# On the use of evolutionary methods in metric theories of gravity X.

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## Plans and Aims:

some of the arguments and techniques developed originally and applied so far exclusively only in the Lorentzian case do also apply to Riemannian spaces

#### • Time evolution and the degrees of freedom

- intimate relations between various parts of Einstein's equations
- fully constrained evolutionary scheme
- evolutionary-evolutionary systems
  - ... gauge choices
  - ... the conformal structure
  - ... gravitational degrees of freedom

Based on some recent papers

- I. Rácz: Is the Bianchi identity always hyperbolic?, Class. Quantum Grav. 31 (2014) 155004
- I. Rácz: Cauchy problem as a two-surface based 'geometrodynamics', Class. Quantum Grav. 32 (2015) 015006
- I. Rácz: Dynamical determination of the gravitational degrees of freedom, arXiv:1412.0667 (2015)
- I. Rácz: Constraints as evolutionary systems, Class. Quantum Grav. 33 015014 (2016)

## Assumptions:

## • The primary space: $(M, g_{ab})$

- M: n+1-dim. ( $n \geq 3$ ), smooth, paracompact, connected, orientable manifold
  - smoothly foliated by a one-parameter family of homologous hypersurfaces determined by a smooth function  $\sigma: M \to \mathbb{R}$  with non-vanishing  $\partial_a \sigma$  gradient; a flow  $\sigma^a$  has also been chosen such that  $\sigma^a \partial_a \sigma = 1$
  - one of these level surfaces is smoothly foliated by a one-parameter family of homologous codimension-two surfaces determined by a smooth function  $\rho: M \to \mathbb{R}$  with a.e. non-vanishing  $\partial_a \rho$  gradient; a "horizontal" flow  $\rho^a$  has also been chosen such that  $\rho^a \partial_a \rho = 1$
  - $\bullet \implies M$  is smoothly foliated by

#### a two-parameter family of codimension-two-surfaces:

- $g_{ab}$ : smooth Lorentzian(-,+,...,+) or Riemannian(+,...,+) metric
- Einsteinian space: Einstein's equation restricting the geometry

$$G_{ab} - \mathscr{G}_{ab} = 0$$

with source term  $\mathscr{G}_{ab}$  having a vanishing divergence,  $\nabla^a \mathscr{G}_{ab} = 0$ .

## The main creatures:

•  $n^a$  the 'unit norm' vector field that is normal to the  $\Sigma_\sigma$  level surfaces

$$n^a n_a = \epsilon$$

- $\epsilon$  takes the value -1 or +1 for Lorentzian or Riemannian metric  $g_{ab},$  resp.
- the projection operator and the metric induced

$$h_a{}^b = \delta_a{}^b - \epsilon n_a n^b \qquad \qquad h_{ab} = h_a{}^e h_b{}^f g_{ef} = g_{ab} - \epsilon n_a n_b$$

 $D_a$  denotes the covariant derivative operator associated with  $h_{ab}$ 

$$\mathscr{G}_{ab} = n_a n_b \, \mathfrak{e} + [n_a \, \mathfrak{p}_b + n_b \, \mathfrak{p}_a] + \mathfrak{S}_{ab}$$

$$\mathfrak{e} = n^e n^f \, \mathscr{G}_{ef}, \ \mathfrak{p}_a = \epsilon \, h^e{}_a n^f \, \mathscr{G}_{ef}, \ \mathfrak{S}_{ab} = h^e{}_a h^f{}_b \, \mathscr{G}_{ef}$$

• r.h.s. of Einstein's equation:  $E_{ab} = G_{ab} - \mathscr{G}_{ab}$ 

$$E_{ab} = n_a n_b E^{(\mathcal{H})} + [n_a E_b^{(\mathcal{M})} + n_b E_a^{(\mathcal{M})}] + (E_{ab}^{(\mathcal{EVOL})} + h_{ab} E^{(\mathcal{H})})$$

$$\stackrel{\mathcal{H}}{=} n^e n^f E_{ef}, \quad E_a^{(\mathcal{M})} = \epsilon h^e{}_a n^f E_{ef}, \quad E_{ab}^{(\mathcal{EVOL})} = h^e{}_a h^f{}_b E_{ef} - h_{ab} E^{(\mathcal{H})}$$

 $E^{\prime}$ 

## Relations between various parts of the basic equations:

$$\begin{aligned} \mathscr{L}_{n} E^{(\mathcal{H})} + D^{e} E_{e}^{(\mathcal{M})} + \left[ E^{(\mathcal{H})} \left( K^{e}_{e} \right) - 2 \epsilon \left( \dot{n}^{e} E_{e}^{(\mathcal{M})} \right) \right. \\ \left. - \epsilon K^{ae} \left( E_{ae}^{(\mathcal{EVOL})} + h_{ae} E^{(\mathcal{H})} \right) \right] &= 0 \end{aligned}$$
$$\\ \mathscr{L}_{n} E_{b}^{(\mathcal{M})} + D^{a} \left( E_{ab}^{(\mathcal{EVOL})} + h_{ab} E^{(\mathcal{H})} \right) + \left[ \left( K^{e}_{e} \right) E_{b}^{(\mathcal{M})} + E^{(\mathcal{H})} \dot{n}_{b} \right. \\ \left. - \epsilon \left( E_{ab}^{(\mathcal{EVOL})} + h_{ab} E^{(\mathcal{H})} \right) \dot{n}^{a} \right] &= 0 \end{aligned}$$

#### Corollary

If the constraint expressions  $E^{(\mathcal{H})}$  and  $E^{(\mathcal{M})}_a$  vanish on the  $\sigma = const$  level surfaces then the relations

