

Fixing D7 Brane Positions by F-Theory Fluxes

Christoph Lüdeling

bctp and PI, University of Bonn

A. Braun, A. Hebecker, CL, R. Valandro,

Nucl.Phys.B815:256-287,2009 [arXiv:0811.2416 [hep-th]]

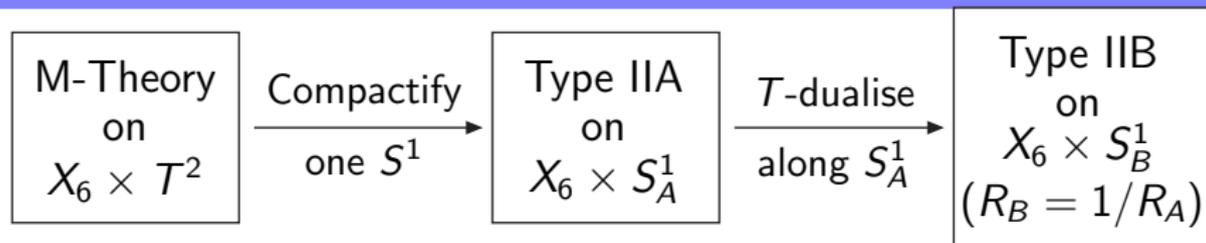
Motivation

- F-Theory: Nonperturbative version of type IIB string theory
[Vafa;Sen]
- Add two auxiliary dimensions, singularities of compactification manifold encode brane positions
- Recently, lots of interest in F-theory for model building interest
[Beasley,Heckman,Vafa;Saulina,Schäfer-Nameki;Bourjaily;Tatar,Watari. . .]
- Local models do not address global constraints like tadpole cancellation
- Four-form flux can stabilise moduli, including brane positions
- Simple example: F-Theory on $K3 \times \widetilde{K3}$, where $\widetilde{K3}$ is an elliptic fibration over \mathbb{P}^1 [Görllich et al.;Lust et al.; Aspinwall,Kalosh;Dasgupta et al.]
- Includes as special case the type IIB orientifold $K3 \times T^2/\mathbb{Z}_2$
[Angelantonj et al.]

Motivation

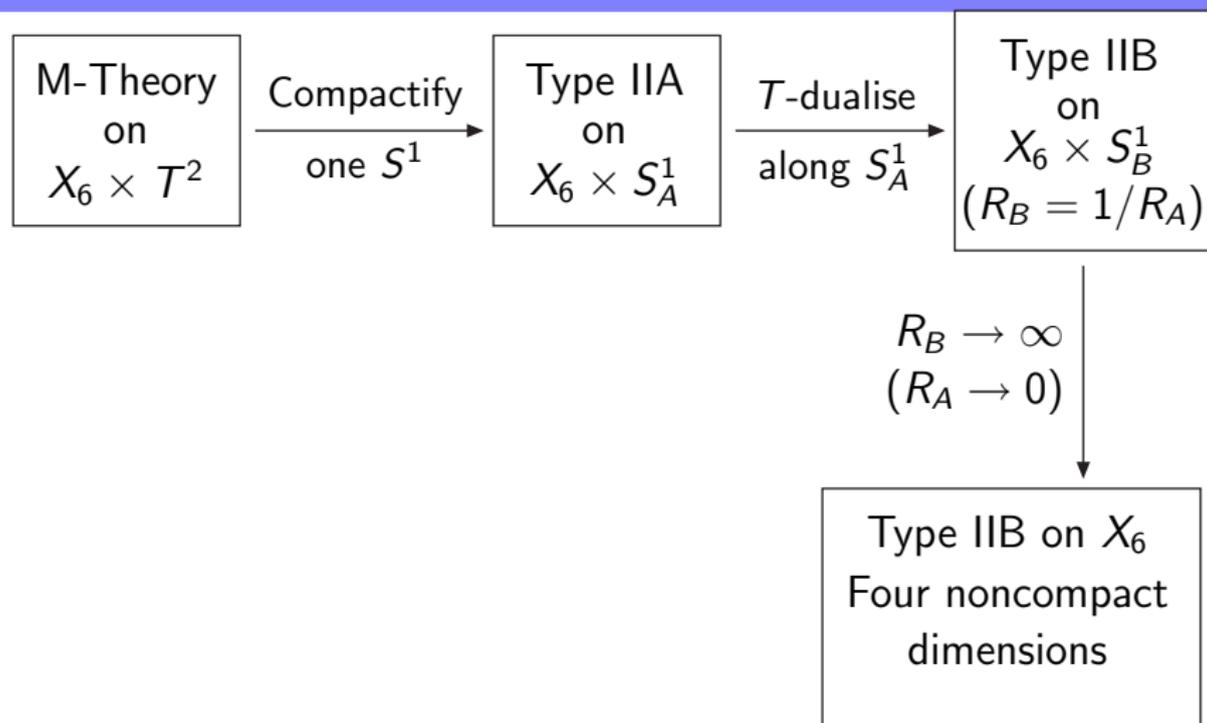
- F-Theory: Nonperturbative version of type IIB string theory
[Vafa;Sen]
- Add two auxiliary dimensions, singularities of compactification manifold encode brane positions
- Recently, lots of interest in F-theory for model building interest
[Beasley,Heckman,Vafa;Saulina,Schäfer-Nameki;Bourjaily;Tatar,Watari. . .]
- Local models do not address global constraints like tadpole cancellation
- Four-form flux can stabilise moduli, including brane positions
- Simple example: F-Theory on $K3 \times \widetilde{K3}$, where $\widetilde{K3}$ is an elliptic fibration over \mathbb{P}^1 [Görllich et al.;Lust et al.; Aspinwall,Kalosh;Dasgupta et al.]
- Includes as special case the type IIB orientifold $K3 \times T^2/\mathbb{Z}_2$
[Angelantonj et al.]

