Physical interpretation of the Newman-Janis algorithm

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Based on P. Beltracchi and P. Gondolo, Phys. Rev. D 104, 124066 (2021) P. Beltracchi and P. Gondolo, Phys. Rev. D 104, 124067 (2021)

Overview

- The Newman-Janis algorithm¹ originally allowed for the derivation of the Kerr-Newman black hole and a rederivation of the Kerr black hole
- Gurses and Gursey² showed a version of the algorithm can create rotating Kerr-Schild spacetimes from static spherical Kerr-Schild spacetimes. Popular with nonsingular black hole research
- Drake and Szekeres³ examined a further extension which could create rotating spacetimes from arbitrary spherically symmetric spacetimes
- While exact solutions to rotating spacetimes are interesting, the physical nature of the algorithm and properties of the resultant spacetime are not immediately apparent.

[1] E. T. Newman and A. I. Janis, J. Math. Phys. 6, 915 (1965).[2]M. Gurses and F. Gursey, J. Math. Phys. 16, 2385 (1975).[3]S. P. Drake and P. Szekeres, Gen. Rel. Grav. 32, 445 (2000).

Original Newman Janis 1

-Write Schwarzschild or Reissner-Nordstrom metric in advanced null coordinates,

$$ds^{2} = -\left(1 - \frac{2M}{r} + \frac{Q^{2}}{r^{2}}\right)du^{2} - 2\,du\,dr + r^{2}(d\theta^{2} + \sin^{2}\theta d\phi^{2}),$$

-express $g^{\mu\nu}$ from null tetrads with complex coordinate r

$$g^{\mu\nu} = -l^{\mu}n^{\nu} - l^{\nu}n^{\mu} + \bar{m}^{\nu}m^{\mu} + \bar{m}^{\mu}m^{\nu},$$

$$l^{\mu} = (0, 1, 0, 0),$$

$$n^{\mu} = \left(1, -\frac{1}{2}\left(1 - M\left(\frac{1}{r} + \frac{1}{\bar{r}}\right) + \frac{Q^{2}}{r\bar{r}}\right), 0, 0\right),$$

$$m^{\mu} = \frac{1}{\sqrt{2}\bar{r}}\left(0, 0, 1, \frac{i}{\sin\theta}\right).$$

Original Newman-Janis 2

-Transform r and u coordinates to new r^* , u^* coordinates,

 $u^* = u - ia\cos\theta, \quad r^* = r + ia\cos\theta$

so that the new tetrads are

$$l^{*\mu} = (0, 1, 0, 0),$$

$$n^{*\mu} = \left(1, -\frac{1}{2}\left(1 - \frac{2r^*M}{\Sigma} + \frac{Q^2}{\Sigma}\right), 0, 0\right),$$

$$m^{*\mu} = \frac{1}{\sqrt{2}(r^* - ia\cos\theta)}\left(ia\sin\theta, -ia\sin\theta, 1, \frac{i}{\sin\theta}\right),$$

where we assume r^*, a, θ are all real and $\Sigma = r^{*2} + a^2 \cos^2 \theta$.

-Construct a metric such that

$$g^{*\mu\nu} = -l^{*\mu}n^{*\nu} - l^{*\nu}n^{*\mu} + \bar{m}^{*\nu}m^{*\mu} + \bar{m}^{*\mu}m^{*\nu},$$

which is the Kerr-Newman metric in u, r^*, θ, ϕ coordinates.

Open questions

- One finds Schwarzschild → Kerr and Reissner-Nordstrom → Kerr-Newman. What else can we do?
- The complexification of the M term and the Q term look rather different at this level. Is there a more systematic way of doing the complexifications?
- Why did this work?

The Gurses-Gursey Algorithm for Kerr-Schild systems

Start with a spherically symmetric Kerr-Schild metric in Schwarzschild coordinates

$$ds^2 = -\left(1 - \frac{2m(r)}{r}\right)dt^2 + \left(1 - \frac{2m(r)}{r}\right)^{-1}dr^2 + r^2d\theta^2 + r^2\sin^2\theta d\phi^2.$$

convert to advanced null coordinates $du = dt - (1 - 2m(r)/r)^{-1}dr$, obtaining

$$ds^2 = -\left(1 - rac{2m(r)}{r}
ight)du^2 - 2\,du\,dr + r^2(d heta^2 + \sin^2 heta d\phi^2).$$

