# On the use of evolutionary methods in metric theories of gravity IV.

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# Characteristic polynomials and directions

#### • consider now a First Order Symmetric Hyperbolic (FOSH) system HW (2)!

$$\mathcal{A}^{\alpha}(t,x)\,\partial_{\alpha}\mathbf{u} + \mathcal{B}(t,x,\mathbf{u}) = 0 \qquad (*)$$

• when the coefficients A<sup>\(\alpha\)</sup> depend on the unknowns u, all the definitions below can also be given but one has to be careful and one should refer to sections of fiber bundles (in fact a vector bundles) over the ambient manifold "(t, x, u)", this would require more structures to be used

- assume that  $\xi_{\alpha}$  is a covector at a given point  $p \in M$ . the principal symbol of (\*) at  $(p, \xi_{\alpha})$  is the matrix  $\varsigma(p, \xi_{\alpha}) = \mathcal{A}^{\alpha} \xi_{\alpha}$  (could be viewed as a linear map)
- suppose that  $\mathscr{H}$  is a hypersurface in a neighbourhood  $\mathcal{U}$  of  $p \in M$ , i.e. there exist a function  $\chi : \mathcal{U} \to \mathbb{R}$  such that  $\mathscr{H} = \{\chi = const \& \partial_{\alpha}\chi \neq 0\}$
- $\mathscr{H}$  is said to be nowhere characteristic for (\*) if  $det(\varsigma(p, \partial_{\alpha}\chi)) \neq 0$  for any  $p \in \mathscr{H}$ , whereas  $\mathscr{H}$  is called to be a characteristic hypersurface, or simply a characteristic for (\*), if  $det(\varsigma(p, \partial_{\alpha}\chi)) = 0$  for any  $p \in \mathscr{H}$ 
  - if  $\mathscr{H}$  is nowhere characteristic for (\*) then if initial data  ${}^{0}\mathbf{u}$  is given on  $\mathscr{H}$  a formal expansion of a "to be solution"  $\mathbf{u}$  can be given taking formal  $\partial_{0}^{k}$ -derivatives (\*) and solving the yielded equations for  $\partial_{0}^{k}\mathbf{u}$  on  $\mathscr{H}$
  - if ℋ is characteristic, the initial data cannot be prescribed freely on ℋ det(ς(p, ∂<sub>α</sub>χ)) = 0 induces relations among the initial data on ℋ : inner equations on ℋ; ξ<sub>α</sub> = ∂<sub>α</sub>χ is then a characteristic direction

# Assumptions on the topology of the ambient manifold

## Foliations

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- Assume: M is foliated by a one-parameter family of homologous hypersurfaces, i.e.  $M \simeq \mathbb{R} \times \Sigma$ , for some *n*-dimensional manifold  $\Sigma$ .
  - known to hold for globally hyperbolic spacetimes (Lorentzian case)
  - equivalent to the existence of a smooth function  $\sigma: M \to \mathbb{R}$  with non-vanishing gradient  $\nabla_a \sigma$  such that the  $\sigma = const$  level surfaces  $\Sigma_{\sigma} = \{\sigma\} \times \Sigma$  comprise the one-parameter foliation of M.  $n_{-} \sim \nabla_{-} \sigma \qquad \& \qquad a^{ab} \longrightarrow n^{a} = a^{ab} n_{+}$

## $\sigma^a$ is "time evolution vector field" if:

• the integral curves of  $\sigma^a$  meet the  $\sigma = const$  level surfaces precisely once

• 
$$\sigma^e \nabla_e \sigma = 1$$



• where N and  $N^a$  denotes the lapse and shift of  $\sigma^a$ :

$$N = \epsilon \left( \sigma^e n_e \right)$$
 and  $N^a = h^a{}_e \sigma^e$ 

## The main creatures:

•  $n^a$  the 'unit norm' vector field that is normal to the  $\Sigma_\sigma$  level surfaces

$$n^a n_a = \epsilon$$

- $\epsilon$  takes the value -1 or +1 for Lorentzian or Riemannian metric  $g_{ab},$  resp.
- the projection operator

$$h_a{}^b = \delta_a{}^b - \epsilon n_a n^b$$

• the metric induced

$$h_{ab} = h_a{}^e h_b{}^f g_{ef} = g_{ab} - \epsilon n_a n_b$$

• the covariant derivative operator  $|D_a|$  associated with  $h_{ab}$ :  $orall \omega_b$  on  $\Sigma$ 

$$D_a\omega_b := h_a{}^d h_b{}^e \nabla_d \,\omega_e$$

• the extrinsic curvature on  $\Sigma$  (symmetric!)