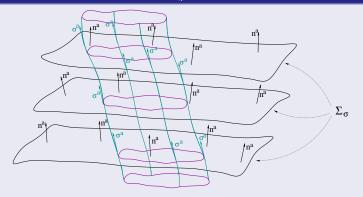
$$\begin{split} K^{ab} \, E^{(\mathcal{EVOL})}_{ab} &= \, 0 \\ D^a E^{(\mathcal{EVOL})}_{ab} - \epsilon \, \dot{n}^a \, E^{(\mathcal{EVOL})}_{ab} &= \, 0 \end{split}$$

hold for the evolutionary expression  $E_{ab}^{(\mathcal{EVOL})}$ .

$$h^{e}{}_{a}h^{f}{}_{b}E_{ef} = E^{(\mathcal{EVOL})}_{ab} + \underline{b_{ab}E}^{(\mathcal{H})}$$

## The two-parameter foliations:

The Lie drag this foliation of  $\Sigma_0$  along the integral curves of the vector field  $\sigma^a$  yields then a two-parameter foliation  $\mathscr{S}_{\sigma,\rho}$ :



• the fields  $\hat{n}^i$ ,  $\hat{\gamma}_{ij}$  and the projection  $\left[\hat{\gamma}^k_l = h^k_l - \hat{n}^k \hat{n}_l\right]$ , to the codimension-two surfaces  $\mathscr{S}_{\sigma,\rho}$ , get to be well-defined on each of the individual  $\sigma = const$  hypersurfaces

## The equations on the $\sigma = const$ hypersurfaces:

Some important relations we learned while studying the kinematical background:

using

$$h_{b}{}^{e}h_{d}{}^{f}R_{ef} = {}^{(n)}\!R_{bd} + \epsilon \left\{ -\mathscr{L}_{n}K_{bd} - K_{bd}K_{e}{}^{e} + 2K_{b}{}^{e}K_{de} - \epsilon N^{-1}D_{b}D_{d}N \right\}$$

$$R = {}^{(n)}\!R + \epsilon \left\{ -2\,\mathscr{L}_n(K_{bd}h^{bd}) - (K_e{}^e)^2 - K_{ef}K^{ef} - 2\,\epsilon\,N^{-1}D^eD_eN \right\}$$

one gets

$$\begin{split} \boxed{h_b{}^e h_d{}^f E_{ef}} &= h_b{}^e h_d{}^f \left\{ \left[ R_{ef} - \frac{1}{2} g_{ef} R \right] - \mathscr{G}_{bd} \right\} = h_b{}^e h_d{}^f \left\{ \left[ R_{ef} - \frac{1}{2} h_{ef} R \right] - \mathscr{G}_{bd} \right\} \\ &= \left[ {}^{(n)} R_{bd} - \frac{1}{2} h_{ef}{}^{(n)} R \right] - {}^{(n)} \mathscr{G}_{bd} = {}^{(n)} G_{bd} - {}^{(n)} \mathscr{G}_{bd} = {}^{(n)} E_{bd} \end{split}$$

where

## The explicit forms:

Expressions in the [n-1] + 1 decomposition:

$${}^{\scriptscriptstyle (n)}\!E_{ij} = \widehat{E}^{\scriptscriptstyle (\mathcal{H})}\widehat{n}_i\widehat{n}_j + [\widehat{n}_i\widehat{E}_j^{\scriptscriptstyle (\mathcal{M})} + \widehat{n}_j\widehat{E}_i^{\scriptscriptstyle (\mathcal{M})}] + (\widehat{E}_{ij}^{\scriptscriptstyle (\mathcal{EVOL})} + \widehat{\gamma}_{ij}\widehat{E}^{\scriptscriptstyle (\mathcal{H})})$$

$$\widehat{E}^{(\mathcal{H})} = \widehat{n}^e \widehat{n}^{f^{(n)}} E_{ef}, \quad \widehat{E}_i^{(\mathcal{M})} = \widehat{\gamma}^e{}_j \widehat{n}^{f^{(n)}} E_{ef}, \quad \widehat{E}_{ij}^{(\mathcal{EVOL})} = \widehat{\gamma}^e{}_i \widehat{\gamma}^f{}_j^{(n)} E_{ef} - \widehat{\gamma}_{ij} \widehat{E}^{(\mathcal{H})} \widehat{E}_{ef}$$

$$\begin{split} \widehat{\boldsymbol{E}}^{(\mathcal{H})} &= \ \frac{1}{2} \left\{ -\widehat{\boldsymbol{R}} + (\widehat{\boldsymbol{K}}^{l}{}_{l})^{2} - \widehat{\boldsymbol{K}}_{kl}\widehat{\boldsymbol{K}}^{kl} - 2\,\widehat{\mathfrak{e}} \right\}, \\ \widehat{\boldsymbol{E}}_{i}^{(\mathcal{M})} &= \ \widehat{D}^{l}\widehat{\boldsymbol{K}}_{li} - \widehat{D}_{i}\widehat{\boldsymbol{K}}^{l}{}_{l} - \widehat{\mathfrak{p}}_{i}\,, \\ \widehat{\boldsymbol{E}}_{ij}^{(\mathcal{EVOL})} &= \ \widehat{\boldsymbol{R}}_{ij} - \mathscr{L}_{\widehat{n}}\widehat{\boldsymbol{K}}_{ij} - (\widehat{\boldsymbol{K}}^{l}{}_{l})\widehat{\boldsymbol{K}}_{ij} + 2\,\widehat{\boldsymbol{K}}_{il}\widehat{\boldsymbol{K}}^{l}{}_{j} - \widehat{N}^{-1}\,\widehat{D}_{i}\widehat{D}_{j}\widehat{N} \\ &+ \widehat{\gamma}_{ij}\{\mathscr{L}_{\widehat{n}}\widehat{\boldsymbol{K}}^{l}{}_{l} + \widehat{\boldsymbol{K}}_{kl}\widehat{\boldsymbol{K}}^{kl} + \widehat{N}^{-1}\widehat{D}^{l}\widehat{D}_{l}\widehat{N}\} - [\widehat{\mathfrak{S}}_{ij} - \widehat{\mathfrak{e}}\,\widehat{\gamma}_{ij}] \end{split}$$

where  $\widehat{D}_i, \widehat{R}_{ij}$  and  $\widehat{R}$  denote ....