Write in terms of l, m, n as before, but with the appropriately modified n

$$n^{\mu} = \left(1, -\frac{1}{2}\left(1 - \frac{2m(r)}{r}\right), 0, 0\right)$$

Complexify the r coordinate such that

$$n^{\mu} = \left(1, -\frac{1}{2}\left(1 - \frac{(r+\bar{r})m(\frac{r+\bar{r}}{2})}{r\bar{r}}\right), 0, 0\right),$$

Kerr-Schild systems have metrics that can be written $g_{\mu\nu}=\eta_{\mu\nu}$ -S $k_{\mu}k_{\nu}$ where S is a scalar function and k is a null vector with respect to both the Minkowski metric η and full metric g

GG Algorithm Continued Perform the same coordinate change, the generalized *n* becomes

$$n^{*\mu} = \left(1, -\frac{1}{2}\left(1 - \frac{2r^*m(r^*)}{r^{*2} + a^2\cos^2\theta}\right), 0, 0\right)$$

Reconstruct metric using new tetrads, and relabel $r^* \to r$ for simplicity, to obtain

$$ds^{2} = -\left(1 - \frac{2rm}{\Sigma}\right) du^{2} - 2 \, du \, dr + \Sigma \, d\theta^{2}$$
$$+ \sin^{2} \theta \left[2a \, dr \, d\phi - \frac{4arm}{\Sigma} \, du \, d\phi + \left(r^{2} + a^{2} + \frac{2a^{2}rm \sin^{2} \theta}{\Sigma}\right) d\phi^{2}\right]$$

where $\Sigma = r^2 + a^2 \cos^2 \theta$. Convert to Boyer-Lindquist coordinates using

$$du = dt - \frac{r^2 + a^2}{\Delta} dr, d\phi = d\varphi - \frac{a}{\Delta} dr$$

with the notation $\Delta = r^2 + a^2 - 2rm(r)$, and relabel $d\varphi \to d\phi$ to get

$$ds^{2} = -\left(1 - \frac{2rm}{\Sigma}\right)dt^{2} + \frac{\Sigma}{\Delta}dr^{2} + \Sigma d\theta^{2} + \sin^{2}\theta \left(\frac{2a^{2}rm\sin^{2}\theta}{\Sigma} + a^{2} + r^{2}\right)d\phi^{2} - \frac{4arm\sin^{2}\theta}{\Sigma}dt d\phi.$$

-To go backwards, set a=0. -a can be thought of as the rotation parameter -Rotating/nonrotating pair of spacetimes uniquely specified by mass function m -What can we say about the physical content for these pairs?

Properties of GG systems: Metric

It is helpful to call rewrite the metric to call attention to the principal directions

$$ds^{2} = -\frac{\Delta}{\Sigma} \left(dt - a \sin^{2} \theta \, d\phi \right)^{2} + \frac{\Sigma}{\Delta} \, dr^{2} + \Sigma \, d\theta^{2} + \frac{\sin^{2} \theta}{\Sigma} \left[(r^{2} + a^{2}) d\phi - a \, dt \right]^{2}.$$

We can also write the Kerr-Schild null vector and scalar function

$$S = -\frac{2rm}{r^2 + a^2 \cos^2 \theta},$$
$$k_{\mu} = \left(1, \frac{\Sigma}{\Delta}, 0, -a \sin^2 \theta\right)$$

the remaining portion

$$\eta_{\mu\nu}dx^{\mu}dx^{\nu} = -dt^{2} + \frac{\Sigma\left(a^{2} - 4rm + r^{2}\right)}{\Delta^{2}}dr^{2} + \Sigma\,d\theta^{2} + \left(a^{2} + r^{2}\right)\sin^{2}\theta\,d\phi^{2} + \frac{4arm\sin^{2}\theta}{\Delta}\,dr\,d\phi - \frac{4rm}{\Delta}\,dr\,dt$$

has a fully 0 Riemann tensor, so it is the required Minkowski metric.

