

I Classical Part

- GR formulated as an SU(2) gauge theory (Holst action, Ashtekar variables)
- Quantization of systems with constraints
- Observables for GR, physical phase space. (relational framework)
- BK-Model + add. matter coupled
DGKL-Model to GR

Literature:

Book:

C. Rovelli Quantum Gravity, Cambridge, 2004
T. Thiemann, Modern Canonical, —, 2007
QG

- Ashtekar, Lewandowski, gr-qc/0404018
T. Thiemann gr-qc/0210094
 - A. Perez (Spin foams) long gr-qc/0110034
gr-qc/0409006
 - P. Dona, S. Speziale gr-qc/1007.0402
 - H. Nicolai, K. Peters, M. Zambrini hep-th/0508114
T. Thiemann hep-th/0608210
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- C. Rovelli, gr-qc/1012.4707
H. Sahlmann gr-qc/1001.4188

II Kinematics

- Kinematical Hilbert space of LQG
(Representation of Holonomy-flux-algebra)
- Geometric Operators: Area Operator

- ' (Johannes Brunneemann: volume operator)
- c) Implementation of the classical constraints as operator (Gauß-, Diffeo Constraint) Solutions of Constraints
- d) LOST - Theorem

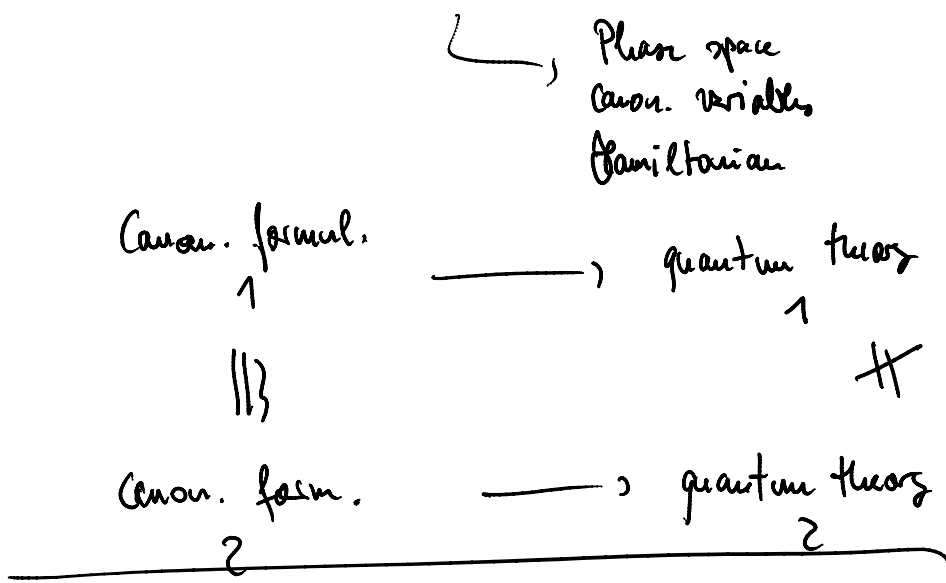
III Dynamics

- a) Quantization of the Hamiltonian constraint (Thiemann's trick)
- b) Quantization of the BK- and the DBK- Models
- c) Semiclassical LQG: Coherent States
- d) Black holes in LQG
- e) Outlook & ^{open} problems in LQG

I. Classical theory

1. Canon. formulation, no variables

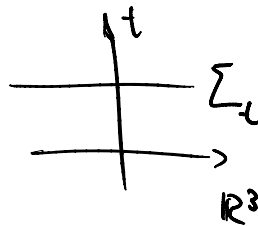
Dir: Canon. quantization of GR
 ~ need canonical formulation of GR



Remarkably: \exists formulation s.t. phase space is that of χ M-theory!

