

wyklad_1a

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Notation : $\gamma^{\mu\nu} = \gamma_{\mu\nu} = \text{diag}(+, -, -, -)$ Minkowski metric tensor

Levi-Civita tensor $\epsilon_{\mu\nu\rho\beta} := \begin{cases} -1 & \text{for } 0, 1, 2, 3 \\ +1 & \text{odd permutations of } 0, 1, 2, 3 \\ 0 & \text{otherwise} \end{cases}$

$$\epsilon^{0123} = \gamma^{0\mu} \gamma^{1\nu} \gamma^{2\lambda} \gamma^{3\beta} \epsilon_{\mu\nu\lambda\beta} = 1 (-1) \epsilon_{0123}^3 = +1$$

$$A_\mu B^\mu := \sum_{\mu=0,1,2,3} A_\mu B^\mu \quad \epsilon_{ijk} := \begin{cases} +1 & \text{for } 1, 2, 3 \\ -1 & \text{odd permutations} \\ 0 & \text{otherwise} \end{cases}$$

$$\bar{A} := (A^0, A^1, A^2, A^3) \quad \epsilon^{ijk} := \epsilon_{ijk}$$

$$\partial_\mu := \frac{\partial}{\partial x^\mu} \quad \square := \partial_\mu \partial^\mu = \partial_0^2 - \underbrace{\partial_i^2}_{\nabla^2} = \partial_t^2 - \nabla^2 \quad - \text{d'Alembertian}$$

$$x^\mu = (ct, x^1, x^2, x^3) = (ct, x^1, x^2, x^3) \quad \overbrace{\partial x^i}^{\partial^2}$$

$$f \overset{\leftrightarrow}{\partial}_\mu g := f \partial_\mu g - (\partial_\mu f) g$$

$$\not{A} := A_\mu \gamma^\mu \quad \text{for } \{ \gamma^\mu, \gamma^\nu \} = 2 \gamma^{\mu\nu} \quad - \text{Dirac matrices}$$

Fourier transform:

$$p_{\mu\nu} = p_{\mu}{}^{\alpha} p_{\nu}{}^{\beta} e^{-ikx} \tilde{p}_{\alpha\beta}$$

Fourier transform:

$$f(x) = \int \frac{d^4 k}{(2\pi)^4} e^{-ikx} \tilde{f}(k), \quad k_x := k_\mu x^\mu$$

$$\tilde{f}(k) = \int d^4 x e^{ikx} f(x)$$

$$f(x) = \int \frac{d^3 k}{(2\pi)^3} e^{i\vec{k}\cdot\vec{x}} \tilde{f}(\vec{k}) \quad \vec{k}\cdot\vec{x} = k^i x^i$$

Dirac delta: $\int d^4 x e^{ikx} = (2\pi)^4 \delta^{(4)}(k)$

Natural units: $\hbar = c = 1 \Rightarrow$ the fine structure constant $\alpha = \frac{e^2}{4\pi(\hbar c)} = \frac{1}{137} = \frac{e^2}{4\pi}$

$$c = 299792458 \frac{\text{m}}{\text{s}} \quad \text{one can measure velocity in units of } c$$

velocity $v = \frac{1}{2}c \Rightarrow v = \frac{1}{2}$ ($"c"$ is still there, we simply don't write it, we do know how to convert to SI units)

$$c=1 \Rightarrow [\text{length}] = [\text{time}]$$

$[\text{velocity}] = \text{dimensionless}$

$$E = \hbar v \Rightarrow [\text{energy}] = [\text{time}]^{-1} = [\text{length}]^{-1} = [\text{mass}]$$

$$\hbar := \frac{\hbar}{2\pi} = 6.582 \text{ MeV fm} \cdot 10^{-16} \text{ eV} \cdot \text{s}$$

$$(mc^2)^2 = E^2 - (\vec{p}c)^2$$

typical length scale in particle physics: $1 \text{ fm} = 10^{-15} \text{ m}$ (size of the proton)

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(one Fermi)

$$\hbar c \approx 200 \text{ MeV fm}$$

$$\Rightarrow \text{in natural units } 1 \text{ fm} = \frac{1}{200 \text{ MeV}}$$

useful to convert to ordinary units
e.g. the Compton radius

$$r_c = \frac{1}{mc} \approx \frac{200 \text{ MeV} \cdot \text{fm}}{0.5 \text{ MeV}} = 4 \cdot 10^{-13} \text{ m}$$