$$K_{ab} = h^e{}_a \nabla_e n_b = \frac{1}{2} \mathscr{L}_n h_{ab}$$

acceleration

$$\dot{n}_a = h^f{}_a n^e \nabla_e n_f = n^e \nabla_e n_a$$

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# Summary of the principal relations:

Gauss relation:
$${}^{(n)}R_{abc}{}^e = h_a{}^f h_b{}^g h_c{}^k h_j{}^e R_{fgk}{}^j + \epsilon \left[ K_{ac}K_b{}^e - K_{bc}K_a{}^e \right]$$
Codazzi relation: $h_e{}^a h_f{}^b h_d{}^g n^c R_{abc}{}^d = -2D_{[e} K_{f]}{}^g$ The  $3^{rd}$  relation: $h_b{}^e h_f{}^d n^a n^c R_{aec}{}^f = -\mathscr{L}_n K_b{}^d - K_b{}^e K_e{}^d - \epsilon N^{-1} D_b D^d N$ 

Various projections of the Ricci tensor:

$$n^{e}n^{f}R_{ef} = \frac{1}{2}\epsilon \left[ (R - {}^{(n)}R) + \epsilon \{ (K_{e}^{\ e})^{2} - K_{ef}K^{ef} \} \right]$$

$$h_{a}^{\ e}n^{f}R_{ef} = D_{e}K_{ae}^{\ e} - D_{a}K_{e}^{\ e}$$

$$eh_{d}^{\ f}R_{ef} = {}^{(n)}R_{bd} + \epsilon \{ -\mathscr{L}_{n}K_{bd} - K_{bd}K_{e}^{\ e} + 2K_{b}^{\ e}K_{de} - \epsilon N^{-1}D_{b}D_{d}N \}$$

#### relation of the scalar curvatures:

$$R = {}^{(n)}R + \epsilon \left\{ -2 \mathscr{L}_n(K_{bd}h^{bd}) - (K_e^{\ e})^2 - K_{ef}K^{ef} - 2 \epsilon N^{-1}D^e D_e N \right\}$$

no field equation had been used yet !!!

 $h_{h}$ 

## More exercises:

#### Any symmetric tensor field $P_{ab}$ can be decomposed

in terms of  $n^a$  and fields living on the  $\sigma = const$  level surfaces as

$$P_{ab} = \boldsymbol{\pi} n_a n_b + [n_a \mathbf{p}_b + n_b \mathbf{p}_a] + \mathbf{P}_{ab}$$

ere  $\pi = n^e n^f P_{ef}, \quad \mathbf{p}_a = \epsilon h^e{}_a n^f P_{ef}, \quad \mathbf{P}_{ab} = h^e{}_a h^f{}_b P_{ef}$ 

## The projections of $\nabla^a P_{ab}$

$$h_a{}^b = \delta_a{}^b - \epsilon n_a n^b$$

$$\begin{aligned} \nabla_e P_{ab} &= \nabla_e [\,\boldsymbol{\pi} \, n_a n_b + [n_a \, \mathbf{p}_b + n_b \, \mathbf{p}_a] + \mathbf{P}_{ab} \,] \\ &= (\nabla_e \boldsymbol{\pi}) \, n_a n_b + \boldsymbol{\pi} \, (\nabla_e \, n_a) n_b + \boldsymbol{\pi} \, n_a (\nabla_e \, n_b) \\ &+ (\nabla_e \, n_a) \, \mathbf{p}_b + n_a (\nabla_e \, \mathbf{p}_b) + (\nabla_e \, \mathbf{p}_a) \, n_b + (\nabla_e \, n_b) \, \mathbf{p}_a + \nabla_e \, \mathbf{P}_{ab} \end{aligned}$$