Warm-up: Maxwell theory

$$S[A] = \frac{1}{4} \int_{M^4} F_{\mu\nu} F^{\mu\nu} dx^4$$



Introduce equal time surfaces Σ_t

canonical coordinates: A_μ and momenta

$$p^\mu = \frac{\delta S}{\delta \dot{A}_\mu} \quad \leadsto \quad p^a = E^a, \quad p^0 = 0$$

$$S = \int dt \int_{\Sigma_t} d^3x \quad E^a \dot{A}_a - \frac{1}{2} (B^2 + E^2) - A_0 \nabla E$$

Now: GR

Frame? ("Tetrad") $e_I \equiv e_I^\mu \partial_\mu$: Basis of tangent space at each point. Also, map $\mathbb{R}^4 \rightarrow T_p M$

If there is metric on internal space \leadsto define metric on M :

$$g^{\mu\nu} := e_I^\mu e_J^\nu \eta^{IJ}$$

Co-frame: $e^I = e^I_\mu dx^\mu$

$$S[\omega, e] = S_p[\omega, e] + S_H[\omega, e]$$

\hookrightarrow $so(3,1)$ connection

$$S_0 = \frac{1}{2} \int \langle e_{\mu\nu}, e^I_\mu e^J_\nu \rangle \eta^{IJ} dx^4$$

$$S[\omega, e] = S_p[\omega, e] + S_H[\omega, e]$$

So (3,1) connection

$$S_p = \frac{1}{4\kappa} \int \epsilon_{\mu\nu\alpha} e^{\mu} \wedge e^{\nu} \wedge F^{\alpha}(\omega)$$

$$S_H = -\frac{1}{2\kappa\beta} \int e^{\mu} \wedge e^{\nu} \wedge F_{\mu\nu}(\omega)$$

$$\frac{\delta S}{\delta \omega} \stackrel{!}{=} 0 \quad (\Rightarrow) \quad D^{(\omega)} e = 0 \quad \rightsquigarrow \quad \omega \equiv \omega(e)$$

Insert into S

$$S_H[\omega(e), e] = 0 \quad S_p[\omega(e), e] = EH$$

$\beta \in \mathbb{R}/\{0\}$ in the following.

Space-time decomposition:

time function $t \rightsquigarrow t = \text{const slices } \Sigma_t$

time vectorfield t^α : $t^\alpha \partial_\alpha t \stackrel{!}{=} 1$

$$t^\alpha = N u^\alpha + N^\alpha$$

\hat{e} unit normal to Σ_t

Also: partial gauge fixing:

$$e_\mu^0 \stackrel{!}{=} u_\mu$$

Thus only $SO(3)$ remains as gauge group.

Decompose fields:

$$(e^I_\mu) = \begin{pmatrix} N & N^i \\ 0 & \boxed{e^a} \end{pmatrix} \quad \text{co-triad.}$$

Also break ω into parts: $SO(3)$ connection on Σ_t

+ "the rest" Γ, K

$$\omega = \omega^i \partial_i + \omega^a G_a + N^a C_a + N \cdot C$$

$$S = \frac{1}{2\kappa\beta} \int dt \int_{\Sigma_t} E_i^a \dot{A}_a^i - \underbrace{(\omega_0^i G_i + N^a C_a + N \cdot C)}_{\text{("Hamiltonian")}}$$

$$A_a^i = \Gamma_a^i + \beta K_a^i \quad E_i^a = \sqrt{\det q} e_i^a$$

$$(q_{ab} = e_a^i e_b^j \delta_{ij})$$

$$G_i = D_a^{(N)} E_i^a$$

$$C_a = E_i^b F_{ab}^i + \left(\right)_a^i G_i \quad (H_a = C_a - G_a)$$

$$H = \frac{\beta}{2} \frac{1}{\sqrt{\det q}} E_i^a E_j^b \left[\epsilon^{ij} F_{ab}^k - 2(1+\beta^2) \frac{k_e^i k_e^j}{\epsilon} \right]$$

$$\{A_e^i(x), E_j^b(y)\} = 8\pi G \beta \delta_a^b \delta_{ij} \delta(x,y)$$

Constraint equations $G_i = 0$, $H_a = 0$, $H = 0$, together with

$$\dot{A} = \{A, h\}, \quad \dot{E} = \{E, h\}$$

are equivalent to Einstein's equations.