The Lorentz transformation

a linear transformation $x^i \rightarrow x'^i = \Lambda^\mu_\nu x^\nu$ such that

$$x^\mu x^\lambda = \gamma_{\mu\nu} x^\nu x^\lambda = t^2 - x^2 - y^2 - z^2 \text{ is invariant i.e. } = x'_\mu x'^\lambda$$

$$x'_\mu x'^\lambda = \gamma_{\mu\nu} x'^\nu x'^\lambda = \underbrace{\gamma_{\mu\nu} \Lambda^\mu_\alpha}_{x'^\nu} \underbrace{\Lambda^\nu_\beta}_{x'^\lambda} x^\beta = \underbrace{\gamma_{\mu\nu} \Lambda^\mu_\alpha}_{x'^\nu} \underbrace{\Lambda^\nu_\beta}_{x'^\lambda} x^\lambda x^\beta = \gamma_{\alpha\beta} x^\alpha x^\beta$$

$$(\det \Lambda)^2 = 1 \Leftrightarrow \Lambda^\dagger \gamma \Lambda = \gamma \Leftrightarrow \Lambda^\mu_\alpha \gamma_{\mu\nu} \Lambda^\nu_\beta = \gamma_{\alpha\beta}$$

Scalar fields

$$m \cdot v^i \propto k^m v^r \quad \partial_i \phi(v) \propto \partial^i \phi(v) = \partial_i \phi$$

comes from

$$x^r \rightarrow x'^r = \Lambda^m{}_r x^r$$

$$\& \quad \phi(x) \rightarrow \phi'(x') = \phi(x)$$

$$\phi'(\Lambda x) = \phi(x)$$

Classical field theory

Classical mechanics

$$q_i(t), p_i(t) \\ i=1, \dots, N$$

$$[q_i(t), p_j(t)] = 0$$



$N \rightarrow \infty$

Classical field theory

$$q_i(t) \xrightarrow[N \rightarrow \infty]{} \phi(t, \bar{x}) \equiv \phi(x) \\ i \leftrightarrow \bar{x}$$

first quantization



Quantum mechanics

$$\text{operators: } \hat{q}_i(t), \hat{p}_i(t) \\ i=1, \dots, N$$

$$[\hat{q}_i(t), \hat{p}_j(t)] \neq 0$$

second quantization



Quantum Field Theory (QFT)

$\hat{\phi}(t, \bar{x})$ — an operator



particles as excitations
of quantum fields, e.g.
Higgs bosons

History of field theory

Classical field theory (electrodynamics) : • 1831 discovery of induction by Faraday
(1879 - first electric passenger train)

• 1861 Maxwell equations

QFT : • 1927-29 Dirac, Heisenberg, Pauli QED (quantum electrodynamics)

• 1937 Fermi, β -decay $n \rightarrow p + \nu$

• 1936 Yukawa, nuclear forces

• 1958 Feynman, Gell Mann

• 1967-68 Glashow, Salam, Weinberg

} the Standard Model of electroweak interactions

Classical mechanics in 1D

$$m\ddot{q}_V = -\frac{\partial V}{\partial q_V}, \quad q_V(t_0), \dot{q}_V(t_0) \Rightarrow \text{unique solution } q_V(t)$$

Lagrange function: $L(q_V, \dot{q}_V) = T - V = \frac{1}{2} m \dot{q}_V^2 - V(q_V)$

Action: $S[q_V(t)] = \int_{t_1}^{t_2} dt L(q_V(t), \dot{q}_V(t))$

t_1
Minimal action principle:

$$\delta S = 0 \text{ with } \delta q_v(t_1) = \delta q_v(t_2) = 0$$

↓
motion

$$q_v(t_1) = q_1, q_v(t_2) = q_2 \text{ (fixed ends)}$$

$$\delta S = \delta \int_{t_1}^{t_2} L(q_v, \dot{q}_v) dt := \int_{t_1}^{t_2} dt \left\{ L(q_v + \delta q_v, \dot{q}_v + (\delta \dot{q}_v)) - L(q_v, \dot{q}_v) \right\} = \int_{t_1}^{t_2} dt \left\{ \frac{\partial L}{\partial q_v} \delta q_v + \frac{\partial L}{\partial \dot{q}_v} \frac{d}{dt} \delta q_v \right\} =$$