We label these directions 1,2,3,4 respectively

Properties of GG systems: EMT1

$$\begin{split} T^{t}_{\ t} &= -\frac{m'}{4\pi\Sigma^{3}} \left[r^{2}(r^{2}+a^{2}) - a^{4}\sin^{2}\theta\cos^{2}\theta \right] + \frac{ra^{2}\sin^{2}\theta\,m''}{8\pi\Sigma^{2}} & \to \frac{-m'}{4\pi r^{2}}, \\ T^{\phi}_{\ t} &= \frac{a}{8\pi\Sigma^{3}} \left[(r^{2}+a^{2}\cos^{2}\theta)rm'' - 2(r^{2}-a^{2}\cos^{2}\theta)m' \right] & \to 0, \\ T^{r}_{\ r} &= -\frac{r^{2}m'}{4\pi\Sigma^{2}} & \to \frac{-m'}{4\pi r^{2}}, \\ T^{\theta}_{\ \theta} &= -\frac{rm''}{8\pi\Sigma} - \frac{a^{2}\cos^{2}\theta\,m'}{4\pi\Sigma^{2}} & \to \frac{-m''}{8\pi r}, \\ T^{t}_{\ \phi} &= -\sin^{2}\theta\,(a^{2}+r^{2})\,T^{\phi}_{\ t} & \to 0, \\ T^{\phi}_{\ \phi} &= \frac{a^{2}m'}{4\pi\Sigma^{3}} \left[r^{2}\sin^{2}\theta - (r^{2}+a^{2})\cos^{2}\theta \right] - \frac{r(a^{2}+r^{2})m''}{8\pi\Sigma^{2}} & \to \frac{-m''}{8\pi r}. \end{split}$$

Properties of GG systems: EMT2

• Eigenvalues:

$$-\rho = p_{\parallel} = \Lambda_{(1)} = \Lambda_{(2)} = -\frac{r^2 m'}{4\pi \Sigma^2}$$
$$p_{\perp} = \Lambda_{(3)} = \Lambda_{(4)} = -\frac{rm''}{8\pi\Sigma} - \frac{a^2 \cos^2 \theta m'}{4\pi\Sigma^2}$$

- Segre type [(11)(1,1)] or degenerates to [(111,1)]
- Eigenvalue degeneracy \rightarrow freedom with eigenvectors $v_{\mu}^{12} = A(-1, 0, 0, a \sin^2 \theta) + B(0, 1, 0, 0),$ $v_{12}^{\mu} = \frac{A}{\Delta}(a^2 + r^2, 0, 0, a) + \frac{B\Delta}{\Sigma}(0, 1, 0, 0)$ $w_{\mu}^{34} = C(0, 0, 1, 0) + D\left(-\frac{a}{a^2 + r^2}, 0, 0, 1\right),$ $w_{34}^{\mu} = \frac{C}{\Sigma}(0, 0, 1, 0) + \frac{D}{a^2 + r^2}(a, 0, 0, \csc^2 \theta)$

 $\rightarrow \frac{-m'}{4\pi r^2},$ $\rightarrow \frac{-m''}{8\pi r}.$ Overview of Segre Type
- Notation of the eigenvalue/
eigenvector structure of a
matrix
-In GR, typically use Segre
types to examine $T^{\mu_{\nu}}$ and $R^{\mu_{\nu}}$ -[(11)(1,1)] refers to a pair of
degenerate "space-space"
eigenvalues and second
degenerate eigenvalues

Properties of GG systems: EMT3

- Symmetry of 12 directions \rightarrow boosts, Symmetry of 34 directions \rightarrow rotations
- Normalized, timelike version of $v^{\mu}_{(12)} \rightarrow$ family of 4 velocities

$$u^{\mu} = \frac{\cosh(W)}{\sqrt{|\Delta|\Sigma}} (a^{2} + r^{2}, 0, 0, a) + \sinh(W) \sqrt{\frac{|\Delta|}{\Sigma}} (0, 1, 0, 0),$$

"Angular velocity" of "matter" can be found

$$\frac{\partial \phi}{\partial t} = \frac{\frac{\partial \phi}{\partial \tau}}{\frac{\partial t}{\partial \tau}} = \frac{u^{\phi}}{u^{t}} = \frac{a}{a^{2} + r^{2}}$$

note: no dependence on m, same for all GG systems

$$0 = \frac{1}{2} + \frac{$$

r/a

GG systems: Equations of State 1

- Consider an EOS written in the form F(p,ρ,T,...)=0
- Segre [(11)(1,1)] automatically satisfies $ho = -p_{\parallel}, \, p_2 = p_3 = p_{\perp}.$
- We are particularly interested in

 $F(\rho, p_{\perp}) = 0$

- For spherical systems, if either eigenvalue is monotonic in r, an F can be derived
- It is usually NOT preserved when we pass into a rotating system, but under certain circumstances it is