Evolution is gauge:

$$\{A_e, G(\Lambda)\} = -D_a^{(N)} \Lambda = \frac{d}{d\epsilon} \Big|_{\epsilon=0} g_\epsilon^A g_\epsilon^{-1} + g_\epsilon^A g_\epsilon^{-1}$$

$$\int G_i \Lambda^i$$

$$g_\epsilon = \exp(\epsilon \Lambda)$$

$$\{E^e, G(\Lambda)\} = [\Lambda, E^e]$$

$$\{A, \vec{H}(\vec{N})\} = \mathcal{L}_{\vec{N}}(A) \quad \{E, \vec{H}(\vec{N})\} = \dots$$

Action of $H(N)$ related to $\mathcal{L}_{u^e N}$.

Diac algebra:

$$\begin{aligned} \{G_i, G_j\} &= G_k, & \{\tilde{H}_i, \tilde{H}_j\} &= \tilde{H}_k \\ \{G_i, \tilde{H}_j\} &= G_k, & \{H_i, G_j\} &= 0 \\ \{H_i, \tilde{H}_j\} &= H_k, & \{H_i, H_j\} &= \tilde{H}_k \end{aligned}$$

Remarks: $D+1$

1) $A_i \sim D(D-1)/2$ 1-Forms

$E_i \rightarrow D$ vector fields

Matters only for $D=3$

$$\hat{H}(N) \Psi \stackrel{!}{=} 0$$

Reduced Phase space Approach

(i) Solve the constraints already at the classical level (Observables)

• Observables are gauge-invariant

(ii) Dynamics of the observables (true physical evolution no gauge-transformation)



Notation: $(A, E) \rightsquigarrow (q_{ab}, p_{ab})$
 $G_{ij}, C_a, C \rightsquigarrow C_a, C$
 $\vec{C}(\vec{N}), C(N)$

In the canonical
 $\{C(N), \sigma^j\} = \{ \vec{C}(\vec{N}), \sigma^j \} = 0$

$$\{C(N), \mathcal{O}\} = \{ \vec{C}(\vec{N}), \mathcal{O} \} = 0$$

$\Leftrightarrow \mathcal{O}$ is an observable (Dirac observables)

• $H_{can} = \vec{C}(\vec{N}) + C(N)$

\Rightarrow if \mathcal{O} is an observable we have

$$\{ \mathcal{O}, H_{can} \} = 0$$

This shows that the dynamics of observables cannot be generated by H_{can} .

• There must be a different generator for the dynamics of $\hat{\mathcal{O}}$, physical Hamiltonian $H_{phys} \neq 0$ on the constraint hypersurface

• Idea of the reduced framework:

(i) Construct Dirac observables for (A,E)
(q_{ab}, p_{ab})

(ii) Derive the associated H_{phys}
then the dynamics

$$Q_{ab} := \mathcal{O}_{q_{ab}}, \quad P_{ab} := \mathcal{O}_{p_{ab}}$$

$$\begin{aligned} \dot{Q}_{ab} &= \{ Q_{ab}, H_{phys} \} \text{ gauge-invariant} \\ \dot{P}_{ab} &= \{ P_{ab}, H_{phys} \} \text{ version of Einstein's equation} \end{aligned}$$

• This is the classical starting point for a reduced quantization.