$$\widehat{\mathfrak{e}} = \widehat{n}^k \widehat{n}^{l} \widehat{\mathcal{G}}_{kl}, \quad \widehat{\mathfrak{p}}_i = \widehat{\gamma}^k{}_i \, \widehat{n}^{l} \widehat{\mathcal{G}}_{kl} \quad \text{and} \quad \widehat{\mathfrak{S}}_{ij} = \widehat{\gamma}^k{}_i \widehat{\gamma}^{l}{}_j \widehat{\mathcal{G}}_{kl}$$

and

$$\widehat{K}_{ij} = \widehat{\gamma}^l{}_i \, D_l \, \widehat{n}_j = \frac{1}{2} \, \mathscr{L}_{\widehat{n}} \, \widehat{\gamma}_{ij}$$

Foliations and their use

## Relations between various parts of the basic equations I.:

## Substituting the [n-1] + 1 splitting of ${}^{(n)}E_{ij}$ :

$$\begin{split} K^{ab} {}^{(n)}\!E_{ab} &= 0\\ D^{a} \big[ {}^{(n)}\!E_{ab} \big] - \epsilon \, \dot{n}^{a} {}^{(n)}\!E_{ab} &= 0 \end{split}$$
as
$$\begin{split} & \begin{pmatrix} m E_{ab} &= h^{e}{}_{a}h^{f}{}_{b} E_{ef} &= E_{ab}^{(\mathcal{EVOC})} + b_{ab} E^{(\mathcal{H})} \\ \dot{n}^{a} {}^{(n)}\!E_{ab} &= \kappa \, \hat{E}^{(\mathcal{H})} + 2 \, \mathbf{k}^{e} \hat{E}_{e}^{(\mathcal{M})} + \mathbf{K}^{ef} \, \hat{E}_{\mathcal{F}}^{(\mathcal{EVOC})} + (\mathbf{K}^{e}{}_{e}) \, \hat{E}^{(\mathcal{H})} \\ \dot{n}^{a} {}^{(n)}\!E_{ab} &= [(\hat{n}_{a}\dot{n}^{a}) \hat{E}^{(\mathcal{H})} + (\dot{n}^{a} \, \hat{E}_{a}^{(\mathcal{M})})] \hat{n}_{b} + (\hat{n}_{a}\dot{n}^{a}) \hat{E}_{b}^{(\mathcal{M})} + \dot{n}^{a} \, [\hat{E}_{ab}^{(\mathcal{EVOC})} + \hat{\gamma}_{ab} \, \hat{E}^{(\mathcal{H})}] \\ \hat{n}^{e} D^{a} \big[ {}^{(n)}\!E_{ae} \big] &= \mathcal{L}_{\hat{n}} \, \hat{E}^{(\mathcal{H})} + \hat{D}^{e} \hat{E}_{e}^{(\mathcal{H})} + (\hat{K}^{e}{}_{e}) \, \hat{E}^{(\mathcal{H})} - [\hat{E}_{\mathcal{F}}^{(\mathcal{EVOC})} + \hat{\gamma}_{ef} \, \hat{E}^{(\mathcal{H})}] \, \hat{K}^{ef} - 2 \, \dot{n}^{e} \hat{E}_{e}^{(\mathcal{M})} \\ \hat{\gamma}^{e}{}_{b} D^{a} \big[ {}^{(n)}\!E_{ae} \big] &= \mathcal{L}_{\hat{n}} \, \hat{E}_{b}^{(\mathcal{M})} + \hat{D}^{e} [\hat{E}_{eb}^{(\mathcal{EVOC})} + \hat{\gamma}_{eb} \, \hat{E}^{(\mathcal{H})}] + (\hat{K}^{e}{}_{e}) \, \hat{E}_{b}^{(\mathcal{M})} - \dot{n}^{e} \, \hat{E}_{eb}^{(\mathcal{EVOC})} \\ \hline & \mathcal{L}_{\hat{n}} \, \hat{E}^{(\mathcal{H})} + \hat{\gamma}^{ef} \, \hat{D}_{e} \, \hat{E}_{f}^{(\mathcal{M})} = \hat{\mathcal{E}} \end{split}$$

 $\implies \mathbf{IF} \ \widehat{E}_{ef}^{(\mathcal{EVOL})} = 0 \ \text{holds: a linear and homogeneous FOSH for} \ (\widehat{E}^{^{(\mathcal{H})}}, \widehat{E}_{i}^{^{(\mathcal{M})}})^T$ 

 $\mathscr{L}_{\widehat{n}}\,\widehat{E}_{b}^{(\mathcal{M})}+\widehat{D}_{b}\,\widehat{E}^{(\mathcal{H})}=\widehat{\mathscr{E}}_{b}$ 

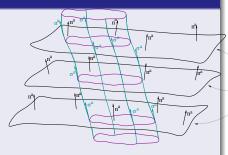
## What do the above observations imply?