F-Theory/M-Theory Duality



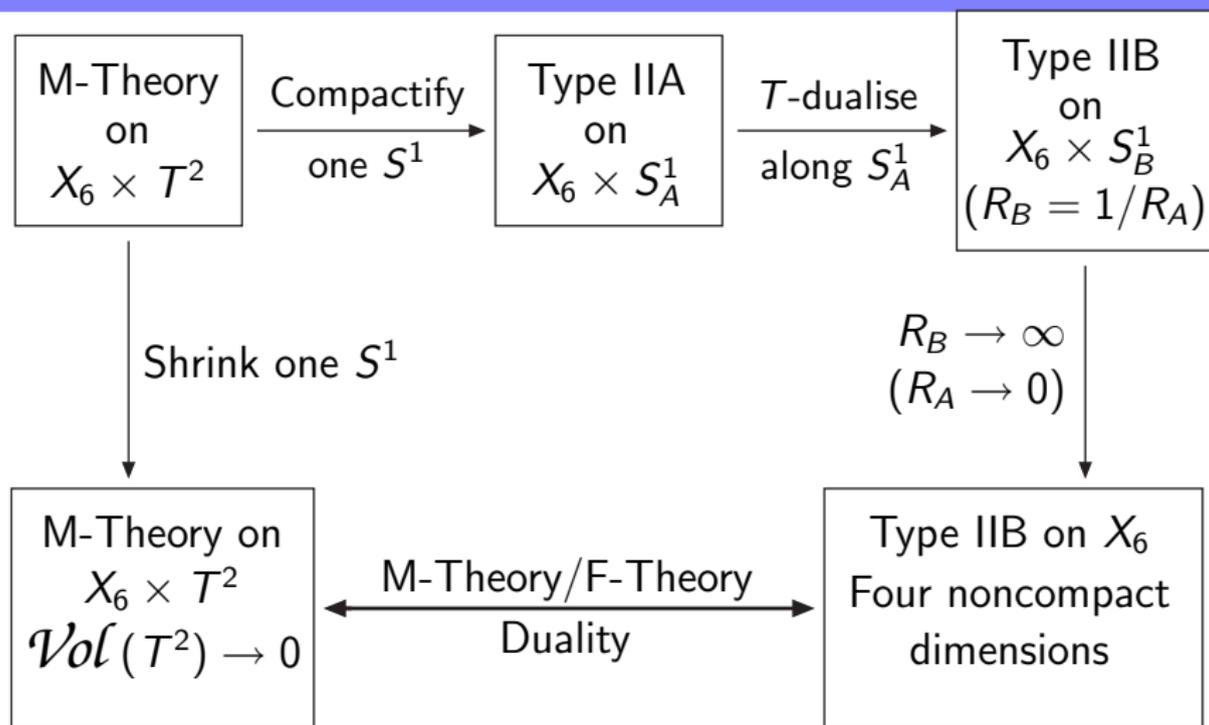
Fibrewise duality: $X_6 \times T^2 \rightsquigarrow$ elliptically fibred CY_4
dual to type IIB on base of fibration