• Construction of Dirac observables:

• Choice: for each of the constraints in the system you choose one reference field, clocks

- there exist a general map for each gauge-variant quantity (q_{ab}, p_{ab}) to its corresponding Dirac observable

- Relational formalism (dynamics is formulated wrt the values that the reference fields take)

- Dirac observables:

$$Q_{ab}(\tau) = \sum_{n=0}^{\infty} \frac{(\tau - T)^n}{n!} \left(\underbrace{\frac{1}{\{C, T\}}}_{\mathcal{K}_C} \right)^n \cdot q_{ab}$$

τ = physical time values

T = time reference field

\mathcal{K}_C = Hamiltonian VF of C

$$\mathcal{K}_C = \exp(\mathcal{K}_C) \cdot q_{ab}$$

$$\mathcal{K}_C \cdot q_{ab} = \{C, q_{ab}\}$$

$$\mathcal{K}_C^n \cdot q_{ab} = \{ \{q_{ab}, C\}, C \}, \{C, C\}, \dots \} \text{ up to order } n$$

$$\frac{1}{\{C, T\}} \text{ to ensure } \mathcal{K}_C \cdot T = 1 \Leftrightarrow \{C, T\} = 1$$

We have $\{C, Q_{ab}\} = 0$

- We will construct Dirac observables in two particular models:

- GR: $4 \times \infty$ constraints $C(x) = 0, \mathcal{C}_a(x) = 0$

→ $4 \times \infty$ many clocks in GR

- 4 scalar fields are appropriate

- 4 particular scalar fields

- BK-dust model (gravity + dust matter)

$$S = S_{\text{gravity}} + S_{\text{dust}}$$

Einstein-Hilbert

$$S = S_{\text{gravity}} + S_{\text{dust}}$$

Einstein-Hilbert

$$\int_{\mathcal{M}} d^4x \sqrt{\det(g)} R$$

$$S_{\text{dust}} = - \frac{1}{2} \int_{\mathcal{M}} d^4x \sqrt{\det(g)} g (g^{\alpha\beta} U_{\alpha\beta} + 1)$$

$g \hat{=}$ energy density of the dust

$$U_{\alpha} = -T_{,\alpha} + \omega_j S^j_{,\alpha} \quad T_i, S^j, \omega_j \quad j=1,2,3$$

7 scalar fields

ω_j is related to the momenta T, S^j

• 4 'independent' scalar fields, which we will use as reference fields

$T \hat{=}$ reference field for time (Hamiltonian)

$S^j \hat{=}$ reference field for spatial coord.

(Diffeomorphism constraint)

• Assume: $\det(S^k_{,\alpha}) \neq 0 \quad S^k_{,\alpha} = (T, S^k)$

• Perform (3+1) decomposition

$$(T, P), (S^j, P_j)$$

first class constraints

$$C^{\text{tot}} = C^g + C^{\text{dust}} = 0 \quad C^{\text{dust}} = - \sqrt{p^2 + q^{ab} g} \begin{matrix} (PT)_{,a} + P_j S^j_{,a} \\ (PT)_{,b} + P_k S^k_{,b} \end{matrix}$$

$$C_a^{\text{tot}} = C_a^g + C_a^{\text{dust}} = 0$$

$$C_a^{\text{dust}} = PT_{,a} + P_j S^j_{,a}$$

• Idea of BK:

$$C^{\text{dust}} = - \sqrt{p^2 + q^{ab} C_a^{\text{dust}} C_b^{\text{dust}}} \approx$$

$$\stackrel{\text{wealdy equiv.}}{\approx} - \sqrt{p^2 + q^{ab} C_a^g C_b^g}$$

• Using $c^{\text{tot}} = 0$

$$\tilde{x}^{\text{tot}} = P + h(q, P),$$

$$h(p, q) = \sqrt{(C^a)^2 - q^{ab} C_a^a C_b^a}$$

• Same game for the diffeomorphism constraint

$$\tilde{C}_j^{\text{tot}} = P_j - h_j(S_{iT}, q, p), \quad S_{i,a}^j, S_{i,a}^a \text{ inverse}$$

$$S_{i,a}^j S_{i,k}^a = \delta_{k,b}^j \quad S_{i,a}^j S_{i,j}^a = \delta_b^a$$

$$C_J := (\tilde{C}^{\text{tot}}, \tilde{C}_j^{\text{tot}}) \quad h_j = S_{i,j}^a (P_{T,a} + C_a^a)$$