### Theorem (I.)

 $\bullet \Longrightarrow$ 

- Assume that the primary constraint expressions  $E^{(\mathcal{H})}$  and  $E^{(\mathcal{M})}_a$  vanish on the  $\sigma = const$  level surfaces, also that
- the secondary constraint expressions  $\widehat{E}^{(\mathcal{H})}$  and  $\widehat{E}_{a}^{(\mathcal{M})}$  vanish along the hypersurface yielded by the Lie dragging,  $\mathscr{W}_{\rho_0} = \Phi_{\sigma}[\mathscr{S}_{\rho_0}]$ , of one of the level surfaces  $\mathscr{S}_{\rho_0}$  foliating  $\Sigma_0$ .

Then, to get solutions to the full set of Einstein's equations  $G_{ab} - \mathcal{G}_{ab} = 0$ it suffices—regardless whether the primary metric  $g_{ab}$  is Riemannian or Lorentzian—to solve, in addition, only the secondary reduced equations  $\widehat{E}_{ij}^{(\mathcal{EVOL})} = 0.$ 



**Remark (i).**: the Lie dragging is done by using the one-parameter group of diffeomorphisms,  $\Phi_{\sigma}$ , associated by the "time evolution vector field"  $\sigma^a$ — could be only a world-line

**Remark (ii):** if one wants to setup an initial-boundary value problem on either side of the hypersurface  $\mathcal{W}_{\rho_0}$  the previous theorem provides a clear mean to identify the geometrical freedom we have on  $\mathcal{W}_{\rho_0}$ 

## Relations between various parts of the basic equations II.:

$$\begin{split} K^{ab} {}^{(n)}\!E_{ab} &= 0 \\ D^{a} [{}^{(n)}\!E_{ab}] - \epsilon \dot{n}^{a} {}^{(n)}\!E_{ab} &= 0 \end{split}$$

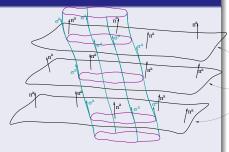
$$K^{ab} {}^{(n)}\!E_{ab} &= \kappa \, \hat{E}^{(\mathcal{H})} + 2 \, \mathbf{k}^{e} \hat{E}_{e}^{(\mathcal{M})} + \mathbf{K}^{ef} \, \hat{E}_{ef}^{(\mathcal{EVOL})} + (\mathbf{K}^{e}_{e}) \, \hat{E}^{(\mathcal{H})} \\ \dot{n}^{a} {}^{(n)}\!E_{ab} &= [(\hat{n}_{a}\dot{n}^{a}) \hat{E}^{(\mathcal{H})} + (\dot{n}^{a} \, \hat{E}_{a}^{(\mathcal{M})})]\hat{n}_{b} + (\hat{n}_{a}\dot{n}^{a}) \hat{E}_{b}^{(\mathcal{M})} + \dot{n}^{a} \, [\hat{E}_{ab}^{(\mathcal{EVOL})} + \hat{\gamma}_{ab} \, \hat{E}^{(\mathcal{H})}] \\ \hat{n}^{e} D^{a} [{}^{(n)}\!E_{ae}] &= \mathcal{L}_{\hat{n}} \, \hat{E}^{(\mathcal{H})} + \hat{D}^{e} \hat{E}_{e}^{(\mathcal{M})} + (\hat{\kappa}^{e}_{e}) \, \hat{E}^{(\mathcal{H})} - [\hat{E}_{ef}^{(\mathcal{EVOL})} + \hat{\gamma}_{ef} \, \hat{E}^{(\mathcal{H})}] \, \hat{K}^{ef} - 2 \, \dot{\hat{n}}^{e} \hat{E}_{e}^{(\mathcal{M})} \\ \hat{\gamma}^{e}{}_{b} D^{a} [{}^{(n)}\!E_{ae}] &= \mathcal{L}_{\hat{n}} \, \hat{E}_{b}^{(\mathcal{M})} + \hat{D}^{e} [\hat{E}_{eb}^{(\mathcal{EVOL})} + \hat{\gamma}_{eb} \, \hat{E}^{(\mathcal{H})}] + (\hat{K}^{e}_{e}) \, \hat{E}_{b}^{(\mathcal{M})} - \dot{\hat{n}}^{e} \, \hat{E}_{eb}^{(\mathcal{EVOL})} \\ \Rightarrow \text{ if the trace free part of } \hat{E}_{ef}^{(\mathcal{EVOL})} \text{ vanishes:} \\ \hat{\underline{E}}_{ef}^{(\mathcal{EVOL})} &= \hat{E}_{ef}^{(\mathcal{EVOL})} - \frac{1}{n-1} \, \hat{\gamma}_{ef} \, \left[ \hat{\gamma}^{kl} \, \hat{E}_{kl}^{(\mathcal{EVOL})} \right] = 0 \\ K^{ab} E^{(\mathcal{EVOL})}_{ab} &= (\kappa + \mathbf{K}^{e}_{e}) \, \hat{E}^{(\mathcal{H})} + 2 \, \mathbf{k}^{e} \hat{E}_{e}^{(\mathcal{M})} + \frac{1}{n-1} \, (\mathbf{K}^{e}_{e}) \, (\hat{\gamma}^{kl} \, \hat{E}_{kl}^{(\mathcal{EVOL})}) = 0 \\ \mathcal{L}_{\hat{n}} \, \hat{E}_{b}^{(\mathcal{H})} - (\mathbf{K}^{e}_{e})^{-1} \, [\kappa \, \hat{D}_{b} \hat{E}^{(\mathcal{H})} + 2 \, \mathbf{k}^{e} \, \hat{D}_{b} \hat{E}_{e}^{(\mathcal{M})} ] = \hat{\mathcal{E}}_{b} \end{cases}$$

and  $\kappa \cdot {f K}^e{}_e < 0$  !!! it is a linear and homogeneous strongly hyperbolic system