$$h_{f}{}^{b}(\nabla^{a}P_{ab}) = h_{f}{}^{b} \left[ h^{ea} + \epsilon n^{e}n^{a} \right] \nabla_{e}P_{ab} = \pi \dot{n}_{f} + (K_{a}{}^{a}) \mathbf{p}_{f}$$
$$+ h_{f}{}^{b} \left[ n^{a}\nabla_{a} \mathbf{p}_{b} + \mathbf{p}_{a}(h^{ea}\nabla_{e} n_{b}) \right] + D^{a}\mathbf{P}_{af} - \epsilon \left( n^{e}\nabla_{e} n^{a} \right) \mathbf{P}_{af}$$
$$= \pi \dot{n}_{f} + (K_{a}{}^{a}) \mathbf{p}_{f} + h_{f}{}^{b} \mathscr{L}_{n} \mathbf{p}_{b} + D^{a}\mathbf{P}_{af} - \epsilon \dot{n}^{a}\mathbf{P}_{af}$$

$$h_f{}^b(\nabla^a P_{ab}) = \mathscr{L}_n \, \mathbf{p}_f + D^a \mathbf{P}_{af} + [\, \boldsymbol{\pi} \, \dot{n}_f + (K_a{}^a) \, \mathbf{p}_f - \boldsymbol{\epsilon} \, \dot{n}^a \mathbf{P}_{af}]$$

# More exercises:

$$\begin{split} & \text{The projection } n^b (\nabla^a P_{ab}) & h_a{}^b = \delta_a{}^b - \epsilon n_a n^b \\ \nabla_e P_{ab} &= (\nabla_e \pi) n_a n_b + \pi (\nabla_e n_a) n_b + \pi n_a (\nabla_e n_b) \\ &+ (\nabla_e n_a) \mathbf{p}_b + n_a (\nabla_e \mathbf{p}_b) + (\nabla_e \mathbf{p}_a) n_b + (\nabla_e n_b) \mathbf{p}_a + \nabla_e \mathbf{P}_{ab} \\ \hline n^b (\nabla^a P_{ab}) &= n^b \left[ h^{ea} + \epsilon n^e n^a \right] \nabla_e P_{ab} = \epsilon \mathscr{L}_n \pi + \epsilon \pi (K_e^e) + (n^a \nabla_a \mathbf{p}_b) n^b \\ &+ \epsilon \left[ h^{ea} + \epsilon n^e n^a \right] \nabla_e \mathbf{p}_a - \mathbf{P}_{ab} \left[ h^{ea} + \epsilon n^e n^a \right] (\nabla_e n^b) \\ &= \epsilon \mathscr{L}_n \pi + \epsilon \pi (K_e^e) - \dot{n}^a \mathbf{p}_a + \epsilon \left[ D^a \mathbf{p}_a - \epsilon \dot{n}^a \mathbf{p}_a \right] \\ &- \mathbf{P}_{ab} h^{ea} \left[ K_e^b + \epsilon n_e \dot{n}^b \right] \\ &= \epsilon \left[ \mathscr{L}_n \pi + \pi (K_e^e) + D^a \mathbf{p}_a \right] - 2 \mathbf{p}_a \dot{n}^a - \mathbf{P}_{ab} K^{ab} \\ \hline \epsilon n^b (\nabla^a P_{ab}) &= \mathscr{L}_n \pi + D^e \mathbf{p}_e + \left[ \pi (K_e^e) - \epsilon \mathbf{P}_{ef} K^{ef} - 2 \epsilon \mathbf{p}_e \dot{n}^e \right] \\ \hline \text{Simple projections } n^a (\nabla_a P_b^b) & h_e{}^a (\nabla_a P_b^b) \\ n^a (\nabla_a P_b^b) &= \epsilon \mathscr{L}_n \pi + \mathcal{L}_n \mathbf{P}_b^b \\ h_e{}^a (\nabla_a P_b^b) &= \epsilon D_e \pi + D_e \mathbf{P}_b^b \end{split}$$

# Projections of divergences:

## The projections of $\nabla^a P_{ab}$

 $abla^a$ 

$$h_a{}^b = \delta_a{}^b - \epsilon n_a n^b$$

$$\epsilon \, n^b (\nabla^a P_{ab}) = \mathscr{L}_n \pi + D^e \mathbf{p}_e + [\, \pi(K_e{}^e) - \epsilon \, \mathbf{P}_{ef} K^{ef} - 2 \, \epsilon \, \mathbf{p}_e \dot{n}^e \,]$$

$$h_f{}^b(\nabla^a P_{ab}) = \mathscr{L}_n \, \mathbf{p}_f + D^a \mathbf{P}_{af} + [\, \boldsymbol{\pi} \, \dot{n}_f + (K_a{}^a) \, \mathbf{p}_f - \epsilon \, \dot{n}^a \mathbf{P}_{af}]$$