F-Theory/M-Theory Duality



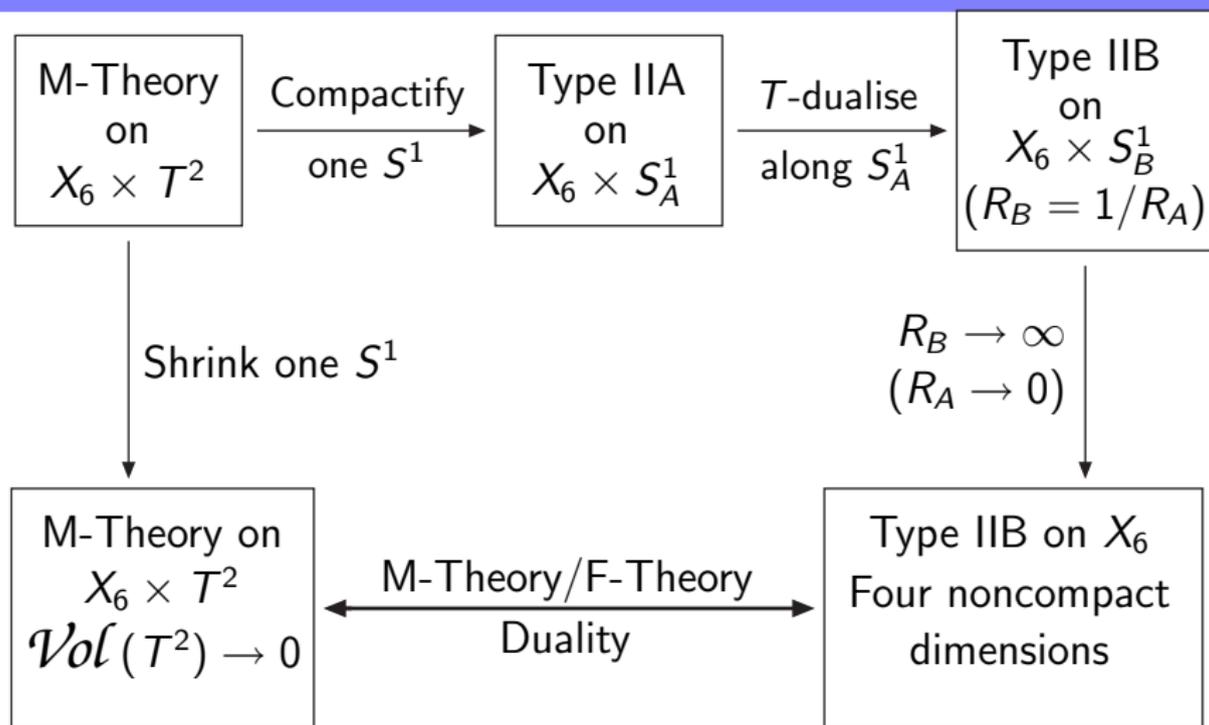
Fibrewise duality: $X_6 \times T^2 \rightsquigarrow$ elliptically fibred CY_4
dual to type IIB on base of fibration

F-Theory/M-Theory Duality



Fibrewise duality: $X_6 \times T^2 \rightsquigarrow$ elliptically fibred CY_4
dual to type IIB on base of fibration

F-Theory/M-Theory Duality



Fibrewise duality: $X_6 \times T^2 \rightsquigarrow$ elliptically fibred CY_4
 dual to type IIB on base of fibration

K3: Calabi–Yau Two-Fold

- $H^2(K3, \mathbb{R})$ has signature $(3, 19)$
- Holomorphic two-form and Kähler form spanned by three real forms ω_i with $\omega_i \cdot \omega_j = \delta_{ij}$ and overall volume ν :

$$\omega = \omega_1 + i\omega_2$$

$$j = \sqrt{2\nu} \omega_3$$

- K3 is **hyperkähler**, i.e. $SO(3)$ rotating the $\omega_i \rightsquigarrow$ geometry fixed by positive-norm **three-plane** $\Sigma \subset H^2(K3, \mathbb{R})$ and ν
- Moduli space has $3 \times 19 + 1 = 58$ dimensions
- Integral basis for $H^2(K3)$ with intersection matrix $U \oplus U \oplus U \oplus (-E_8) \oplus (-E_8)$, where $U = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ and E_8 is Cartan matrix of E_8
 \Rightarrow The ω_i must have components along the U blocks, components along “ E_8 directions” determine gauge group