GG systems: Equations of State 2

$$\begin{split} F(\rho,p_{\perp}) &= 0 \quad \text{implies} \\ \frac{\partial F}{\partial \rho} \frac{\partial \rho}{\partial r} + \frac{\partial F}{\partial p_{\perp}} \frac{\partial p_{\perp}}{\partial r} &= 0, \\ \frac{\partial F}{\partial \rho} \frac{\partial \rho}{\partial \theta} + \frac{\partial F}{\partial p_{\perp}} \frac{\partial p_{\perp}}{\partial \theta} &= 0, \\ \frac{\partial F}{\partial \rho} \frac{\partial \rho}{\partial \theta} + \frac{\partial F}{\partial p_{\perp}} \frac{\partial p_{\perp}}{\partial \theta} &= 0. \\ \frac{\partial p_{\perp}}{\partial r} \frac{\partial \rho}{\partial \theta} - \frac{\partial p_{\perp}}{\partial \theta} \frac{\partial \rho}{\partial r} &= 0 \\ \frac{\partial p_{\perp}}{\partial r} \frac{\partial \rho}{\partial \theta} - \frac{\partial p_{\perp}}{\partial \theta} \frac{\partial \rho}{\partial r} &= 0 \\ r^2 m''(r)^2 - 2rm'(r) \left(m''(r) + rm^{(3)}(r)\right) + 4m'(r)^2 &= 0, \\ \text{Reminiscent of Schwarzschild term, Reisnner-Nordstrom term, string cloud term, de Sitter term} \\ m(r) &= M - \frac{K}{r} + \lambda r + \frac{1}{6} \Lambda r^3, \text{ with } \lambda^2 = 2K\Lambda. \end{split}$$

GG systems: Equations of State 3



GG "Rotating de Sitter"

- $m=\Lambda r^{3}/6, \rightarrow de$ Sitter in nonrotating case
- Previously studied, name used in¹²³
- has inhomogeneous anisotropic properties in rotating case
- Does not follow vacuum energy EOS, does follow GGEOS
- Violates NEC, except on equator



[1]N. Ibohal, Gen. Rel. Grav. 37, 19 (2005),

[2] I. Dymnikova, Physics Letters B 639, 368 (2006)

[3] E. J. Gonzalez de Urreta and M. Socolovsky, arXiv:1504.01728 (2015

GG Recap

- Kerr-Schild nature, [(11)(1,1)] Segre type preserved
- Eigenvalue degeneracy → freedom in eigenvectors. 4 velocity can be constructed, implies same angular velocity for all m functions.
- Equation of state preserved for Schwarzschild \rightarrow Kerr and Reissner/Nordstrom \rightarrow Kerr/Newman
- Vacuum energy equation of state, general nonlinear electrodynamics/nonsingular black holes: alterations of equation of state, possible violation of NEC.
- We derived the particular equation of state that is preserved GGEOS, this can be examined further, or in other contexts like Cosmology¹

[1] P. Beltracchi JCAP 09 (2023) 010

Drake-Szekeres for general systems

Write the metric of the general static spherically symmetric spacetime as

$$ds^{2} = -f(r) dt^{2} + \frac{dr^{2}}{h(r)} + r^{2} d\theta^{2} + r^{2} \sin^{2} \theta d\phi^{2},$$

with

$$h(r) = 1 - \frac{2m(r)}{r}, \qquad f(r) = \frac{h(r)}{[j(r)]^2},$$

and j(r) defined in such a way that it is positive and real.

The corresponding rotating metric is

where $\Sigma_j = r^2 j(r) + a^2 \cos^2 \theta$. As before, rewrite in terms of principal directions

$$ds^{2} = -\frac{\Sigma\Delta}{\Sigma_{j}^{2}} \left(dt - a\sin^{2}\theta \,d\phi\right)^{2} + \frac{\Sigma}{\Delta} \,dr^{2} + \Sigma \,d\theta^{2} + \frac{\Sigma\sin^{2}\theta}{\Sigma_{j}^{2}} \left[(a^{2} + jr^{2})d\phi - a\,dt\right]^{2}.$$

-Again, a can be thought of as the rotation parameter -When j=1, the systems are Kerr-Schild and the Gurses-Gursey metric is recovered