$$P_{ab}=0$$
 , and that

$$\dot{n}_a = 0$$
,  $K_e^e = 0$ ,  $\mathbf{P}_{ef} K^{ef} = 0$ 

• then the above relations reduce to

$$\mathscr{L}_n \boldsymbol{\pi} + D^e \mathbf{p}_e = 0$$
  
 $\mathscr{L}_n \mathbf{p}_b + D^a \mathbf{P}_{ab} = 0$ 

• though  $P_{ab}$  is arbitrary the above relations look very much like the balance relation in fluid dynamics  $\partial_t \rho + \partial_{\bar{\alpha}}(\rho v^{\bar{\alpha}}) = 0$ 

and the Euler equation 
$$\rho \left[ \partial_t \mathrm{v}^{\bar{lpha}} + \mathrm{v}^{\bar{arepsilon}} \partial_{\bar{arepsilon}} \mathrm{v}^{\bar{lpha}} 
ight] = -h^{\bar{lpha}ar{arepsilon}} \partial_{ar{arepsilon}} P$$

# The program for the present lecture:

## The main message:

some of the arguments and techniques developed originally and applied so far exclusively only in the Lorentzian case do also apply to Riemannian spaces

## Plans and Aims:

## The propagation of the constraints

- Einsteinian spaces:  $(M, g_{ab})$
- Bianchi identity
- no gauge condition

 $\ldots$  arbitrary choice of foliations & "evolutionary" vector field

## Reference:

• I. Rácz: Is the Bianchi identity always hyperbolic?, CQG 31 155004 (2014)

# The considered Einsteinian spaces:

• The ambient spaces:  $(M, g_{ab})$ 

- M : n+1-dimensional, smooth, paracompact, connected, orientable manifold
- g<sub>ab</sub>: smooth Lorentzian<sub>(-,+,...,+)</sub> or Riemannian<sub>(+,+,...,+)</sub> metric

#### • Einstein's equations:

$$G_{ab} - \mathscr{G}_{ab} = 0$$
 with source term:  $\nabla^a \mathscr{G}_{ab} = 0$ 

• in a more familiar setup: Einstein's equations with cosmological constant  $\Lambda$ 

$$[R_{ab} - \frac{1}{2} g_{ab} R] + \Lambda g_{ab} = 8\pi T_{ab}$$

with matter fields satisfying their Euler-Lagrange equations

$$\mathscr{G}_{ab} = 8\pi \, T_{ab} - \Lambda \, g_{ab}$$

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# Decompositions of various fields:

• the metric

$$g_{ab} = \epsilon \, n_a n_b + h_{ab}$$

• the "source term"

$$\mathscr{G}_{ab} = n_a n_b \, \mathfrak{e} + [n_a \, \mathfrak{p}_b + n_b \, \mathfrak{p}_a] + \mathfrak{S}_{ab}$$

where the energy, momentum and stress densities are defined as

$$\mathfrak{e} = n^e n^f \mathscr{G}_{ef}, \ \mathfrak{p}_a = \epsilon \, h^e{}_a n^f \mathscr{G}_{ef}, \ \mathfrak{S}_{ab} = h^e{}_a h^f{}_b \mathscr{G}_{ef}$$

• projections of the divergence  $\nabla^a \mathscr{G}_{ab}$ 

$$\begin{split} \epsilon \, n^b (\nabla^a \mathscr{G}_{ab}) &= \mathscr{L}_n \mathfrak{e} + D^e \mathfrak{p}_e + [\mathfrak{e}(K_e{}^e) - \epsilon \, \mathfrak{S}_{ef} K^{ef} - 2 \, \epsilon \, \mathfrak{p}_e \dot{n}^e \,] \\ h_f{}^b (\nabla^a \mathscr{G}_{ab}) &= \mathscr{L}_n \, \mathfrak{p}_f + D^a \mathfrak{S}_{af} + [\mathfrak{e} \, \dot{n}_f + (K_a{}^a) \, \mathfrak{p}_f - \epsilon \, \dot{n}^a \mathscr{G}_{af}] \end{split}$$

• as 
$$\nabla^a \mathscr{G}_{ab} = 0$$
, assuming that  $\dot{n}_a = 0$ ,  $K_e^e = 0$ ,  $\mathfrak{S}_{ef} K^{ef} = 0$   
 $\mathscr{L}_n \mathfrak{e} + D^e \mathfrak{p}_e = 0$   
 $\mathscr{L}_n \mathfrak{p}_f + D^a \mathfrak{S}_{af} = 0$ 