K3: Calabi–Yau Two-Fold

- $H^2(K3, \mathbb{R})$ has signature $(3, 19)$
- Holomorphic two-form and Kähler form spanned by three real forms ω_i with $\omega_i \cdot \omega_j = \delta_{ij}$ and overall volume ν :

$$\omega = \omega_1 + i\omega_2$$

$$j = \sqrt{2\nu} \omega_3$$

- K3 is **hyperkähler**, i.e. $SO(3)$ rotating the $\omega_i \rightsquigarrow$ geometry fixed by positive-norm **three-plane** $\Sigma \subset H^2(K3, \mathbb{R})$ and ν
- Moduli space has $3 \times 19 + 1 = 58$ dimensions
- Integral basis for $H^2(K3)$ with intersection matrix $U \oplus U \oplus U \oplus (-E_8) \oplus (-E_8)$, where $U = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ and E_8 is Cartan matrix of E_8
 \Rightarrow The ω_i must have components along the U blocks, components along “ E_8 directions” determine gauge group

K3: Elliptic Fibration and F-Theory Limit

- For an elliptically fibred $K3$, require integral cycles B and F (base and fibre) with

- intersection matrix $\begin{pmatrix} -2 & 1 \\ 1 & 0 \end{pmatrix}$

- $B \cdot \omega = F \cdot \omega = 0$

$\Rightarrow (B, F)$ spans a U block, and we can parametrise the Kähler form as

$$j = bB + fF + c^a u_a \quad (\text{where } u_a \cdot \omega = 0)$$

- F-theory limit: Fibre volume shrinks to zero $\Rightarrow b \rightarrow 0$. $K3$ volume is $\nu \sim bf - c^a c^a$, so we have to take $c^a \rightarrow 0$ as fast as \sqrt{b} (as intuitively expected)
- In the limit, $j = fF$ is the Kähler form of the \mathbb{P}^1 base

K3: Elliptic Fibration and F-Theory Limit

- For an elliptically fibred $K3$, require integral cycles B and F (base and fibre) with

- intersection matrix $\begin{pmatrix} -2 & 1 \\ 1 & 0 \end{pmatrix}$

- $B \cdot \omega = F \cdot \omega = 0$

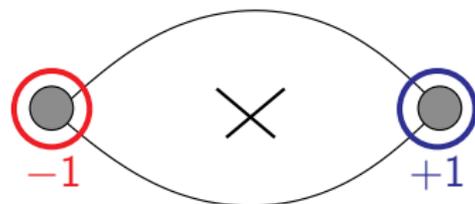
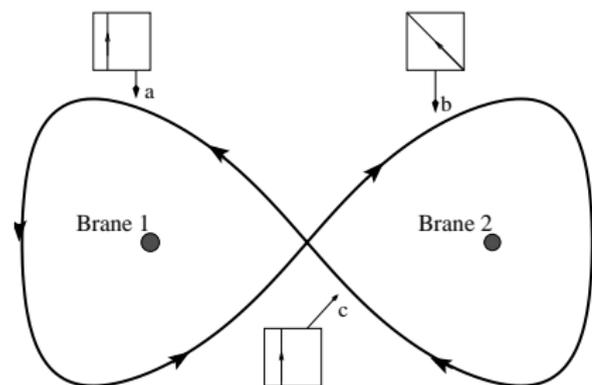
$\Rightarrow (B, F)$ spans a U block, and we can parametrise the Kähler form as

$$j = bB + fF + c^a u_a \quad (\text{where } u_a \cdot \omega = 0)$$

- F-theory limit: Fibre volume shrinks to zero $\Rightarrow b \rightarrow 0$. $K3$ volume is $\nu \sim bf - c^a c^a$, so we have to take $c^a \rightarrow 0$ as fast as \sqrt{b} (as intuitively expected)
- In the limit, $j = fF$ is the Kähler form of the \mathbb{P}^1 base