## What is the meaning?

#### Theorem (II.)

- Assume that the primary constraint expressions  $E^{(\mathcal{H})}$  and  $E^{(\mathcal{M})}_a$  vanish on the  $\sigma = const$  level surfaces, also that
- $\kappa \cdot \mathbf{K}^{e}{}_{e} < 0$  (on all  $\mathscr{S}_{\sigma,\rho}$ ) and the secondary constraint expressions  $\widehat{E}^{(\mathcal{H})}$  and  $\widehat{E}_{a}^{(\mathcal{M})}$  vanish along the Lie dragging  $^{(*)}$ ,  $\mathscr{W}_{\rho_{0}} = \Phi_{\sigma}[\mathscr{S}_{\rho_{0}}]$ , of one of the level surfaces  $\mathscr{S}_{\rho_{0}}$  foliating  $\Sigma_{0}$ .
  - $^{(*)}$  w.r.t. the one-parameter group of diffeomorphisms,  $\Phi_{\sigma}$ , associated by the "time evolution vector field"  $\sigma^a$



**Remark:** initial-boundary value problem on either side of the hypersurface  $\mathcal{W}_{\rho_0}$ ..... — could be only a world-line

•  $\implies$  Then, to get solutions to the full set of the primary Einstein's equations  $G_{ab} - \mathscr{G}_{ab} = 0$  it suffices—regardless whether the primary metric  $g_{ab}$  is Riemannian or Lorentzian—to solve, in addition, only the trace free part of the secondary reduced equations

$$\stackrel{\diamond}{E}_{ef}^{(\mathcal{EVOL})} = \widehat{E}_{ef}^{(\mathcal{EVOL})} - \frac{1}{n-1} \, \widehat{\gamma}_{ef} \, \left[ \widehat{\gamma}^{kl} \, \widehat{E}_{kl}^{(\mathcal{EVOL})} \right] = 0$$

## The complexity of the field equations has to be reduced I.

#### Assume: the shift of the "time evolution" vector field $\sigma^a$ vanishes

- appears to be pretty strong as a requirement...
- !!! Müller and Sánches (2011): it is not as ill and hellish as it looks for the first glance
  - ... (in the Lorentzian case) to any globally hyperbolic spacetime  $(M,g_{ab})$  there always exists a smooth time function  $\sigma: M \to \mathbb{R}$  with timelike gradient such that the  $\sigma = const$  level surfaces are Cauchy surfaces, and such that the metric can be given in the form

$$g_{ab} = \epsilon N^2 (d\sigma)_a (d\sigma)_b + h_{ab}$$

with a bounded lapse function  $N:M\to\mathbb{R},$  and with a smooth Riemannian metric  $h_{ab}$  on the  $\Sigma_\sigma$  time level surfaces.

- In case of Riemannian spaces one cannot refer to the correspondent of the result of Müller and Sánches.
  - Nevertheless, based on the diffeomorphism invariance of the underlying theory we may simply require, without loss of generality, that the metric  $g_{ab}$  possesses the above "canonical form" [Christodoulou and Klainerman (1993)].

Foliations and their use

## The complexity of the field equations can be reduced II.

Introduce the conformal structure by splitting the induced metric  $\hat{\gamma}_{ij}$ :

• Assume: there exist a smooth function  $\Omega: M \to \mathbb{R}$  which does not vanish—except at locations where the foliation  $\mathscr{S}_{\sigma,\rho}$  smoothly reduces to a lover dimensional subset on the  $\Sigma_{\sigma}$  level surfaces—such that the induced metric  $\widehat{\gamma}_{ij}$  can be decomposed as

$$\widehat{\gamma}_{ij} = \Omega^2 \, \gamma_{ij}$$

 $\gamma_{ij}$  is singled out by the condition:

$$\gamma^{ij}(\mathscr{L}_\eta\gamma_{ij})=0$$

that is expected to hold on each of the  $\mathscr{S}_{\sigma,\rho}$  surfaces, where  $\eta^a$  stands for either of the "time evolution" vector fields  $\sigma^a = (\partial_{\sigma})^a$  or  $\rho^a = (\partial_{\rho})^a$ 

$$\gamma^{ij}(\mathscr{L}_{\eta}\gamma_{ij}) = \mathscr{L}_{\eta} \ln[\det(\gamma_{ij})] = 0$$

the determinant of  $\gamma_{ij}$  is independent of the coordinates  $\sigma$  and  $\rho$ !!! it may depend on directions tangential to the level surfaces  $\mathscr{S}_{\sigma,\rho}$ 

0

## Verifications

#### The conformal structure:

• Does the desired smooth function  $\Omega: M \to \mathbb{R}$  and, in turn, the metric  $\gamma_{ij}$  exist?

$$\widehat{\gamma}^{ij}(\mathscr{L}_{\eta}\widehat{\gamma}_{ij}) = \underline{\gamma}^{ij}(\mathscr{L}_{\eta}\widehat{\gamma}_{ij}) + (n-1)\,\mathscr{L}_{\eta}(\ln\Omega^2)$$

where  $\eta^a$  stands either for  $\sigma^a$  or for  $\rho^a$ 

• (i) start with the smooth distribution of the induced metric  $\hat{\gamma}_{ij}$  on the  $\mathscr{S}_{\sigma,\rho}$  surfaces. (ii) integrate the above relation first along the integral curves of  $\rho^a$  on  $\Sigma_0$ , starting at some  $\mathscr{S}_0$ , and then along the integral curves of  $\sigma^a$ , starting at the surface  $\mathscr{S}_{\rho}$  on  $\Sigma_0$ , (iii) one gets  $\Omega^2 = \Omega^2(\sigma, \rho, x^3, \dots, x^{n+1})$  as