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# Decompositions of various fields:

• Einstein's equations:

 $G_{ab} - \mathscr{G}_{ab} = 0$  with source term:  $\nabla^a \mathscr{G}_{ab} = 0$ 

• r.h.s. of Einstein's equation:  $E_{ab} = G_{ab} - \mathscr{G}_{ab}$ 

$$E_{ab} = n_a n_b E^{(\mathcal{H})} + [n_a E_b^{(\mathcal{M})} + n_b E_a^{(\mathcal{M})}] + (E_{ab}^{(\mathcal{EVOL})} + h_{ab} E^{(\mathcal{H})})$$

$$E^{(\mathcal{H})} = n^{e} n^{f} E_{ef}, \quad E_{a}^{(\mathcal{M})} = \epsilon h^{e}{}_{a} n^{f} E_{ef}, \quad E_{ab}^{(\mathcal{EVOL})} = h^{e}{}_{a} h^{f}{}_{b} E_{ef} - h_{ab} E^{(\mathcal{H})}$$

The decomposition of the covariant divergence  $\nabla^a E_{ab} = 0$  of  $E_{ab} = G_{ab} - \mathscr{G}_{ab}$ :

$$\begin{aligned} \mathscr{L}_{n} E^{(\mathcal{H})} + D^{e} E^{(\mathcal{M})}_{e} + \left[ E^{(\mathcal{H})} \left( K^{e}_{e} \right) - 2 \epsilon \left( \dot{n}^{e} E^{(\mathcal{M})}_{e} \right) \right. \\ \left. - \epsilon K^{ae} \left( E^{(\mathcal{EVOL})}_{ae} + h_{ae} E^{(\mathcal{H})} \right) \right] &= 0 \end{aligned}$$
$$\begin{aligned} \mathscr{L}_{n} E^{(\mathcal{M})}_{b} + D^{a} \left( E^{(\mathcal{EVOL})}_{ab} + h_{ab} E^{(\mathcal{H})} \right) + \left[ E^{(\mathcal{H})} \dot{n}_{b} + \left( K^{e}_{e} \right) E^{(\mathcal{M})}_{b} \right. \\ \left. - \epsilon \left( E^{(\mathcal{EVOL})}_{ab} + h_{ab} E^{(\mathcal{H})} \right) \dot{n}^{a} \right] &= 0 \end{aligned}$$

The decomposition of the covariant divergence  $\nabla^a E_{ab} = 0$  of  $E_{ab} = G_{ab} - \mathscr{G}_{ab}$ :

$$\mathscr{L}_{n} E^{(\mathcal{H})} + D^{e} E_{e}^{(\mathcal{M})} + \left[ E^{(\mathcal{H})} \left( K^{e}_{e} \right) - 2 \epsilon \left( \dot{n}^{e} E_{e}^{(\mathcal{M})} \right) - \epsilon K^{ae} \left( E_{ae}^{(\mathcal{EVOL})} + h_{ae} E^{(\mathcal{H})} \right) \right] = 0$$
  
$$\mathscr{L}_{n} E_{b}^{(\mathcal{M})} + D^{a} \left( E_{ab}^{(\mathcal{EVOL})} + h_{ab} E^{(\mathcal{H})} \right) + \left[ E^{(\mathcal{H})} \dot{n}_{b} + \left( K^{e}_{e} \right) E_{b}^{(\mathcal{M})} - \epsilon \left( E_{ab}^{(\mathcal{EVOL})} + h_{ab} E^{(\mathcal{H})} \right) \dot{n}^{a} \right] = 0$$

1st order symmetric hyperbolic system: linear and homogeneous in  $(E^{(\mathcal{H})}, E^{(\mathcal{M})}_i)^T$ :