Cycles Between Branes

[Braun, Hebecker, Triendl]

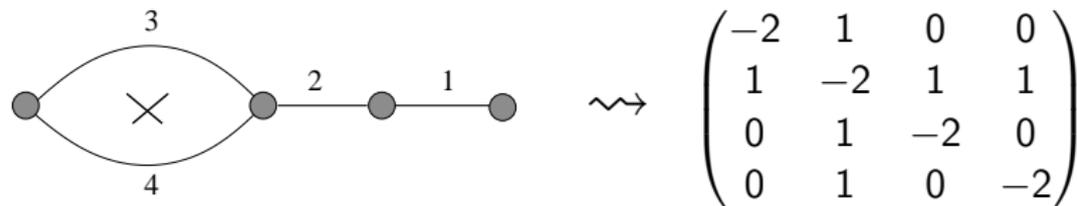


- One leg in the base, one in the fibre torus
- **Shrink to zero** when the branes are moved on top of each other.
- They are topologically a **sphere** \leftrightarrow self-intersection -2 .
- Cycles meeting at a brane intersect once, cycles encircling 0 planes (\times) do not intersect

Shrinking Cycles and Gauge Enhancement

Intersection matrix of shrinking cycles determines gauge group:

Consider e.g. T^2/\mathbb{Z}_2 orientifold: One O7, four D7s $\rightsquigarrow SO(8)$



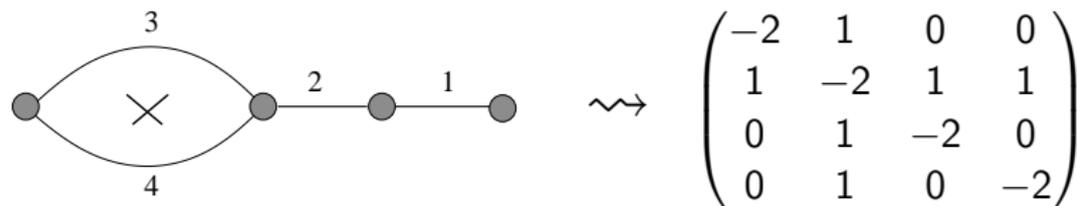
In appropriate basis, complex structure of $\widetilde{K3}$ is [Braun, Hebecker, Triendl]

$$\omega = \frac{\alpha}{2} + u e_2 + s \frac{\beta}{2} - \left(u s - \frac{z^2}{2} \right) e_1 + z_I \hat{E}_I$$

Explicit mapping between complex structure and brane positions!

Shrinking Cycles and Gauge Enhancement

Intersection matrix of shrinking cycles determines gauge group:
Consider e.g. T^2/\mathbb{Z}_2 orientifold: One O7, four D7s $\rightsquigarrow SO(8)$



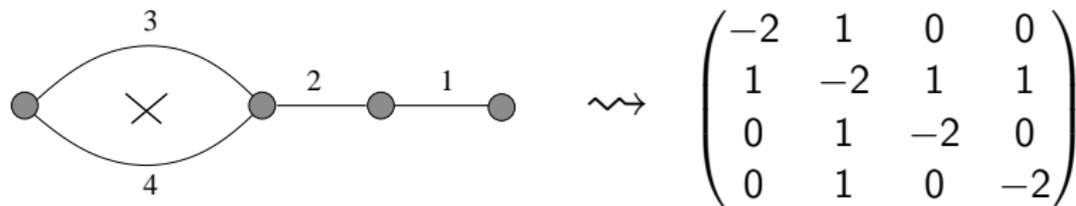
In appropriate basis, complex structure of $\widetilde{K3}$ is [Braun, Hebecker, Triendl]

$$\omega = \frac{\alpha}{2} + u e_2 + s \frac{\beta}{2} - \left(u s - \frac{z^2}{2} \right) e_1 + z_I \hat{E}_I$$

Explicit mapping between complex structure and brane positions!