$$\Omega^2 = \Omega_0^2 \cdot \exp\left[\frac{1}{n-1} \int_0^\rho \left(\widehat{\gamma}^{ij}(\mathscr{L}_\rho \widehat{\gamma}_{ij})\right) \, d\tilde{\rho}\right] \cdot \exp\left[\frac{1}{n-1} \int_0^\sigma \left(\widehat{\gamma}^{ij}(\mathscr{L}_\sigma \widehat{\gamma}_{ij})\right) \, d\tilde{\sigma}\right] \,,$$

where  $\Omega_0 = \Omega_0(x^3, \dots, x^{n+1})$  denotes the conformal factor **chosen** at  $\mathscr{S}_0$ • Is  $\Omega$  consistently defined throughout M? ... the integrability condition for  $\ln \Omega^2$  is

$$\mathscr{L}_{\sigma}\left[\widehat{\gamma}^{ij}(\mathscr{L}_{\rho}\widehat{\gamma}_{ij})\right] - \mathscr{L}_{\rho}\left[\widehat{\gamma}^{ij}(\mathscr{L}_{\sigma}\widehat{\gamma}_{ij})\right] = 0$$

holds as the vector fields  $\sigma^a$  and  $\rho^a$  do commute by construction

## The decomposition of $h_{ij}$ and $K_{ij}$ :

• in adopted (local) coordinates  $(\sigma, \rho, x^3, \dots, x^{n+1})$   $h_{ij}$  read as

$$h_{ij} = (\widehat{N}^2 + \widehat{N}_E \widehat{N}^E) \, (\mathrm{d}\rho)_i (\mathrm{d}\rho)_j + 2 \, \widehat{N}_A \, (\mathrm{d}\rho)_{(i} (\mathrm{d}x^A)_{j)} + \widehat{\gamma}_{AB} \, (\mathrm{d}x^A)_i \, (\mathrm{d}x^B)_j$$

• whereas, as in the adopted coordinates  $(\sigma, \rho, x^3, ..., x^{n+1})$ , for any  $\alpha = 2, 3, \ldots, n = 1$   $(x^{\alpha} = \rho, x^A)$ 

$$\mathscr{L}_n(\mathrm{d}x^\alpha)_i = N^{-1}\,\mathscr{L}_\sigma(\mathrm{d}x^\alpha)_i = 0$$

$$K_{ij} = \frac{1}{2} \mathscr{L}_n h_{ij}$$

read as

 $2\,K_{ij} = \mathscr{L}_n(\widehat{N}^2 + \widehat{N}_E \widehat{N}^E)\,(\mathrm{d}\rho)_i(\mathrm{d}\rho)_j + 2\,\mathscr{L}_n \widehat{N}_A\,(\mathrm{d}\rho)_{(i}(\mathrm{d}x^A)_{j)} + \mathscr{L}_n \widehat{\gamma}_{AB}\,(\mathrm{d}x^A)_i\,(\mathrm{d}x^B)_j$ 

## The decomposition of $h_{ij}$ and $K_{ij}$ :

$$2\,K_{ij} = \mathscr{L}_n(\widehat{N}^2 + \widehat{N}_E \widehat{N}^E)\,(\mathrm{d}\rho)_i(\mathrm{d}\rho)_j + 2\,\mathscr{L}_n \widehat{N}_A\,(\mathrm{d}\rho)_{(i}(\mathrm{d}x^A)_{j)} + \mathscr{L}_n \widehat{\gamma}_{AB}\,(\mathrm{d}x^A)_i\,(\mathrm{d}x^B)_j$$

$$K_{ij} = \boldsymbol{\kappa} \, \widehat{n}_i \widehat{n}_j + [\widehat{n}_i \, \mathbf{k}_j + \widehat{n}_j \, \mathbf{k}_i] + \mathbf{K}_{ij} \,,$$

 $\widehat{n}_i = \widehat{N}(\mathrm{d}\rho)_i \And \widehat{\gamma}^i{}_j = \delta^i{}_j - \widehat{n}^i \widehat{n}_j \And \qquad \Longrightarrow \quad \widehat{n}^i(\mathrm{d}\rho)_i = \widehat{N}^{-1} \,, \quad \widehat{n}^i(\mathrm{d}x^A)_i = -\widehat{N}^{-1}\widehat{N}^A \quad \mathrm{and} \quad (\mathrm{d}\rho)_j \widehat{\gamma}^j{}_i = 0$ 

$$\begin{aligned} \boldsymbol{\kappa} &= \widehat{n}^{k} \widehat{n}^{l} K_{kl} = \mathscr{L}_{n} \ln \widehat{N} \\ \mathbf{k}_{i} &= \widehat{\gamma}^{k}{}_{i} \widehat{n}^{l} K_{kl} = \left(2 \widehat{N}\right)^{-1} \widehat{\gamma}_{il} \left(\mathscr{L}_{n} \widehat{N}^{l}\right) \\ \mathbf{K}_{ij} &= \widehat{\gamma}^{k}{}_{i} \widehat{\gamma}^{l}{}_{j} K_{kl} = \frac{1}{2} \widehat{\gamma}^{k}{}_{i} \widehat{\gamma}^{l}{}_{j} \left(\mathscr{L}_{n} \widehat{\gamma}_{kl}\right) \\ \end{aligned}$$

the (conformal invariant) projection operator reads as

$$\Pi^{kl}{}_{ij} = \widehat{\gamma}^k{}_i \widehat{\gamma}^l{}_j - \frac{1}{n-1} \, \widehat{\gamma}_{ij} \widehat{\gamma}^{kl} = \gamma^k{}_i \gamma^l{}_j - \frac{1}{n-1} \, \gamma_{ij} \gamma^{kl}$$

$$\overset{\circ}{\mathbf{K}}_{ij} = \Pi^{ef}{}_{ij} \, \mathbf{K}_{ef} = \mathbf{K}_{ij} - \frac{1}{n-1} \, \gamma_{ij}(\gamma^{ef} \mathbf{K}_{ef}) = \frac{1}{2} \, \Omega^2 \, \gamma^k{}_i \gamma^l{}_j \, \mathscr{L}_n \, \gamma_{kl}$$