•  $N \times "(1)"$  and  $Nh^{ij} \times "(2)"$  in local coordinates  $(\sigma, x^1, x^2, \dots, x^n)$  adopted to the vector field  $\sigma^a = N n^a + N^a$ :  $\sigma^e \nabla_e \sigma = 1$  and the foliation  $\{\Sigma_\sigma\}$ , read as

$$\left\{ \left( \begin{array}{cc} 1 & 0 \\ 0 & h^{ij} \end{array} \right) \partial_{\sigma} + \left( \begin{array}{cc} -N^k & N \, h^{ik} \\ N \, h^{jk} & -N^k \, h^{ij} \end{array} \right) \partial_k \right\} \begin{pmatrix} E^{(\mathcal{H})} \\ E^{(\mathcal{M})}_i \end{pmatrix} = \begin{pmatrix} \mathscr{E} \\ \mathscr{E}^j \end{pmatrix} \right|$$

where the source terms  $\mathscr E$  and  $\mathscr E^j$  are linear and homogeneous in  $E_i^{(\mathcal H)}$  and  $E_i^{(\mathcal M)}$ 

$$\mathcal{A}^{\mu} \, \partial_{\mu} \mathbf{u} + \mathcal{B} \, \mathbf{u} = 0 \quad \text{ with } \quad \mathbf{u} = (\boldsymbol{E}^{(\mathcal{H})}, \boldsymbol{E}^{(\mathcal{M})}_{i})^{T}$$

HW (+): determine the characteristic directions for this equation.

## Theorem

Let  $(M, g_{ab})$  be an Einsteinian space as specified and assume that the metric  $h_{ab}$  induced on the  $\sigma = const$  level surfaces is Riemannian. Then, regardless whether  $g_{ab}$  is of Lorentzian or Euclidean signature, any solution to the reduced equations  $E_{ab}^{(\mathcal{EVOL})} = 0$  is also a solution to the full set of field equations  $G_{ab} - \mathcal{G}_{ab} = 0$  provided that the constraint expressions  $E^{(\mathcal{H})}$  and  $E_{a}^{(\mathcal{M})}$  vanish on one of the  $\sigma = const$  level surfaces.

• no gauge condition was used anywhere in the above analyze !

• it applies regardless of the choice of the foliation,  $\Sigma_{\sigma}$ , of M and for any choice of the evolution vector field,  $\sigma^a (N, N^a)$ .

The decomposition of the covariant divergence  $\nabla^a E_{ab} = 0$  of  $E_{ab} = G_{ab} - \mathscr{G}_{ab}$ :

$$\begin{aligned} \mathscr{L}_{n} E^{(\mathcal{H})} + D^{e} E^{(\mathcal{M})}_{e} + \left[ E^{(\mathcal{H})} \left( K^{e}_{e} \right) - 2 \epsilon \left( \dot{n}^{e} E^{(\mathcal{M})}_{e} \right) \right. \\ \left. - \epsilon K^{ae} \left( E^{(\mathcal{EVOL})}_{ae} + h_{ae} E^{(\mathcal{H})} \right) \right] &= 0 \end{aligned}$$
$$\begin{aligned} \mathscr{L}_{n} E^{(\mathcal{M})}_{b} + D^{a} \left( E^{(\mathcal{EVOL})}_{ab} + h_{ab} E^{(\mathcal{H})} \right) + \left[ E^{(\mathcal{H})} \dot{n}_{b} + \left( K^{e}_{e} \right) E^{(\mathcal{M})}_{b} \right. \\ \left. - \epsilon \left( E^{(\mathcal{EVOL})}_{ab} + h_{ab} E^{(\mathcal{H})} \right) \dot{n}^{a} \right] &= 0 \end{aligned}$$

## What is if the constraints hold on each $\sigma = const$ hypersurface?

• 
$$E^{(\mathcal{H})} = 0$$
 and  $E^{(\mathcal{M})}_a = 0$ 

$$\begin{split} K^{ae} \, E^{(\mathcal{EVOL})}_{ae} &= 0\\ D^a E^{(\mathcal{EVOL})}_{ab} &- \epsilon \, E^{(\mathcal{EVOL})}_{ab} \, \dot{n}^a = 0 \end{split}$$

- homework HW (3):
  - show that the constraints holds for any foliations of the ambient manifold then the evolution equations follow