Shrinking Cycles and Gauge Enhancement

Intersection matrix of shrinking cycles determines gauge group:
 Consider e.g. T^2/\mathbb{Z}_2 orientifold: One O7, four D7s $\rightsquigarrow SO(8)$



In appropriate basis, complex structure of $\widetilde{K3}$ is [Braun, Hebecker, Triendl]

$$\omega = \frac{\alpha}{2} + \underbrace{u}_{\text{base complex structure}} e_2 + \underbrace{s}_{\text{axiodilaton}} \frac{\beta}{2} - \left(us - \frac{z^2}{2} \right) e_1 + \underbrace{z_1}_{\text{brane positions, } z_1 = 0 \text{ is } SO(8)^4 \text{ point}} \hat{E}_1$$

base complex structure

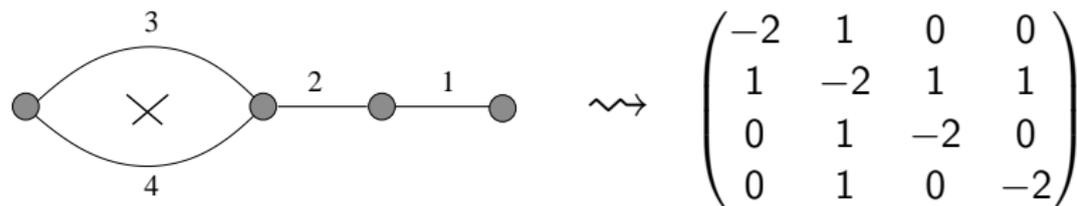
axiodilaton

brane positions, $z_1 = 0$ is $SO(8)^4$ point

Explicit mapping between complex structure and brane positions!

Shrinking Cycles and Gauge Enhancement

Intersection matrix of shrinking cycles determines gauge group:
 Consider e.g. T^2/\mathbb{Z}_2 orientifold: One O7, four D7s $\rightsquigarrow SO(8)$



In appropriate basis, complex structure of $\widetilde{K3}$ is [Braun, Hebecker, Triendl]

$$\omega = \frac{\alpha}{2} + \underbrace{u}_{\text{base complex structure}} e_2 + \underbrace{s}_{\text{axiodilaton}} \frac{\beta}{2} - \left(us - \frac{z^2}{2} \right) e_1 + \underbrace{z_i}_{\text{brane positions}} \hat{E}_i$$

base complex structure

axiodilaton

brane positions, $z_i = 0$ is $SO(8)^4$ point

Explicit mapping between complex structure and brane positions!

Flux Potential

- Type IIB: **Three-form flux G_3** on the bulk, **two-form gauge flux F_2** on the branes can stabilise geometric and brane moduli
- In M-theory, these are combined into **four-form flux G_4** (brane moduli become four-form geometric moduli)
- Consistency conditions:
 - Flux quantisation: flux needs to be integral
 - Tadpole cancellation (without spacetime-filling M2 branes)

$$\frac{1}{2} \int_{K3 \times \widetilde{K3}} G_4 \wedge G_4 = \frac{\chi}{24} = 24$$

- G_4 needs to have exactly one leg on each on base and fibre for Lorentz invariance, hence two on each $K3$: $G = G^{I\Lambda} \eta_I \wedge \tilde{\eta}_\Lambda$, but no flux along B or F

Flux Potential

- Type IIB: **Three-form flux G_3** on the bulk, **two-form gauge flux F_2** on the branes can stabilise geometric and brane moduli
- In M-theory, these are combined into **four-form flux G_4** (brane moduli become four-form geometric moduli)
- Consistency conditions:
 - Flux quantisation: flux needs to be integral
 - Tadpole cancellation (without spacetime-filling M2 branes)

$$\frac{1}{2} \int_{K3 \times \widetilde{K3}} G_4 \wedge G_4 = \frac{\chi}{24} = 24$$

- G_4 needs to have exactly one leg on each on base and fibre for Lorentz invariance, hence two on each $K3$: $G = G^{I\Lambda} \eta_I \wedge \tilde{\eta}_{\Lambda}$, but no flux along B or F

- Flux potential (\mathcal{V} is the volume) :

[Haack,Louis]

$$\mathcal{V} = \frac{1}{4\mathcal{V}^3} \left(\int_{K3 \times \widetilde{K3}} G \wedge *G - \frac{\chi}{12} \right)$$

- $K3 \times \widetilde{K3}$ is not a proper CY_4 : Holonomy is $SU(2) \times SU(2)$
- G_4 induces map $G : H^2(\widetilde{K3}) \rightarrow H^2(K3)$ and its adjoint G^a by

$$G\tilde{\eta} = \int_{\widetilde{K3}} G \wedge \tilde{\eta} \qquad G^a \eta = \int_{K3} G \wedge \eta$$