## The n+1 constraints

#### The momentum constraint:

$$E_a^{(\mathcal{M})} = \epsilon h^e{}_a n^f E_{ef} = \epsilon \left( D_e K^e{}_a - D_a K^e{}_e - \epsilon \mathfrak{p}_a \right) = 0$$

It is a first order symmetric hyperbolic system for the vector valued variable

$$(\mathbf{k}_B, \mathbf{K}^{E_E})^T \longrightarrow (\mathcal{L}_n \widehat{N}^B, \mathcal{L}_n \ln \Omega^2)^T$$

where the 'radial coordinate'  $\rho$  plays the role of 'time' regardless of the value of  $\epsilon$ 

#### The Hamiltonian constraint:

$$E^{(\mathcal{H})} = n^{e} n^{f} E_{ef} = \frac{1}{2} \left\{ -\epsilon^{(n)} R + \left( K^{e}_{e} \right)^{2} - K_{ef} K^{ef} - 2 \mathfrak{e} \right\} = 0$$

) it is a parabolic equation for 
$$\widehat{\hat{N}}$$
  $[\widehat{K}^l{}_l = \widehat{N}^{-1} \stackrel{\star}{K} \& \widehat{N}^{-1} \widehat{D}^l \widehat{D}_l \widehat{N}]$ 

• algebraic equation for  $\kappa = \mathscr{L}_n \ln \widehat{N}$ 

• regardless of the value of  $\epsilon$ 

## Solving the primary constraints:

The n(n+1) independent components of  $(h_{ij}, K_{ij})$  may be represented by

$$(\widehat{N}, \widehat{N}^i, \Omega, \gamma_{ij}; \boldsymbol{\kappa}, \mathbf{k}_i, \mathbf{K}^l_l, \overset{\circ}{\mathbf{K}}_{ij}))$$

• or by applying  $\kappa = \mathscr{L}_n \ln \widehat{N}$  and  $\mathbf{k}_i = (2\widehat{N})^{-1} \widehat{\gamma}_{il} (\mathscr{L}_n \widehat{N}^l)$   $\mathbf{K}^l_l = \frac{n-1}{2} \mathcal{L}_n \ln \Omega^2$  and  $\mathbf{\hat{K}}_{ij} = \frac{1}{2} \Omega^2 \gamma^k_{\ i} \gamma^l_{\ j} (\mathscr{L}_n \gamma_{kl})$  $\widehat{(\widehat{N}, \widehat{N}^i, \Omega, \gamma_{ij}; \mathscr{L}_n \widehat{N}, \mathscr{L}_n \widehat{N}^i, \mathcal{L}_n \Omega, \mathscr{L}_n \gamma_{ij})}$ 

• The constraints can be solved either

(i) as a parabolic-hyperbolic system for

$$\widehat{N}, \mathscr{L}_n \widehat{N}^i, \mathscr{L}_n \Omega$$

with freely specifiable variables on  $\Sigma_0$ :

$$(\widehat{N}^{i}, \Omega, \boldsymbol{\gamma_{ij}}; \mathscr{L}_{n}\widehat{N}, \mathscr{L}_{n}\boldsymbol{\gamma_{ij}})$$

 $(\widehat{N}, \widehat{N}^i, \Omega, \gamma_{ij}; \mathcal{L}_n \gamma_{ij})$ 

(ii) or as a symmetrizable hyperbolic system & algebraic equation for

$$(\mathscr{L}_n \widehat{N}, \mathscr{L}_n \widehat{N}^i, \mathcal{L}_n \Omega)$$

with freely specifiable variables on  $\Sigma_0$ :

Solving the constraints

## Principal parts of the secondary constraints:

## $\widehat{E}^{(\mathcal{H})} = 0$

$$-2\mathscr{L}_n^2\Omega + \widehat{D}^l\widehat{D}_l\Omega + \Omega\widehat{D}^l\widehat{D}_l(\ln N) - \frac{1}{n-1}{}^{(\gamma)}R\Omega^{-1} + \{\text{lower order terms}\} = 0$$

$$\Longrightarrow \mathscr{L}_n^2 \Omega = \dots \Longrightarrow \mathscr{L}_n \Omega = \dots \text{ on } \mathscr{W}_{\rho_0} = \Phi_{\sigma}[\mathscr{S}_{\rho_0}]$$

## $\widehat{E}_i^{(\mathcal{M})} = 0$

$$(2\widehat{N})^{-1}\Omega^{2}\gamma_{il}(\mathscr{L}_{n}^{2}\widehat{N}^{l}) + \widehat{N}^{-1}\widehat{D}_{i}(\widehat{D}_{l}\widehat{N}^{l}) + \frac{1}{n-1}\Omega^{2}\widehat{D}^{l}[\mathscr{L}_{\widehat{n}}\gamma_{li}] - \widehat{D}_{i}[\mathscr{L}_{\widehat{n}}(\ln N)] + \Omega^{-1}\widehat{D}_{i}[\mathscr{L}_{\widehat{n}}\Omega] - 2(\widehat{N}\Omega)^{-1}\widehat{D}_{i}[\mathscr{L}_{\rho}\Omega] + \{\text{lower order terms}\} = 0 \Longrightarrow \mathscr{L}_{n}^{2}\widehat{N}^{l} = \dots \Longrightarrow \mathscr{L}_{n}\widehat{N}^{l} = \dots \text{ on } \mathscr{W}_{\rho_{0}} = \Phi_{\sigma}[\mathscr{L}_{\rho_{0}}]$$