DS properties: EMT 1

The actual expressions for the EMT components are too long to fit on a slide, but using the principal direction we can define tetrads and analyze the STRUCTURE in a Local Lorentz frame

$$e^{\alpha}_{\ \hat{\alpha}} = \begin{pmatrix} \frac{a^2 + jr^2}{\sqrt{|\Delta|\Sigma}} & 0 & 0 & \frac{a\sin\theta}{\sqrt{\Sigma}} \\ 0 & \sqrt{\frac{|\Delta|}{\Sigma}} & 0 & 0 \\ 0 & 0 & \sqrt{\frac{1}{\Sigma}} & 0 \\ \frac{a}{\sqrt{|\Delta|\Sigma}} & 0 & 0 & \frac{1}{\sin\theta\sqrt{\Sigma}} \end{pmatrix} \rightarrow T^{\hat{\mu}}_{\ \hat{\nu}} = \begin{pmatrix} \hat{\mu}_0 & 0 & 0 & -\hat{\sigma}_{30} \\ 0 & \hat{\mu}_1 & \varepsilon_{\Delta} \hat{\sigma}_{12} & 0 \\ 0 & \hat{\sigma}_{12} & \hat{\mu}_2 & 0 \\ \varepsilon_{\Delta} \hat{\sigma}_{30} & 0 & 0 & \hat{\mu}_3 \end{pmatrix}.$$

We assume $\Delta \neq 0$ and $\varepsilon_{\Delta} = sign(\Delta)$. The metric in this orthornormal frame is

$$g_{\hat{\alpha}\hat{\beta}} = g_{\alpha\beta}e^{\alpha}_{\ \hat{\alpha}}e^{\beta}_{\ \hat{\beta}} = \text{diag}(-\varepsilon_{\Delta}, \ \varepsilon_{\Delta}, \ 1, \ 1),$$

-General property of axisymmetric EMT: Block diagonal structure with tφ block and rθ block -Tetrad does not generally diagonalize EMT, but we later show doing so is not always possible

DS properties: EMT2

The eigenvalues are

$$\lambda_{r\theta}^{\pm} = \frac{1}{2} \Big(\hat{B}_{12} \pm \sqrt{\hat{D}_{12}} \Big), \quad \lambda_{t\phi}^{\pm} = \frac{1}{2} \Big(\hat{B}_{30} \pm \sqrt{\hat{D}_{30}} \Big).$$

using the discriminants D and traces B the blocks, which are

$$\hat{D}_{12} = (\hat{\mu}_1 - \hat{\mu}_2)^2 + 4 \varepsilon_{\Delta} \hat{\sigma}_{12}^2, \qquad \hat{B}_{12} = \hat{\mu}_1 + \hat{\mu}_2,$$
$$\hat{D}_{30} = (\hat{\mu}_3 - \hat{\mu}_0)^2 - 4 \varepsilon_{\Delta} \hat{\sigma}_{30}^2, \qquad \hat{B}_{30} = \hat{\mu}_3 + \hat{\mu}_0.$$

One expression of the eigenvectors in $(\hat{0}, \hat{1}, \hat{2}, \hat{3})$ is

$$V_1^{\hat{\mu}} = (-\hat{\sigma}_{30}, \ 0, \ 0, \ \lambda_{t\phi}^+ - \hat{\mu}_0) \qquad V_2^{\hat{\mu}} = (\lambda_{t\phi}^- - \hat{\mu}_3, \ 0, \ 0, \ \varepsilon_{\Delta}\hat{\sigma}_{30})$$
$$V_3^{\hat{\mu}} = (0, \ \varepsilon_{\Delta}\hat{\sigma}_{12}, \ \lambda_{r\theta}^+ - \hat{\mu}_1, \ 0) \qquad V_4^{\hat{\mu}} = (0, \ \lambda_{r\theta}^- - \hat{\mu}_2, \ \hat{\sigma}_{12}, \ 0).$$

$\Delta > 0$					
$t\phi~{ m block}$				$r\theta$ block	
$\hat{D}_{30} > 0$	$\hat{D}_{30}=0$		$\hat{D}_{30} < 0$	$\hat{D}_{12} = 0$	$\hat{D}_{12} eq 0$
	$\hat{\sigma}_{30}=0$	$\hat{\sigma}_{30} \neq 0$			
[1, 1]	[(1,1)]	[2]	$[Z\bar{Z}]$	[(11)]	[11]
$\Delta < 0$					
r heta block				$t\phi$ block	
$\hat{D}_{12} > 0$	\hat{D}_{12}	= 0	$\hat{D}_{12} < 0$	$\hat{D}_{30} = 0$	$\hat{D}_{30} eq 0$
	$\hat{\sigma}_{12} = 0$	$\hat{\sigma}_{12} \neq 0$			
[1, 1]	[(1, 1)]	[2]	$[Z\bar{Z}]$	[(11)]	[11]