• Dirac Algebra for constraint

$\{C_J(x), C_K(y)\} = 0$ mutually commute
true Lie algebra for the constraints

• Now we use the C_K to construct Dirac observables:
by construction: $\{S^K, C_J\} = \delta_J^K$

Since $c^{\text{tot}} = P + h(p, q)$
Hamiltonian deparametrizes here no dust dof
metrizes no T in $h(p, q)$

• Let's apply the observable map $\mathcal{P}_{\text{reduced}}^{\tilde{c}^{\text{tot}}}$

$$Q_{ab}(\tilde{c}, \sigma^i) = \exp\left(\int h_{\tilde{c}, \cdot} \cdot y\right) \exp\left(\int_{\Sigma} d^3x \beta^j \{C_j(x), \cdot\}\right) \cdot q_{ab}$$

phys. time \uparrow physical spatial coord. \uparrow reduces

$$h_{\tau} = \int_{\mathcal{S}} d^3s (\tau - T) h(s)$$

virt \tilde{c}_a^{tot}

$\dot{p}_i =$
di- \dot{p}_i

• (Q_{ab}, p^{ab}) Dirac observables

• (ii) Dynamics

We want the associated phys. Hamiltonian

$$H_{\text{phys}} = \int_{\mathcal{S}^{\text{dust space}}} d^3s H(s)$$

observable associated to $h(p, q)$

$$H(s) = \sqrt{(C^g)^2 + Q^{ab} C_a^g C_b^g} \quad \Phi h(p, q) = H(Q, P)$$

• $H_{\text{phys}} \neq 0$ and it is gauge-invariant

• EOM:

$$\frac{dQ_{ab}}{d\tau} = \dot{Q}_{ab} = \{Q_{ab}(x), H_{\text{phys}}\}$$

$$\frac{dp^{ab}}{d\tau} = \dot{p}^{ab} = \{p^{ab}(x), H_{\text{phys}}\}$$

reduced phase formulation of GR with dust as clocks

• Classical starting point for quantization

• 2nd Model: DGL-Model

Gravity + one K.G. scalar field

$$S = S_g + \frac{1}{2} \int_{\mathcal{M}} d^4x \sqrt{\det(g)} g^{\alpha\beta} \phi_{, \alpha} \phi_{, \beta}$$

• 3+1-split (ϕ, π)

• Constraints:

$$c^{\text{tot}} = c^g + \frac{1}{2} \frac{\pi^2}{\sqrt{\det(g)}} + \frac{1}{2} g^{ab} \phi_{, a} \phi_{, b} \sqrt{\det(g)}$$

$$c_a^{\text{tot}} = c_a^g + \pi \phi_{, a}$$

1-1

• One reference field, so we will use C_a^{tot} to solve the Hamiltonian constraint for π

$$q^{ab} \phi_{,a} \phi_{,b} = \frac{q^{ab} C_a^\phi C_b^\phi}{\pi^2} \approx \frac{q^{ab} C_a^g C_b^g}{\pi^2}$$

• Insert this into C^{tot} :

$$0 = C^g + \frac{1}{2} \frac{\pi^2}{\sqrt{\det(q)}} + \frac{1}{2} \sqrt{\det(q)} \frac{q^{ab} C_a^g C_b^g}{\pi^2}$$

$$\Leftrightarrow \pi^4 + 2 \sqrt{\det(q)} C^g \pi^2 + \frac{1}{2} \sqrt{\det(q)} q^{ab} C_a^g C_b^g = 0$$

→ solving for π

$$\pi = \pm \sqrt{-\sqrt{\det(q)} C^g + \sqrt{\det(q)}} \sqrt{(C^g)^2 - q^{ab} C_a^g C_b^g}$$

• This allows us to rewrite (choose)

$$C^{\text{tot}} = \pi - h(p, q) \quad h$$