## Solubility of the mixed system:

The principal parts of  $\widehat{E}_{ij}^{(\mathcal{EVOL})} = 0$ :

$$\widehat{E}_{ij}^{(\mathcal{EVOL})} = \Pi^{kl}{}_{ij}\, \widehat{E}_{kl}^{(\mathcal{EVOL})} + \frac{1}{n-1}\, \widehat{\gamma}_{ij}\, \left\{ \widehat{\gamma}^{kl}\, \widehat{E}_{kl}^{(\mathcal{EVOL})} \right\} = 0\,,$$

$$\begin{split} &\frac{1}{2} \gamma^k{}_i \gamma^l{}_j (\epsilon \,\mathscr{L}_n^2 \gamma_{kl} + \mathscr{L}_{\widehat{n}}^2 \gamma_{kl}) + \frac{1}{n-1} \,\widehat{N}^{-1} \gamma_{ij} \,\mathscr{L}_{\widehat{n}}(\mathbb{D}_l \widehat{N}^l) \\ &+ \Omega^{-2} \,\Pi^{kl}{}_{ij} [\mathbb{D}_k \mathbb{D}_l (\ln N + \ln \widehat{N})] + \{\text{lower order terms}\} = 0 \end{split}$$

$$\epsilon \mathscr{L}_{n}^{2}(\ln \widehat{N}) + \mathscr{L}_{\widehat{n}}^{2}(\ln \widehat{N}) + \widehat{D}^{l}\widehat{D}_{l}(\ln \widehat{N}) + \frac{n-2}{2(n-1)}\Omega^{-2}\left[\gamma^{pq}\gamma^{st}(\partial_{t}\partial_{q}\gamma_{ps} - \partial_{t}\partial_{s}\gamma_{pq})\right] + \{\text{lower order terms}\} = 0$$

## Solubility of the mixed system:

$$\begin{split} & \frac{1}{2} \, \gamma^k_{\ i} \gamma^l_{\ j} \, (\epsilon \, \mathscr{L}_n^2 \gamma_{kl} + \mathscr{L}_{\widehat{n}}^2 \gamma_{kl}) + \frac{1}{n-1} \, \widehat{N}^{-1} \gamma_{ij} \, \mathscr{L}_{\widehat{n}}(\mathbb{D}_l \widehat{N}^l) \\ & \qquad + \Omega^{-2} \, \Pi^{kl}{}_{ij} [\mathbb{D}_k \mathbb{D}_l (\ln N + \ln \widehat{N})] + \{ \text{lower order terms} \} = 0 \end{split}$$

$$\begin{split} \epsilon \, \mathcal{L}_n^2(\ln \widehat{N}) &+ \mathcal{L}_{\widehat{n}}^2(\ln \widehat{N}) + \widehat{D}^l \widehat{D}_l(\ln \widehat{N}) \\ &+ \frac{n-2}{2(n-1)} \, \Omega^{-2} \left[ \gamma^{pq} \gamma^{st} (\partial_t \partial_q \gamma_{ps} - \partial_t \partial_s \gamma_{pq}) \right] + \{ \text{lower order terms} \} = 0 \end{split}$$

- Provided that suitable fields  $\Omega, \gamma_{AB}, \hat{N}^A, \mathscr{L}_n \gamma_{AB}, \mathscr{L}_n \hat{N}$  are chosen on  $\Sigma_0$ and  $\hat{N}, \mathscr{L}_n \hat{N}^A, \mathscr{L}_n \Omega$  on some  $\mathscr{S}_{\rho_0} \Longrightarrow$  the parabolic-hyperbolic system  $E_b^{(\mathcal{M})} = 0 \& E^{(\mathcal{H})} = 0$  can be solved for  $\hat{N}, \mathscr{L}_n \hat{N}^A, \mathscr{L}_n \Omega$
- The fields  $\Omega, \widehat{N}^A$  can also be determined on the succeeding  $\Sigma_{\sigma}$  level surfaces by integrating  $\mathscr{L}_n \Omega, \mathscr{L}_n \widehat{N}^A$  along the  $\sigma^a = N n^a = (\partial/\partial \sigma)^a$  'time lines'.
- This way the corresponding inductive process may be closed by evaluating all the fields  $\Omega, \mathscr{L}_n\Omega, \widehat{N}, \mathscr{L}_n\widehat{N}, \widehat{N}^A, \mathscr{L}_n\widehat{N}^A, \gamma_{AB}, \mathscr{L}_n\gamma_{AB}$  on the succeeding  $\Sigma_{\sigma}$  level surfaces.

#### Summary

## Summary:

- Euclidean and Lorentzian signature Einsteinian spaces of n + 1-dimension (n ≥ 3) were considered. The topology of M was restricted by assuming:
  - smoothly foliated by a one-parameter family of homologous hypersurfaces
  - one of these level surfaces is smoothly foliated by a one-parameter family of homologous codimension-two surfaces
- the Bianchi identity and a pair of nested decompositions were used to explore interrelations of various projections of the field equations
- a proposal to setup the initial-boundary problem in GR is given by applying some geometrically distinguished variables and using the interrelation of various parts of Einstein's equations
- the **conformal structure**  $\gamma_{ij}$ , defined on the foliating codimension-two surfaces  $\mathscr{S}_{\sigma,\rho}$ , appears to provide a **convenient embodiment** of the  $\frac{(n-1)n}{2} 1$  degrees of freedom in Einstein's theory of gravity
- III all these results apply regardless whether the primary space is Riemannian or Lorentzian

## That is all...