Complex conjugate and double null eigenvector cases do not diagonalize with a timelike LLF

DS: "Spinning Minkowski"

- In general, DS systems are very complex
- One system where direct analysis is possible is using the spherical seed metric

$$ds^{2} = -\frac{1}{j^{2}} dt^{2} + dr^{2} + r^{2} d\theta^{2} + r^{2} \sin^{2} \theta \, d\phi^{2},$$

which corresponds to Minkowski space with a scaled time coordinate

• If either a=0 (no rotation) or j=1 (typical time scaling), the Riemann tensor for the DS "spinning" metric vanishes and it remains Minkowski space, but for arbitrary a, j there is typically nontrivial curvature and an EMT

DS: "Spinning Minkowski" D,B

The Drake-Szekeres "spinning Minkowski" spacetime results in the following expressions for the invariants \hat{B}_{12} , \hat{B}_{30} , \hat{D}_{12} , and \hat{D}_{30} ,

$$\begin{split} \hat{B}_{12} &= \frac{a^2(j-1)}{4\pi\Sigma^2\Sigma_j^2} \Big[-a^2(4r^2+a^2)\chi^4 - r^2(4jr^2-3ja^2+3a^2)\chi^2 + jr^4 \Big], \\ \hat{D}_{12} &= \frac{a^4(j-1)^2}{16\pi^2\Sigma^4\Sigma_j^4} \Big[a^4 \big[(j-1)(j-13)r^4 - 2(j+11)a^2r^2 + a^4 \big] \chi^8 \\ &\quad + 2a^2r^2 \big[(j-1)^2r^4 + (2j^2-7j-7)a^2r^2 - 2(j-5)a^4 \big] \chi^6 \\ &\quad + r^4 \big[(j-1)(13j-1)r^4 + 2(7j^2+7j-2)a^2r^2 + 2(2j^2+11j+2)a^4 \big] \chi^4 \\ &\quad + 2jr^6 \big[(11j+1)r^2 + 2(5j-1)a^2 \big] \chi^2 + j^2r^8 \Big], \\ \hat{B}_{30} &= \frac{a^2(j-1)}{4\pi\Sigma^2\Sigma_j^2} \Big[a^2(jr^2-r^2-a^2)\chi^4 - (j-1)r^2(r^2-2a^2)\chi^2 + jr^4 \Big], \\ \hat{D}_{30} &= \frac{a^2(j-1)^2}{16\pi^2\Sigma^3\Sigma_j^4} \Bigg[a^6(r^2+a^2)\chi^8 + a^4r^2(4j^2r^2 - 18jr^2 + 13r^2 - 6ja^2 + 4a^2)\chi^6 \\ &\quad + a^2r^4(13j^2r^2 - 18jr^2 + 4r^2 + 5j^2a^2 - 5a^2)\chi^4 + jr^6(jr^2 - 4ja^2 + 6a^2)\chi^2 - j^2r^8 \Bigg] \end{split}$$

Important properties: -a(j-1) in coefficient, conditions for flat, vacuum spacetime -Terms in square brackets are polynomial in r, χ, determine Segre type

where we use the shorthand $\chi = \cos \theta$.





Plots showing Segre types for values j = 1/10 on the left and j = 3 on the right. The gray regions are where $\hat{D}_{30} < 0$ and the Segre type of the $t\phi$ block is $[Z\bar{Z}]$. The white regions are where $\hat{D}_{30} > 0$ and the Segre type of the $t\phi$ block is [11]. The boundary between the two regions (shown as black) with $\hat{D}_{30} = 0$ are generally have Segre type [2] for the $t\phi$ block. The blue line shows the location where there is a cross block degeneracy.

DS: "Spinning Minkowski" On axis cross block degeneracy



Figure 2: This figure illustrates the particular cross-block degeneracies at $\chi^2 \equiv \cos^2 \theta = 1$ for various r/a, j. We have $\lambda_{t\phi}^- = \lambda_{r\theta}^-$ in light orange and $\lambda_{t\phi}^- = \lambda_{r\theta}^+$ in dark orange, both of these indicate a [(1,1)] type degeneracy. We have $\lambda_{t\phi}^+ = \lambda_{r\theta}^+$ in dark blue and $\lambda_{t\phi}^+ = \lambda_{r\theta}^-$ in light blue, both of which are [(11)] cross block degeneracies.