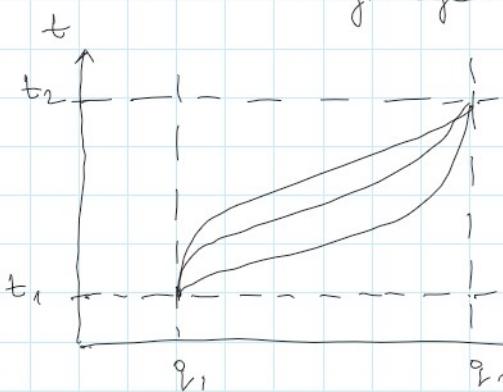
$$\boxed{\delta F[\phi] := F[\phi + \delta \phi] - F[\phi]} = \int_{t_1}^{t_2} dt \left(\frac{\partial L}{\partial q_v} \delta q_v - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_v} \right) \delta \dot{q}_v \right) + \int_{t_1}^{t_2} dt \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_v} \delta q_v \right) =$$

$$= \int_{t_1}^{t_2} dt \left(\frac{\partial L}{\partial q_v} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_v} \right) \right) \delta q_v + \left. \frac{\partial L}{\partial \dot{q}_v} \delta q_v \right|_{t_1}^{t_2} = \int_{t_1}^{t_2} dt \left[\frac{\partial L}{\partial q_v} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_v} \right) \right] \delta q_v = 0$$

for any $\delta q_v(t)$
 $\delta q_v(t_1) = \delta q_v(t_2)$

Euler - Lagrange equation:

$$\frac{\partial L}{\partial q_v} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_v} = 0$$



$$L = \frac{1}{2} m \dot{q}_v^2 - V(q_v)$$

$$\frac{\partial L}{\partial q_v} = m \ddot{q}_v, \quad \frac{\partial L}{\partial \dot{q}_v} = - \frac{\partial V}{\partial q_v}$$

$$\Rightarrow \frac{d}{dt} (m \dot{q}_v) + \frac{\partial V}{\partial q_v} = 0$$

$$m \ddot{q}_v = - \frac{\partial V}{\partial q_v}$$

Hamilton formalism

Hamilton formalism

$$H(q, p) = p \cdot \dot{q}(p) - L(q, \dot{q}(p)) \quad \text{where } p := \frac{\partial L}{\partial \dot{q}}$$

$$(q, \dot{q}) \rightarrow (q, p)$$

Hamilton equations : $\dot{p} = -\frac{\partial H}{\partial q}$
 (first order equations)
 $\dot{q} = \frac{\partial H}{\partial p}$

- let's replace $L(q, \dot{q})$ by a functional $L(\phi, \dot{\phi})$

- Define variation : $\delta F[\phi] := F[\phi + \delta \phi] - F[\phi]$

- Define functional derivative $\frac{\delta F}{\delta \phi}$, such that $\delta F[\phi] = \int d^3x \frac{\delta F}{\delta \phi(x)} \delta \phi(x)$

- Action : $S = \int dt L(\phi, \dot{\phi})$

$$\delta S = \int dt \delta L = \int dt \int d^3x \left[\frac{\delta L}{\delta \phi(x)} \delta \phi(x) + \underbrace{\frac{\delta L}{\delta \dot{\phi}(x)} \delta \dot{\phi}(x)}_{L = \frac{d}{dt} \delta \phi(x)} \right]$$

assume $\delta \phi(t_1, x) = \delta \phi(t_2, x) \Big|_{x \in \partial V} = 0$

then from $\delta S = 0$ for any $\delta \phi(x)$ one gets the Euler-Lagrange eqs.

$$\frac{\delta L}{\delta \phi(x)} - \frac{d}{dt} \frac{\delta L}{\delta \dot{\phi}(x)} = 0$$

$$\frac{\delta L}{\delta \phi(x)} - \frac{d}{dt} \frac{\delta L}{\delta \dot{\phi}(x)} = 0$$

Assumptions:

1. We are going to consider theories for which there exists Lagrangian density $L(\phi, \nabla\phi, \dot{\phi})$, such that

$$L[\phi(t, \bar{x}), \bar{\nabla}\phi(t, \bar{x}), \dot{\phi}(t, \bar{x})] = \int d^3x L(\phi(t, \bar{x}), \bar{\nabla}\phi(t, \bar{x}), \dot{\phi}(t, \bar{x}))$$

2. L depends quadratically on first derivatives only

3. For Lorentz invariance L depends on $\partial_\mu\phi$ only

4. Theory is local, i.e. $L(t, \bar{x})$ depends on fields in the same location.

For instance the following density would be disallowed

$$L(t, \bar{x}) = \int k(t, \bar{x}; \bar{y}) \phi(t, \bar{y}) d^3y$$

5. L is a real function

↙ ↘

$$S = \int_{t_1}^{t_2} dt \int d^3x L(\phi(x), \partial_\mu\phi(x))$$

6. Operators that appear in L should have mass dimension ≤ 4

6. Operators that appear in L should have mean dimension ≤ 4
 in order to ensure renormalisability.

$$\delta L = \int_V d^3x \left(\frac{\partial L}{\partial \phi} \delta \phi + \frac{\partial L}{\partial \bar{\nabla} \phi} \underbrace{\delta(\bar{\nabla} \phi)}_{\bar{\nabla}(\delta \phi)} + \frac{\partial L}{\partial \dot{\phi}} \delta(\dot{\phi}) \right) =$$

$$= \int_V d^3x \left[\frac{\partial L}{\partial \phi} \delta \phi - \bar{\nabla} \left(\frac{\partial L}{\partial \bar{\nabla} \phi} \right) \delta \phi + \frac{\partial L}{\partial \dot{\phi}} \delta(\dot{\phi}) \right] + \underbrace{\int_V d\bar{\sigma} \frac{\partial L}{\partial \bar{\nabla} \phi} \delta \phi}_{= 0} =$$