- Potential is concisely expressed in terms of these maps

- Flux potential (\mathcal{V} is the volume) :

[Haack,Louis]

$$V = \frac{1}{4\mathcal{V}^3} \left(\int_{K3 \times \widetilde{K3}} G \wedge *G - \frac{\chi}{12} \right)$$

- $K3 \times \widetilde{K3}$ is not a proper CY_4 : Holonomy is $SU(2) \times SU(2)$
- G_4 induces map $G : H^2(\widetilde{K3}) \rightarrow H^2(K3)$ and its adjoint G^a by

$$G\tilde{\eta} = \int_{\widetilde{K3}} G \wedge \tilde{\eta} \qquad G^a \eta = \int_{K3} G \wedge \eta$$

- Potential is concisely expressed in terms of these maps

$K3 \times \widetilde{K3}$ Flux Potential

$$V = -\frac{1}{2(\nu \cdot \widetilde{\nu})^3} \left(\sum_j \|G \widetilde{\omega}_j\|_{\perp}^2 + \sum_i \|G^a \omega_i\|_{\perp}^2 \right)$$

Here $\|\cdot\|_{\perp}^2$ is the norm orthogonal to the three-plane

- Positive definite potential
- Manifestly symmetric under $SO(3)$
- Minima at $V = 0$:

$$G \widetilde{\omega}_j \in \langle \omega_1, \omega_2, \omega_3 \rangle \quad G^a \omega_i \in \langle \widetilde{\omega}_1, \widetilde{\omega}_2, \widetilde{\omega}_3 \rangle$$

- ν and $\widetilde{\nu}$ are unfixed, flat directions (when $V = 0$)

$K3 \times \widetilde{K3}$ Flux Potential

$$V = -\frac{1}{2(\nu \cdot \widetilde{\nu})^3} \left(\sum_j \|G \widetilde{\omega}_j\|_{\perp}^2 + \sum_i \|G^a \omega_i\|_{\perp}^2 \right)$$

Here $\|\cdot\|_{\perp}^2$ is the norm orthogonal to the three-plane

- Positive definite potential
- Manifestly symmetric under $SO(3)$
- Minima at $V = 0$:

$$G \widetilde{\omega}_j \in \langle \omega_1, \omega_2, \omega_3 \rangle \quad G^a \omega_i \in \langle \widetilde{\omega}_1, \widetilde{\omega}_2, \widetilde{\omega}_3 \rangle$$

- ν and $\widetilde{\nu}$ are unfixed, flat directions (when $V = 0$)

Minima: Existence, Flat Directions

- Minkowski minima do **not necessarily** exist: $G^a G$ must be diagonalisable and positive semi-definite (not guaranteed although $G^a G$ is self-adjoint, since metric is indefinite!)
- Flat directions **generally exist** and are **desired**: M-theory moduli become part of 4D **vector fields** in F-theory limit \rightsquigarrow fixing these moduli breaks the gauge group (rank-reducing)
- Flux also induces explicit mass term for three-dimensional vectors
- Vacua can preserve $\mathcal{N} = 4$, $\mathcal{N} = 2$ or $\mathcal{N} = 0$ supersymmetry in four dimensions, depending on the action of G on the three-plane

Stabilisation Strategy

- F-theory limit fixes Kähler form (up to base volume), $j = f F$
- Holomorphic two-form determines shrinking cycles, i.e. gauge enhancement
- To stabilise a **desired brane configuration**:
 - Identify set of shrinking cycles to obtain desired brane stacks
 - Choose these as part of a basis of $H^2(\widetilde{K3})$ and complete by integral cycles
 - Find an integral block-diagonal flux that satisfies tadpole cancellation condition (strong constraint and computationally costly)

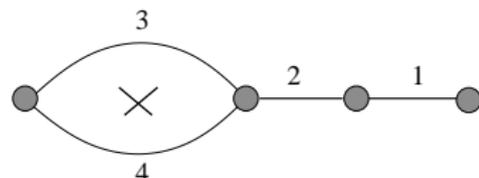
Stabilisation Strategy

- F-theory limit fixes Kähler form (up to base volume), $j = f F$
- Holomorphic two-form determines shrinking cycles, i.e. gauge enhancement
- To stabilise a **desired brane configuration**:
 - Identify set of shrinking cycles to obtain desired brane stacks
 - Choose these as part of a basis of $H^2(\widetilde{K3})$ and complete by integral cycles
 - Find an integral block-diagonal flux that satisfies tadpole cancellation condition (strong constraint and computationally costly)