DS: "Spinning Minkowski" Non-appearing Segre types

- Segre types [31] and [(31)], i.e. triple null eigenvector types, can not occur for any DS system due to the block structure of the EMT.
- [2(11)] and [(211)], i.e. one block with a double null eigenvector and the second with degenerate eigenvalues, or with a double null eigenvector and all degenerate eigenvalues, could in theory occur for a DS system but did not appear here

DS Recap

- Rotating DS systems can have widely variable behavior
- Sorts of Matter or Fields described unclear
- The only globally perfect fluid rotating NJ system is the vacuum Kerr solution, perfect fluid may appear at isolated points
- While this is more general than the GG version, the complexity makes it less used

Conclusion

- Newman-Janis algorithm and its generalizations allow for creation of rotating spacetimes from non-rotating spacetimes
- Rotating system generated may not correspond to something that can be easily interpreted as a rotating version of the spherical system: Equations of state distortion, possible complex eigenvalues...
- One needs to analyze the EMTs of the spherical and corresponding generated rotating system to determine the correspondance
- Possible future: More recent work on alternate forms of the algorithm (e.g.¹) are similar to DS but have different notation, this may lead to more usable expressions. Alternatively, further examinations of systems using the algorithm (e.g.^{1,2,...}) may increase intuitive understanding of how these systems may behave.

[1] M. Azreg-Ainou, Phys. Rev. D 90, 064041 (2014)
[2] A. Smailagic and E. Spallucci, Phys. Lett. B688, 82 (2010)
[3]C. Bambi and L. Modesto, Phys. Lett. B721, 329 (2013)

Thank You

Backup 1: Kerr-Schild, [(11)(1,1)], and nonsingular black holes

• The Anisotropic TOV can be loosely thought of as a static force balance equation



- 2m=r → denominator in gravity term goes to 0, "horizon condition". Forces are unbalanced, or a singularity exists.
- If p_r=-p, gravity term vanishes identically everywhere. Can have "balanced forces" on horizon (see Reissner-Nordstrom for most basic example), popular with nonsingular black holes
- Segre type [(11)(1,1)] is the general type for spherically symmetric spacetimes which satisfy p_r=-ρ
- Spherically symmetric Kerr-Schild is Segre [(11)(1,1)], GG method generates a rotating spacetime

Backup 2: DS Expressions 1

$$\begin{split} \hat{\mu}_{0} &= \frac{1}{32\pi\Sigma^{3}\Sigma_{j}^{2}} \left[\left[-8r^{2}\Sigma\Sigma_{j}^{2}m' + (1-\chi^{2})a^{2}r^{3}\Sigma^{2}(4j+rj')j' \right. \\ &+ 8(j-1)a^{2}r^{2} \left[(1-\chi^{2})(r^{4}-a^{4}\chi^{4}) - 3r\chi^{2}(\Sigma+\Sigma_{j})m \right] \\ &+ 4(j-1)^{2}a^{2}r^{2}\Sigma \left[(1-\chi^{2})\Sigma+r^{2}(1-4\chi^{2}) \right] \right] \end{split}$$
(A.1a)
$$\hat{\mu}_{1} &= \frac{1}{32\pi\Sigma^{3}\Sigma_{j}^{2}} \left[\left[-8r^{2}\Sigma\Sigma_{j}^{2}m' + a^{2}r^{4}(1-\chi^{2})\Sigma^{2}(j')^{2} \\ &- 4r^{3}\Sigmaj' \left[2a^{2}\chi^{2}(a^{2}+r^{2}) + (\Sigma^{2}+(a^{2}+r^{2})(r^{2}-a^{2}\chi^{2}))j - 4mr\Sigma_{j} \right] + \\ 8a^{2}r^{2}\Sigma(j-1) \left[(\chi^{2}-5)\Sigma+6r^{2}(1-\chi^{2}) + 2r\chi^{2}m \right] - \\ 4a^{2}r^{2}(j-1)^{2} \left[6r^{4}(\chi^{2}-1) + r^{2}\Sigma(5+4\chi^{2}) + \Sigma^{2}(\chi^{2}-1) - 6r^{3}\chi^{2}m \right] \right]$$
(A.1b)
$$\hat{\mu}_{2} &= \frac{1}{32\pi\Sigma^{3}\Sigma_{j}^{2}} \left[\left[-4r\Sigma^{2}\Sigma_{j}^{2}m' - 8a^{2}\chi^{2}\Sigma^{3}m' - 4r^{2}\Sigma^{2}\Sigma_{j}(r^{2}+a^{2}-2rm)j'' + \\ r^{4}\Sigma^{2} \left[7(a^{2}+r^{2}) + \Sigma - 16rm \right] (j')^{2} + 4r\Sigma j' \left\{ rm \left[-jr^{2} \left(5a^{2}\chi^{2}+r^{2} \right) + 15a^{2}r^{2}\chi^{2} + 11a^{4}\chi^{4} \right] \\ + jr^{2} \left[a^{2}r^{2} \left(2\chi^{2}+1 \right) + a^{4}\chi^{2} \left(\chi^{2}+3 \right) - r^{4} \right] - a^{2}\chi^{2} \left[a^{2}r^{2} \left(7\chi^{2}+6 \right) + 4a^{4}\chi^{2} + 9r^{4} \right] + 3r^{2}\Sigma\Sigma_{j}m' \right\} \\ + 8(j-1)a^{2}\chi^{2} \left\{ \Sigma \left[m'r^{2} \left(a^{2}\chi^{2}+2jr^{2}-r^{2} \right) - 5a^{2}r^{2} \left(\chi^{2}-1 \right) - a^{4}\chi^{2}r^{4} \right] + rm \left[3a^{2}r^{2}\chi^{2} + 5a^{4}\chi^{4} + r^{4} - 3j(a^{2}r^{2}\chi^{2}+2r^{4}) \right] \right\} + 4(j-1)^{2}(3r^{4}+11a^{2}r^{2}+5a^{4}\chi^{2}-2a^{2}r^{2}\chi^{2}+a^{4}\chi^{4})a^{2}r^{2}\chi^{2} \right]$$
(A.1c)