# The explicit forms I.:

using the projections of the Ricci tensor:

$$n^{e}n^{f}R_{ef} = \frac{1}{2} \epsilon \left[ (R - {}^{(n)}R) + \epsilon \{ (K_{e}^{e})^{2} - K_{ef}K^{ef} \} \right]$$

$$h_a{}^e n^f R_{ef} = D_e K_{ae}{}^e - D_a K_e{}^e$$

$$h_{b}^{e}h_{d}^{f}R_{ef} = {}^{(n)}\!R_{bd} + \epsilon \left\{ -\mathscr{L}_{n}K_{bd} - K_{bd}K_{e}^{e} + 2K_{b}^{e}K_{de} - \epsilon N^{-1}D_{b}D_{d}N \right\}$$

along with the relation of the scalar curvatures:

$$R = {}^{(n)}R + \epsilon \left\{ -2 \mathscr{L}_n(K_e^e) - (K_e^e)^2 - K_{ef}K^{ef} - 2 \epsilon N^{-1}D^e D_e N \right\}$$

and that c

hat of 
$$E_{ab}=G_{ab}-\mathscr{G}_{ab}$$
 , the following explicit forms can be verified:

# The explicit forms II.:

$$\begin{split} E^{(\mathcal{H})} &= n^e n^f E_{ef} = \frac{1}{2} \left\{ -\epsilon^{(n)} R + (K^e{}_e)^2 - K_{ef} K^{ef} - 2\mathfrak{e} \right\}, \\ E^{(\mathcal{M})}_a &= \epsilon h^e{}_a n^f E_{ef} = \epsilon \left[ D_e K^e{}_a - D_a K^e{}_e - \epsilon \mathfrak{p}_a \right] \\ E^{(\mathcal{EVOL})}_{ab} &= {}^{(n)} R_{ab} + \epsilon \left\{ -\mathscr{L}_n K_{ab} - (K^e{}_e) K_{ab} + 2 K_{ae} K^e{}_b - \epsilon N^{-1} D_a D_b N \right\} \\ &- \left[ \mathfrak{S}_{ab} - \mathfrak{e} h_{ab} \right] - \frac{1}{2} h_{ab} \left\{ \left( 1 - \epsilon \right)^{(n)} R - 2 \epsilon \mathscr{L}_n (K^e{}_e) \right. \\ &+ \left( 1 - \epsilon \right) \left( K^e{}_e \right)^2 - \left( 1 + \epsilon \right) K_{ef} K^{ef} - 2 N^{-1} D^e D_e N \right\} \end{split}$$

where

$$\mathfrak{e} = n^e n^f \mathscr{G}_{ef}, \quad \mathfrak{p}_a = \epsilon \, h^e{}_a n^f \mathscr{G}_{ef}, \quad \mathfrak{S}_{ab} = h^e{}_a h^f{}_b \mathscr{G}_{ef}$$

# The explicit forms II.:

The reduced evolutionary expression  $E_{ab}^{(\mathcal{EVOL})}$  looks pretty complicated. Therefore, in certain cases (in particular, whenever  $\epsilon = -1$ ) it is rewarding to introduce

$$\widetilde{E}_{ab}^{(\mathcal{EVOL})} = E_{ab}^{(\mathcal{EVOL})} - \frac{1}{n-1} h_{ab} \left( E_{ef}^{(\mathcal{EVOL})} h^{ef} \right)$$

It can also be seen HW (4) that

$$\widetilde{E}_{ab}^{(\mathcal{EVOL})}=0 \quad \Leftrightarrow \quad E_{ab}^{(\mathcal{EVOL})}=0 \quad \text{and} \quad$$

$$\widetilde{E}_{ab}^{(\mathcal{EVOL})} = h^e{}_a h^f{}_b \left[ R_{ab} - \left( \mathscr{G}_{ab} - \frac{1}{n-1} g_{ab} \left[ \mathscr{G}_{ef} g^{ef} \right] \right) \right] + \frac{1+\epsilon}{n-1} h_{ab} E^{^{(\mathcal{H})}}$$

In virtue of the above relations we have

$$\begin{split} \widetilde{E}_{ab}^{(\mathcal{EVOL})} &= {}^{(n)}\!R_{ab} + \epsilon \left\{ -\mathscr{L}_{n}K_{ab} - (K^{e}_{\ e})K_{ab} + 2K_{ae}K^{e}_{\ b} - \epsilon N^{-1}D_{a}D_{b}N \right\} \\ &- \left(\mathfrak{S}_{ab} - \frac{1}{n-1}h_{ab}\left[\mathfrak{S}_{ef}h^{ef} + \epsilon \mathfrak{e}\right]\right) \\ &+ \frac{1+\epsilon}{2(n-1)}h_{ab}\left\{ -\epsilon^{(n)}\!R + (K^{e}_{\ e})^{2} - K_{ef}K^{ef} - 2\mathfrak{e} \right\} \end{split}$$

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## That is all for now...