Examples

We give explicit examples of

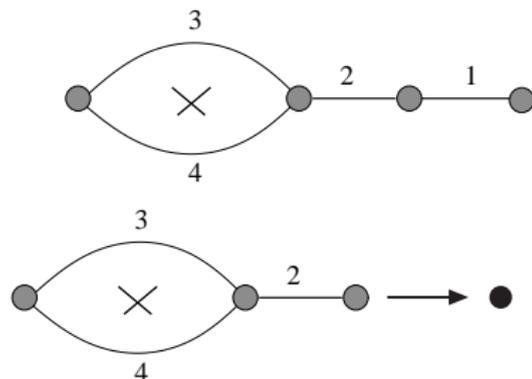
- The T^2/\mathbb{Z}_2 orientifold with $SO(8)^4$: Four stacks of four D7 branes and one O7 plane each
- Moving one brane off a stack.
 $\rightsquigarrow SO(8)^3 \times SO(6) \times U(1)$ or $SO(8)^3 \times SO(6)$
- Moving two branes
 $\rightsquigarrow SO(8)^3 \times SO(4) \times SU(2)$



Examples

We give explicit examples of

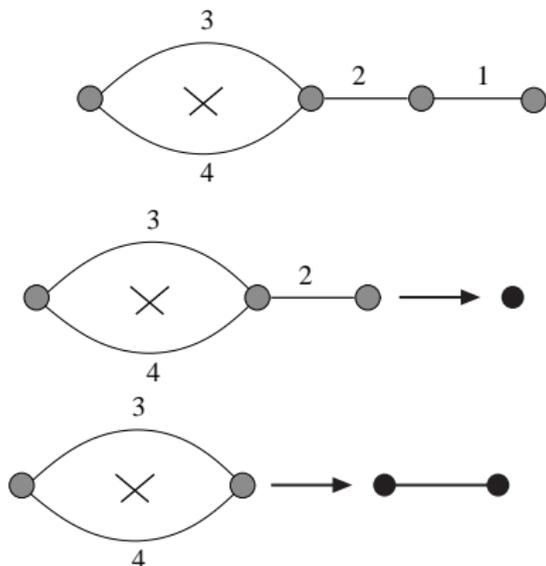
- The T^2/\mathbb{Z}_2 orientifold with $SO(8)^4$: Four stacks of four D7 branes and one O7 plane each
- Moving one brane off a stack.
 $\rightsquigarrow SO(8)^3 \times SO(6) \times U(1)$ or $SO(8)^3 \times SO(6)$
- Moving two branes
 $\rightsquigarrow SO(8)^3 \times SO(4) \times SU(2)$



Examples

We give explicit examples of

- The T^2/\mathbb{Z}_2 orientifold with $SO(8)^4$: Four stacks of four D7 branes and one O7 plane each
- Moving one brane off a stack.
 $\rightsquigarrow SO(8)^3 \times SO(6) \times U(1)$ or $SO(8)^3 \times SO(6)$
- Moving two branes
 $\rightsquigarrow SO(8)^3 \times SO(4) \times SU(2)$



Conclusion

- We have a nice geometric picture of D7 brane motion
 - We found the flux potential in M-theory and explicit conditions for the existence of minima and gauge symmetry breaking
 - Translation to F-theory \Rightarrow recipe to find fluxes that stabilise a desired situation
 - Explicit examples: We can move branes
-
- Open problem: Numerical scan of matrices is very time-consuming
 - Outlook: Generalise to elliptically fibred four-folds to get physically more realistic models, in particular intersecting branes

Conclusion

- We have a nice geometric picture of D7 brane motion
 - We found the flux potential in M-theory and explicit conditions for the existence of minima and gauge symmetry breaking
 - Translation to F-theory \Rightarrow recipe to find fluxes that stabilise a desired situation
 - Explicit examples: We can move branes
-
- Open problem: Numerical scan of matrices is very time-consuming
 - Outlook: Generalise to elliptically fibred four-folds to get physically more realistic models, in particular intersecting branes