Backup 2: DS Expressions 2

$$\begin{aligned} \hat{\mu}_{3} &= \frac{1}{32\pi\Sigma^{3}\Sigma_{j}^{2}} \left[\left[-4r\Sigma^{2}\Sigma_{j}^{2}m'' - 8a^{2}\chi^{2}\Sigma\Sigma_{j}(3\Sigma - 2\Sigma_{j})m' + 12r^{3}\Sigma^{2}\Sigma_{j}j'm' \right. \\ &- 16r^{5}\Sigma^{2}m(j')^{2} + 8r^{3}\Sigma^{2}\Sigma_{j}mj'' - 4r^{2}\Sigma[jr^{4} - a^{4}\chi^{4} + 5a^{2}\chi^{2}(\Sigma_{j} - 3\Sigma)]mj' \\ &+ 8a^{2}r\chi^{2}(j-1)[r^{4} - a^{4}\chi^{4} - 3a^{2}r^{2}\chi^{2}(j-1) - 6(jr^{4} - a^{4}\chi^{4})]m - 4r^{2}(a^{2} + r^{2})\Sigma^{2}\Sigma_{j}j'' \\ &+ r^{4}\Sigma^{2}[5a^{2}(1-\chi^{2}) + 8\Sigma](j')^{2} \\ &- 4r\Sigma(6a^{4}r^{2}\chi^{2} + 9a^{2}r^{4}\chi^{2} + 4a^{6}\chi^{4} + 7a^{4}r^{2}\chi^{4} + a^{2}r^{4}j + r^{6}j - a^{4}jr^{2}\chi^{2} - 4a^{2}r^{4}\chi^{2}j - 3a^{4}r^{2}\chi^{4}j)j' \\ &- 4a^{2}\Sigma\chi^{2}(j-1)(a^{2}r^{2} + r^{4} + 2a^{4}\chi^{2} + 5a^{2}r^{2}\chi^{2} - 3a^{2}jr^{2} - 3r^{4}j - 3a^{2}r^{2}\chi^{2}j) \right] \qquad (3.11) \\ \hat{\sigma}_{30} &= \frac{a\sqrt{|\Delta|}\sin\theta}{16\pi\Sigma^{2}\Sigma_{j}^{2}} \left[\left[-2r(r^{2}\Sigma_{j} + 2\Sigma a^{2}\chi^{2})j' + \Sigma r^{4}(j')^{2} - \Sigma\Sigma_{j}r^{2}j'' - 2(j-1)(r^{2} - a^{2}\chi^{2})(jr^{2} - a^{2}\chi^{2}) \right] \right] \\ (3.12) \end{aligned}$$

$$\hat{\sigma}_{12} = \frac{3a^2 r \cos\theta sqrt|\Delta|\sin\theta}{8\pi\Sigma^3\Sigma_j^2} \left[\left[2(j-1)(a^4\chi^4 - jr^4) + \Sigma^2 rj' \right] \right]$$
(3.13)