{\partial \cdot}{\partial A_i^{\text{dyn}}} \frac{\partial \cdot}{\partial O_i} - \frac{\partial \cdot}{\partial O_i} \frac{\partial \cdot}{\partial A_i^{\text{dyn}}} \right)\tag{23}$$

# Functions on the physical space

- Directional energy density:

$$\rho_i(\lambda, \phi) := \frac{p_\phi^2}{2 v_i^2} \quad (24)$$

The bounce in  $i$ -th direction occurs when  $\rho_i$  approaches its maximum value<sup>1</sup>.

We would like to express above function in terms of observables and an evolution parameter  $\phi$ :

$$\rho_i(\lambda, \phi) = \frac{O_1 O_2 + O_1 O_3 + O_2 O_3}{8\pi G \gamma^2 O_i^2 \cosh^2 \left( \frac{3\sqrt{\pi G} \operatorname{sgn}(p_\phi) (O_j + O_k)}{\sqrt{O_1 O_2 + O_1 O_3 + O_2 O_3}} \phi - A_i^{\text{dyn}} \right)} \quad (25)$$

It will be an observable for each **fixed** value of  $\phi$ , since in such case it will be function of observables only.

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# Functions on the physical space

Big bounce happens when  $v_i$  takes its minimal value:

$v_i^{\min} = 12\pi G\gamma\lambda O_i$ . Thus the maximum value of this density:

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where  $k_\phi$  and  $k_i$  taken from the metric.

$\lambda$  is a **free parameter** of this formalism.

Let assume that  $\lambda = l_{Pl}$ . We get:

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