The Green's theorem : $\int_V d^3x F \cdot \bar{\nabla} g = - \int_V d^3x (\bar{\nabla} \cdot F) g + \int_{\partial V} \bar{F} \cdot g d\bar{\sigma}$

$$= \int_V d^3x \left[\left(\frac{\partial L}{\partial \phi} - \bar{\nabla} \left(\frac{\partial L}{\partial \bar{\nabla} \phi} \right) \right) \delta \phi + \frac{\partial L}{\partial \dot{\phi}} \delta(\dot{\phi}) \right]$$

$$\frac{\delta L}{\delta \phi} \quad \frac{\delta L}{\delta \dot{\phi}}$$

$$\boxed{\frac{\delta L}{\delta \phi(x)} - \frac{d}{dt} \frac{\delta L}{\delta \dot{\phi}} = 0}$$

Then the Euler-Lagrange equations look like

$$\frac{\partial L}{\partial \phi} - \bar{\nabla} \frac{\partial L}{\partial \bar{\nabla} \phi} - \frac{d}{dt} \frac{\partial L}{\partial \dot{\phi}} = 0 \Rightarrow \boxed{\frac{\partial L}{\partial \phi} - \frac{\partial}{\partial x^\mu} \frac{\partial L}{\partial (\partial_\mu \phi)} = 0}$$

For the Hamiltonian formalism we define the conjugate momenta

$$\Pi(t, \vec{x}) = \frac{\delta L}{\delta \dot{\phi}(t, \vec{x})} = \frac{\partial L}{\partial \dot{\phi}(t, \vec{x})}$$

Then $H = \int d^3x \Pi(t, \vec{x}) \dot{\phi}(t, \vec{x}) - L(t)$

Classical mechanics \longleftrightarrow Classical field theory

$$p_i = \frac{\partial L}{\partial \dot{q}_i}$$

$$\Pi(t, \vec{x}) = \frac{\delta L}{\delta \dot{\phi}(t, \vec{x})}$$

$$L(t) = L(q_i(t), \dot{q}_i(t))$$

$$L(t) = L[\phi(t, \vec{x}), \dot{\phi}(t, \vec{x})]$$

$$H(t) = \sum_j p_j \dot{q}_j(p) - L(q_i(t), \dot{q}_i(t))$$

$$H(t) = \int d^3x \Pi(t, \vec{x}) \dot{\phi}(t, \vec{x}) - L(t)$$

We assume that there exists the Hamiltonian density

$$H(t) = \int d^3x \mathcal{H}(t, \vec{x}) = \int d^3x [\Pi(t, \vec{x}) \dot{\phi}(t, \vec{x}) - L(t, \vec{x})]$$

Hamilton equations:

$$\dot{\phi}(t, \vec{x}) = \frac{\delta H}{\delta \Pi(t, \vec{x})} \quad \dot{\Pi}(t, \vec{x}) = - \frac{\delta H}{\delta \dot{\phi}(t, \vec{x})}$$

Derivation

$$\delta H = \int d^3x (\delta \Pi \dot{\phi} + \Pi \delta \dot{\phi}) - \delta L$$

$$\delta H = \int d^3x (\delta \dot{\pi} \phi + \pi \delta \dot{\phi}) - \delta L$$

$$\delta L = \int d^3x \left(\underbrace{\frac{\delta L}{\delta \dot{\phi}} \delta \phi}_{\text{L}} + \underbrace{\frac{\delta L}{\delta \dot{\phi}} \delta \dot{\phi}}_{\text{P}} \right)$$

$$\dot{\pi} = \frac{d}{dt} \frac{\delta L}{\delta \dot{\phi}}$$

$$\text{So } \delta H = \int d^3x \left(\delta \dot{\pi} \phi + \pi \cancel{\delta \dot{\phi}} - \dot{\pi} \delta \phi - \pi \cancel{\delta \dot{\phi}} \right) = \int d^3x \left(\underbrace{\frac{\delta H}{\delta \dot{\phi}} \delta \phi}_{\text{L}} + \underbrace{\frac{\delta H}{\delta \pi} \delta \dot{\pi}}_{\text{P}} \right) - \dot{\pi} \underbrace{\delta \phi}_{\text{P}}$$